

Evaluation unit  
**castxpert** LB 452

**Operating Manual**  
**47344BA2**

Rev. No.: 04, 03/2015  
Embedded Software as of vers. 1.3.0 (CU) and 1.3.0 (MU)





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# 1

## About this Manual

### 1.1 Some Prior Remarks

The LB 452 Evaluation Unit (from now on referred to as EVU) is delivered to you by the manufacturer BERTHOLD TECHNOLOGIES GmbH & Co. KG in a complete and functionally reliable condition.

This manual demonstrates to you how to:

- Assemble/Install the EVU
- Establish the connections to the power supply
- Build the measurement connections
- Carry out the measurements
- Apply software settings
- Install the extension module (optional)
- Carry out maintenance
- Fix errors
- Disassemble
- Dispose of the device

You must read through the entire manual. We have tried to compile for you all information for safe and proper operation.

However, should questions arise which are not answered in this manual, please refer to BERTHOLD TECHNOLOGIES GmbH & Co. KG.

### 1.2 Structure of the Manual

This manual has been divided into chapters. The order of the chapters should help you to familiarise yourself quickly and properly with the operation of the EVU.

### 1.3 Validity of the Manual

The manual is valid from the delivery of the system to the user until its disposal. Modification services are not carried out by the manufacturer BERTHOLD TECHNOLOGIES GmbH & Co. KG.

## 1.4 Copyright

This manual contains copyright-protected information. None of the chapters may be copied or reproduced in any other form without prior authorisation from the manufacturer.

## 1.5 Target Group

This manual is directed at qualified specialist personnel who are familiar with handling electrical and electronic assemblies as well as with communication and measuring techniques.

Specialist personnel refers to those who can assess the work assigned to them and recognise possible dangers through their specialist training, knowledge and experience as well as knowledge of the relevant regulations.

## 1.6 Notation

In this manual the following notations are used to state the software interface and the operation:

Identifier	Meaning	Example
Quotation mark	Field in the software interface	"Calibrating"
Vertical line	Path specification	Settings   Option/Display
Pointed brackets	Keys and buttons	<Update>
Round brackets	Image reference	Connect the plug (Fig. 1, Pos. 1).

In the software description, the term "clicking" is used if a process is to be activated. This also refers to the pressing of a button (key) or an area on the touch display if a mouse is not used for controlling.



## 1.7 Symbols Used

The safety instructions point out possible dangers to you and instruct you on the operation. They apply to the whole document.



Danger

### Possible consequences: Death or serious injury!

Points out a direct threat of danger. If the danger is not avoided, death or serious bodily injury are the consequences.

- Possible consequences are described.
- Measures for prevention are described.



Warning

### Possible consequences: Serious injuries!

Points out a possibly dangerous situation. If the situation is not avoided, death or serious bodily injury could result.

- Possible consequences are described.
- Measures for prevention are described.



Caution

### Possible consequences: Mild or moderate injury!

Points out a possibly dangerous situation. If the situation is not avoided, minor or moderate bodily injury could occur.

- Possible consequences are described.
- Measures for prevention are described.



Attention

### Possible consequences: Material damage!

Points out a situation which could result in the event of material damage if the instructions have not been observed.

- Possible consequences are described.
- Measures for prevention are described.



Note

Points out helpful information on the product or on handling.



# 2 Safety

## 2.1 Proper use

The LB 452 evaluation unit (EVU) measures the fill level along with the GAMMAcast detectors and a compatible radiation source and it may only be used for this purpose.

The following constitutes proper use:

- Adhering strictly to the instructions and operation sequences and not undertaking any different, unauthorised practices which could endanger your safety and the operational reliability of the EVU!
- Observing the given safety instructions!
- Carrying out the prescribed maintenance measures or having them carried out for you!

## 2.2 Improper use



### **Danger to life from electric shock!**

The installation may only be carried out by a qualified electrician.

Danger

- Electric shock.
- Please adhere to the relevant safety regulations.
- Only carry out maintenance work when the device is free of voltage.
- Only open the device when free of voltage.



Attention

### **Injuries to person and material damage!**

In the event of improper use, there is a threat of danger to

- the health of the user.
  - the efficient working of the evaluation unit (EVU).
  - the functional reliability of the EVU.
  - Observe the instructions from the Proper Use section.
-

### Improper Use (Continued)

- If the EVU is used in a way which is not described in the present manual, the EVU's protection is compromised and the guarantee claim becomes invalid.
- BERTHOLD TECHNOLOGIES GmbH & Co. KG only accepts liability for / guarantees the correspondence of the EVU to its published specifications.

Avoid the following circumstances:

- Failing to observe the instructions on safety, operation, maintenance and disposal given in the manual.
- Failure to observe the operating instructions for "47344BA1" RVU and the "48452BA1" GAMMAcast detectors.
- Applying conditions and requirements which do not conform to those stated in the technical documents, data sheets, operation and assembly instructions and other specific guidelines of the manufacturer.
- Using the EVU in a damaged or corroded condition.
- Restructuring or changing the system components.
- The device is not approved according to IEC 61508 "Functional safety of safety-related electric/electronic/programmable electronic systems".
- If the product is used in a way which is not described in the present manual, the device's protection is compromised and the warranty claim becomes invalid.  
BERTHOLD TECHNOLOGIES GmbH & Co. KG shall only accept liability for / guarantee the correspondence of the device to its publicised specifications.

## 2.3 Qualification of the Personnel



Note

A minimum requirement for all work on or with the product would be employees with general knowledge who are instructed by an expert or authorised person.

At different parts in this manual, reference is made to personnel with certain qualifications who can be entrusted with different tasks during the installation, usage and maintenance.

These three groups of people are:

- Those with General Knowledge
- Experts
- Authorised Persons

## Qualification of the Personnel (Continued)

### Those with General Knowledge



Note

Employees with general knowledge must always be guided by an expert at the very least. When dealing with radioactive substances, a radiation safety officer must also be consulted.

Employees with general knowledge must always be guided by an expert at the very least.

When dealing with radioactive substances, a radiation safety officer must also be consulted.

Those with a general knowledge are e.g. technicians or welders who can undertake different tasks during the transportation, assembly and installation of the shielding under the guidance of an authorised person. This can also refer to construction site personnel. The persons in question must have experience in the transportation and assembly of heavy component parts.

### Experts

Experts are persons who have sufficient knowledge in the required area due to their specialist training and who are familiar with the relevant national health and safety regulations, accident prevention regulations, guidelines and recognised technical rules.

Expert personnel must be capable of safely assessing the results of their work and they must be familiar with the content of this manual.

### Authorised Persons

Authorised persons are those who are either designated for the corresponding task due to legal regulations or those who have been authorised by BERTHOLD TECHNOLOGIES for particular tasks. When dealing with radioactive materials, a radiation safety officer must also be consulted.



# 3 Product Description

## 3.1 Description of the System

The evaluation unit (EVU) consists of a system board (CU Control Unit) with an ex-works pre-installed measurement module (channel 1).

The EVU can be distributed with up to 4 measurement modules (channels). This makes the simultaneous monitoring of 4 mould levels possible.

There is also the possibility of ordering the EVU customised with a pre-installed extension module or a fieldbus model or installing these modules yourself afterwards. Further information on the extension module can be found in chapt. 4.3.2 and on the fieldbus module in chapt. **Fehler! Verweisquelle konnte nicht gefunden werden..**

You can connect the EVU to both radiometric detectors (GAMMAcast) and the electromagnetic measurement system (Eccast). When in doubt, the instructions refer to the GAMMAcast instructions. For specific information regarding Eccast, refer to the Eccast supplemental instructions.

## 3.2 Software

The field device is delivered with pre-installed software.

The revision status (version) of the software can be seen on the screen display when starting up the EVU or in the "Channel Setting" menu.

In this manual, the software is described with effect from version 1.3.0 (CU - control unit, system board) and 1.3.0 (MU - channel XY).

## 3.3 Power Supply

The EVU does not have an on and off switch with which the power supply can be switched on or off. Ensure that the current of the EVU can be simply disconnected via the external power supply.

### 3.4 Overview

#### 3.4.1 Front View

On the front view of the EVU there are LEDs for displaying each operation mode, a 7" touch display and a USB connection.

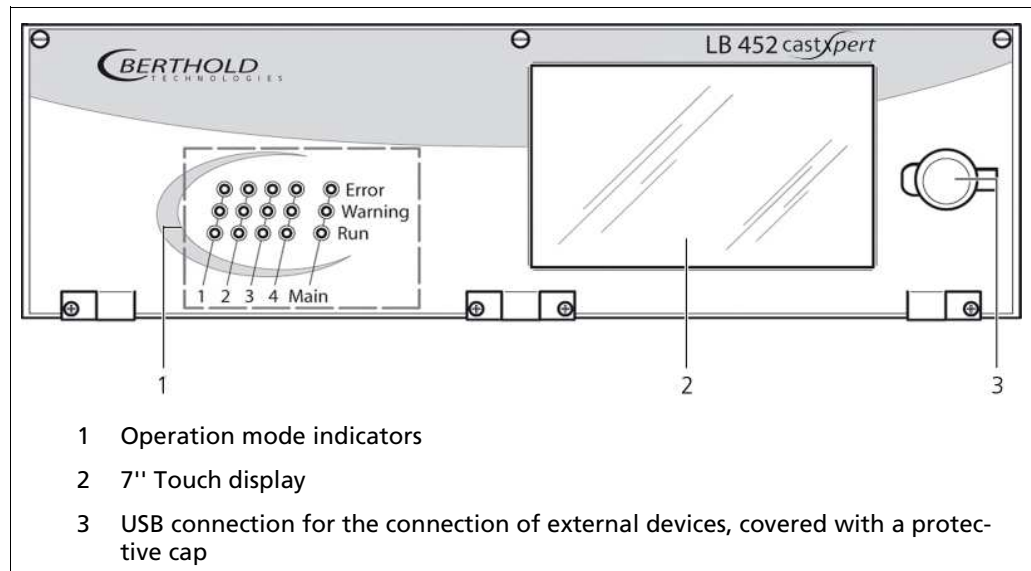


Fig.1 Back view of the EVU

#### 3.4.2 Control Unit Indicators

The indicators in the "Main" section (control unit) indicate the operation mode of the EVU. The indicators "1 to 4"(Fig. 2) indicate the operation mode of each measurement channel. This shows which operation mode is active on each measurement channel.

If an error occurs at just one measurement channel (Error LED lights up), then the other measurement channels are not affected by this error.

The measurement of other channels continues.

	Error	Lights up red in the event of a device error (chapt. 8.1 Error Search).
	Warning	Lights up yellow if a warning is present.
	Run	Lights up green in error-free operation

Fig. 2 Control Unit Indicators



### Control Unit Indicators (Continued)

<b>LED Error</b>	This LED (Fig. 2, Pos. 1) lights up if an error has occurred. The current measurement is retained. Check the device settings. All possible error reports are described in chapt. 8 Troubleshooting .
<b>Warning LED</b>	This LED (Fig. 2, Pos. 2) lights up if calibration is being carried out or if the device is in test mode or if any other warning message is present. The current measurement is retained. All possible error reports are described in chapt. 8 Troubleshooting .
<b>Run LED</b>	This LED (Fig. 2, Pos. 3) lights up if the device is in operation and fault-free. The current measurement is carried out.

### 3.4.3 Back View

The following connections are located on the back of the EVU:

- EVU power supply
- Power supply of channels 1 to 4
- Measurement inputs from the GAMMAcast detector for the channels 1 to 4
- Ethernet port for the data transmission via the LAN connection
- USB ports for the external USB devices

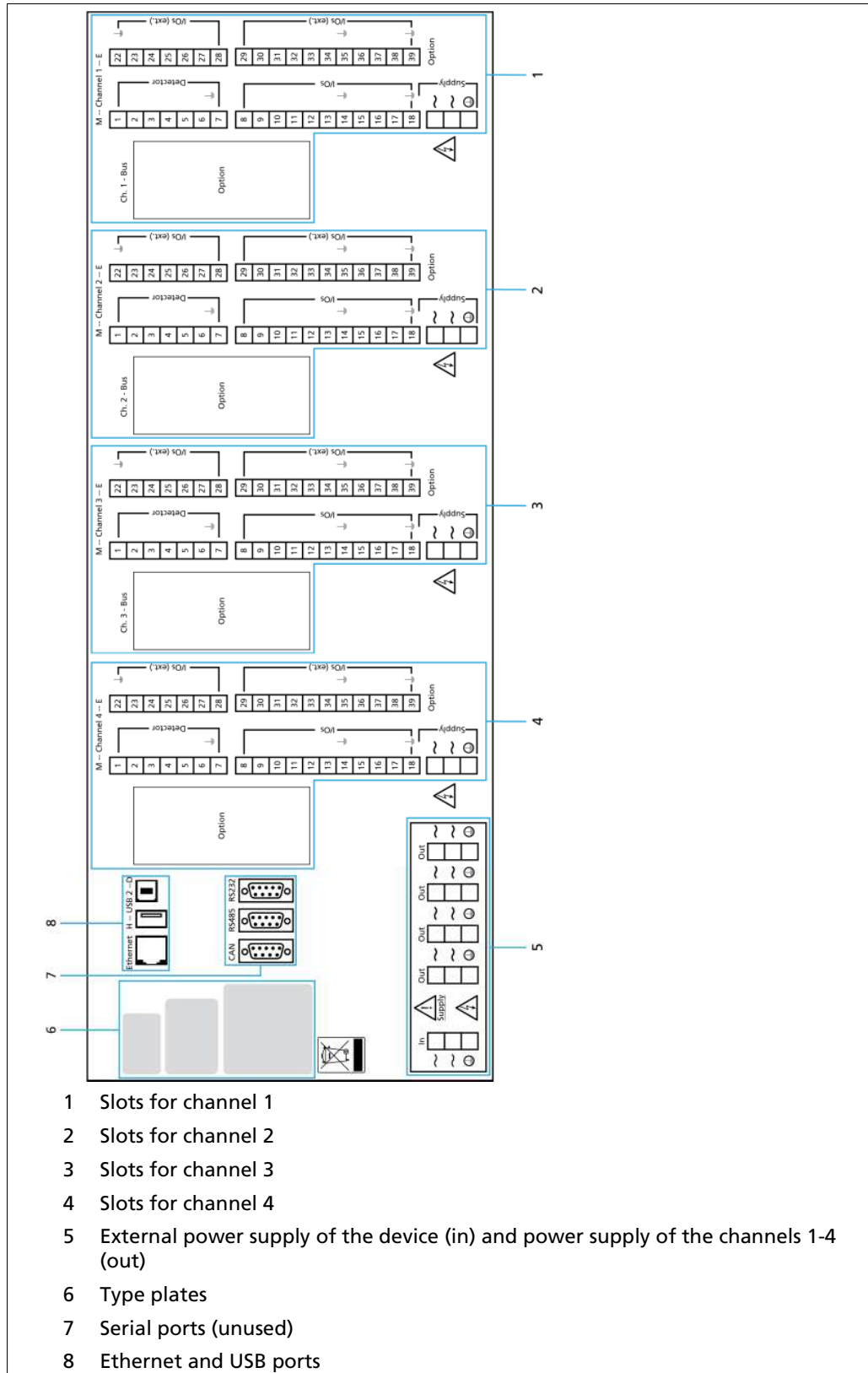


Fig. 3 Back view of the EVU

## 3.5 Radiometric Measurement System

### 3.5.1 Functional Principle

The measurement system functions on the principle of the radiometric measuring method. Here, the weakening of gamma rays by fluid metal in the mould is used in order to (Fig. 4, No. 1) measure the fill level in the mould.

The EVU evaluates the electrical signal generated by the GAMMAcast detector and continually measures the fill level of the mould of a casting plant. Here, the fill level of up to 4 strands can be individually measured at the same time.



Note

#### Notes for the use of casting powder

If casting powder is used for the casting process, note that the height of the casting powder layer is partially measured via the mould level of the measurement device. This means that the mould level appears to be somewhat higher than that corresponding to the actual mould level. The magnitude of this deviation depends on the height of the casting powder layer, the bulk density of the casting powder (granulate has a lesser disruptive effect) and the casting format. The error is constant and is only a few millimetres for a desired uniform allocation of casting powder and lesser casting powder layer for metallurgical reasons.

### 3.5.2 Measurement System Components/Measurement Setup

The measurement system is made up of the following components:

- LB 452 castXpert evaluation unit (EVU)
- Detector from the GAMMAcast series
- Radiation Source/Mould Level Shielding

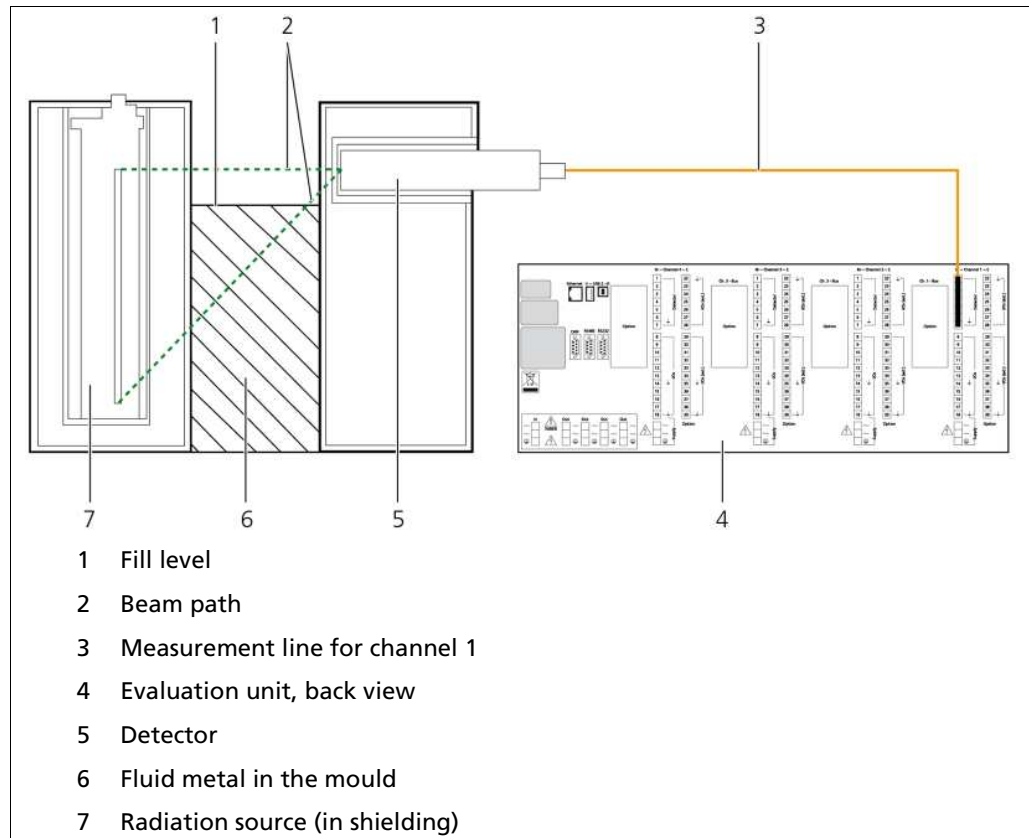


Fig. 4 Measurement Set-up

## Measurement System Components/Measurement Set-up (Continued)



Note

Further information on the functional principle of the detectors can be found in the manual on the GAMMAcast detectors.

Each active measurement channel consists of at least one basic module. This is indispensable for operating the EVU.

The following modules can also be installed in the EVU:

<b>Extension Module</b>	Offers an extra current output, a pulse input for digital inputs and 2 alarm relays
<b>Fieldbus Module</b>	For transmitting measurement-related data via an RS-485 port (Profibus DP) or an RJ-45 Ethernet port (Profinet IO)

Further instructions on the extension module can be found in chapt. 4.3.2 and on the fieldbus module in chapt. 4.4.



# 4 Start-Up

The Start-Up chapter explains how to:

- install the device
- use a terminal box
- configure the current output on the basic module or on the extension module
- communicate via the fieldbus module
- install an SD Card

## 4.1 Installation of the Evaluation Unit (EVU)



Danger

### **Danger to life from electric shock!**

The installation may only be carried out by a qualified electrician.

- Electric shock.
- Please adhere to the relevant safety regulations.
- Only carry out maintenance work when the device is free of voltage.
- Only open the device when free of voltage.



Attention

### **Damage to the device or wrong measurement results!**

Error in the calibration or in the setting of parameters.

- Wrong measurement results.
- Losses of production.
- Damage in the system.
- In general, we would recommend that you have the start-up carried out by the service of the company BERTHOLD TECHNOLOGIES.



Note

When operating the EVU, you must adhere to the manual "Mould Level Shieldings".



Note

BERTHOLD TECHNOLOGIES recommends building a separate power connection for each measurement channel (Fig. 3).

### Installation of the Evaluation Unit (EVU) (Continued)

The advantages of a separate power connection for each measurement channel are:

- Functional reliability in the event of surges or short circuits** Each measurement channel is supplied by its own voltage source.
- Redundancy** If there is a fault in the power supply for one strand, the other measurements can still be carried out without interference.

1. Install the EVU in a 19" rack (not included in delivery contents).
2. Connect the external power supply to the EVU (Fig. 5).

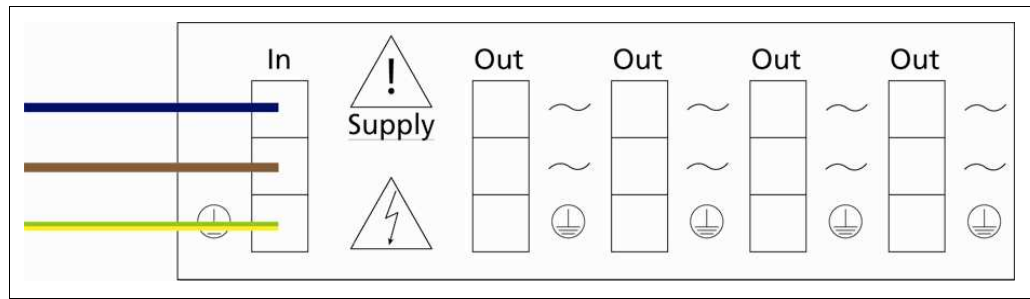


Fig. 5 External power supply for the AWE

3. Connect the power supply (Out) with the corresponding channel (Fig. 6) or connect the individual measurement channels with an external power supply (recommended) (Fig. 7).

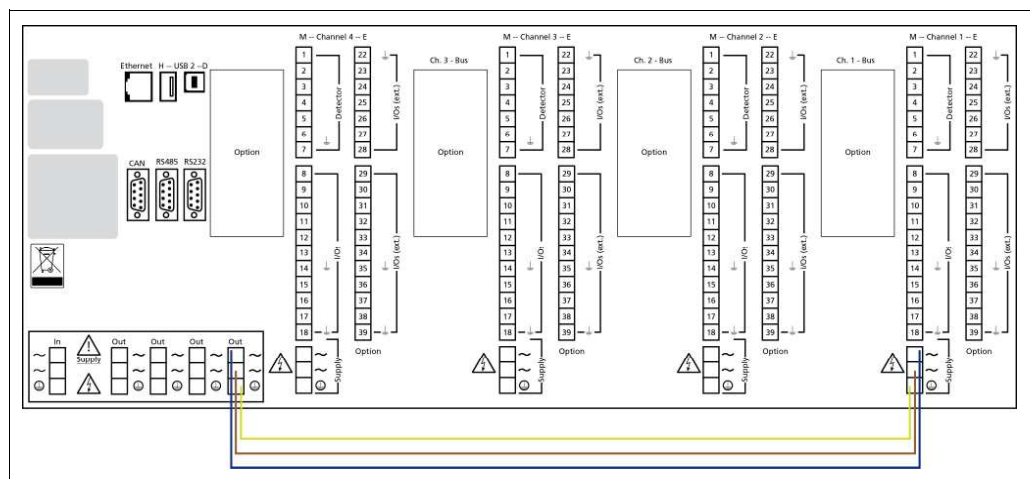


Fig. 6 Internal Power Supply of the Measurement Channel via the EVU, Measurement Channel 1 as Example



## Installation of the Evaluation Unit (EVU) (Continued)

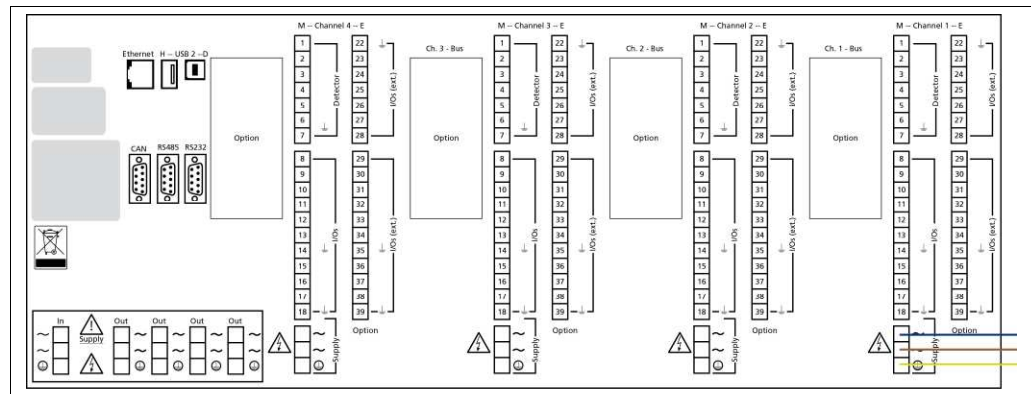


Fig. 7 External Power Supply of the Measurement Channel, Measurement Channel 1 as Example

4. Connect the GAMMAcast detector to a terminal box or directly to the EVU with the special cable (in accordance with the local conditions). Connect the EVU to the terminal box if needed.
5. Configure the current output for the primary signal (chapt. 4.3) and connect the current output loop (chapt. 11.5).
6. Connect the error relay (chapt. 11.5).
7. Connect the alarm relays (chapt. 11.6), if you have installed an extension module.
8. Connect the digital inputs (chapt. 11.5 and 11.6).
9. Insert the radiation source into the mould or into the casting shielding inside the mould.
10. Carry out calibration and set the required parameters for operation (chapt. 7.2). Configure the function of the outputs also (chapt. 7.3).



Note

You can find the procedure for carrying out full calibration and setting the necessary parameters in chapter 7.2. The setting of inputs and outputs is explained in chapter 7.3 .

## 4.2 The Use of a Terminal Box

Install the terminal box in close proximity to the mould in a protected but easily accessible place.

The GAMMAcast detectors and the EVU are to be connected via the terminal box. This connection is to be made with a standard 6-wire shielded cable (6 x 0.5 mm<sup>2</sup>) with a maximum length of up to 1000 m.

As required, the terminal box can be ordered with a plug-in connector (Id. no. 34787, Fig. 8) or for open ends (Id. no. 07005, Fig. 9).

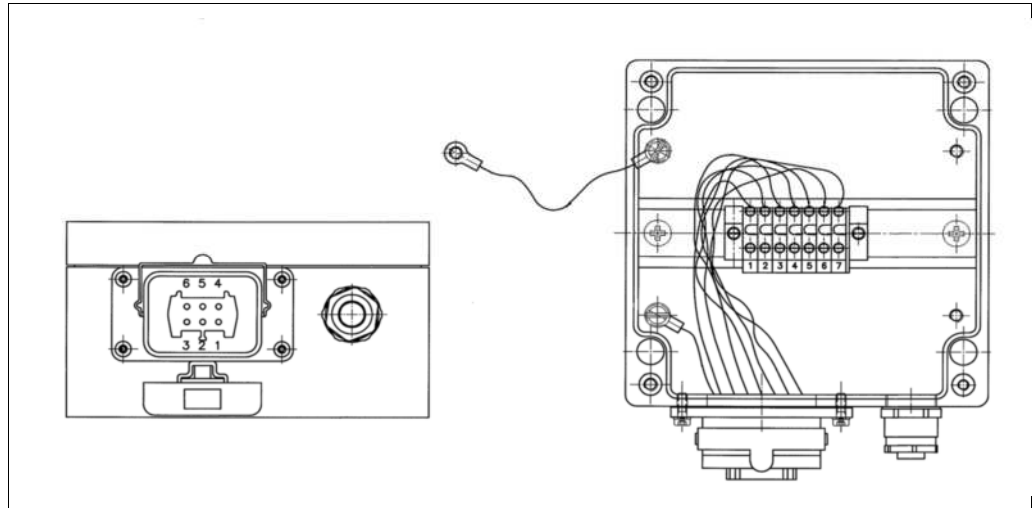


Fig. 8 Terminal Box for GAMMAcast Detectors with Plug-In Connector (Id. no. 34787)

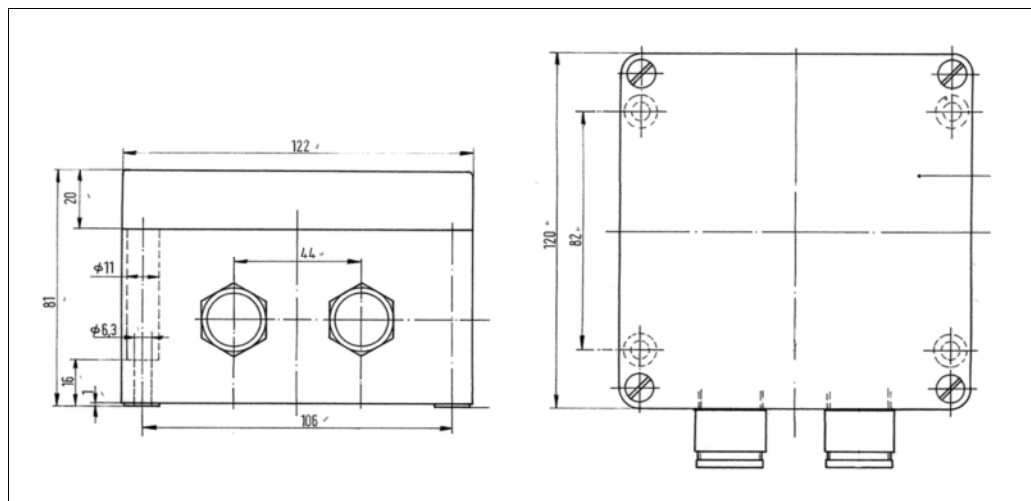


Fig. 9 Terminal Box for GAMMAcast Detectors with Open Ends (Id. no. 07005)

## 4.3 Configuring the Current Output



Danger

### Danger to life from electric shock!

The installation may only be carried out by a qualified electrician.

- Electric shock.
- Please adhere to the relevant safety regulations.
- Only carry out maintenance work when the device is free of voltage.

You can assign the current outputs to two different modes. In order to do so, you must configure the current outputs at the changeover switches on the basic and extension modules.

In source mode, the current output is active and in sink mode, the current output is passive.

Source Mode (Active Current Output)	Sink Mode (Passive Current Output)
<b>Meaning:</b> The EVU supplies the current loop (factory setting)	<b>Meaning:</b> An external power supply supplies the current loop.
Max. Impedance: 500 $\Omega$ Min. Impedance: 120 $\Omega$	Minimum impedance: 120 $\Omega$ <b>Max. 24 V<sub>AC</sub> / Min. 12 V<sub>DC</sub></b> Max. Impedance at 12 V: 250 $\Omega$ Max. Impedance at 24 V: 500 $\Omega$

### 4.3.1 Configuring the Current Output on the Basic Module

Before you start to configure the current outputs, get an overview of the installed modules.

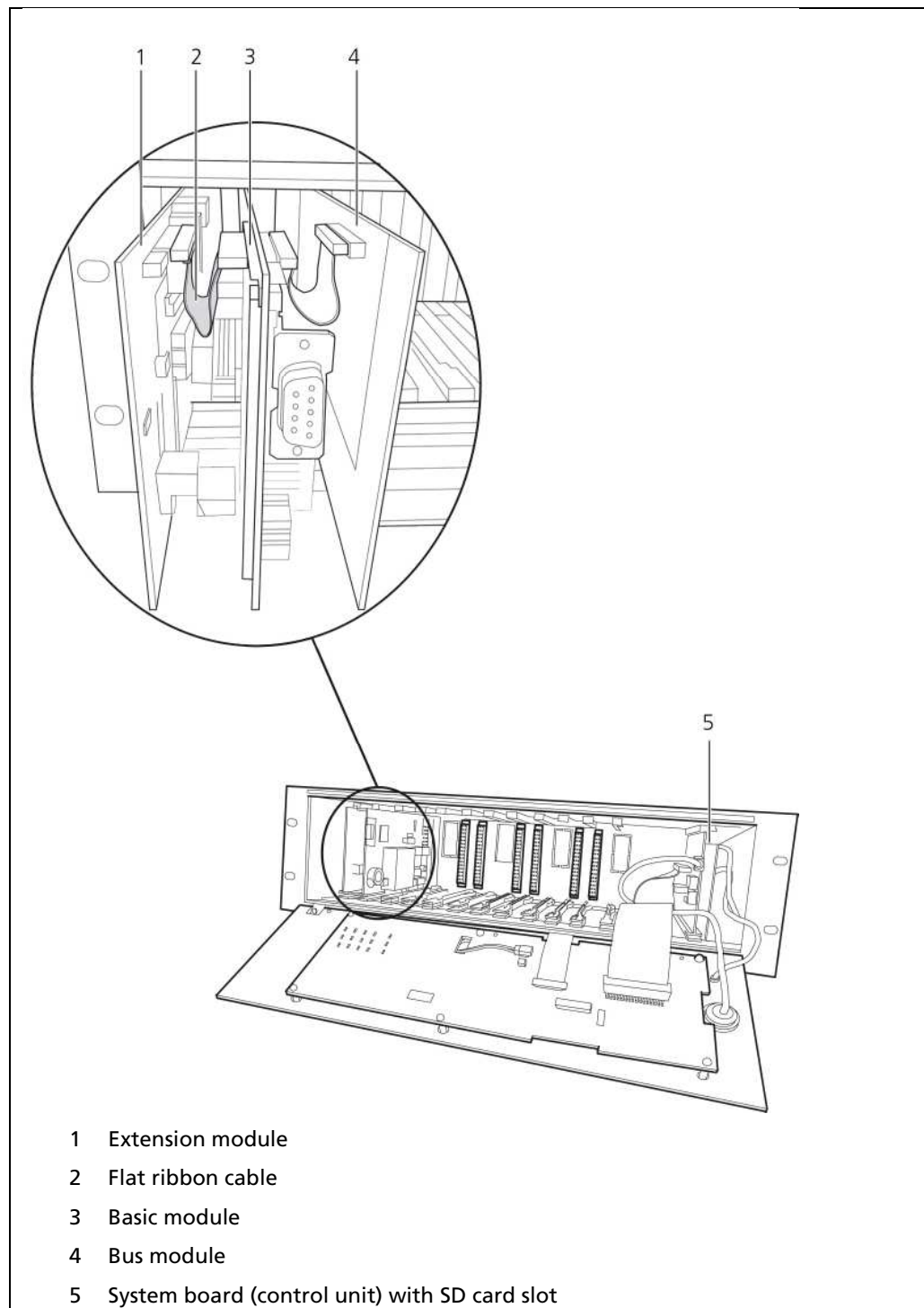


Fig. 10 Overview of the Installed Modules

## Configuring the Current Output on the Basic Module (Continued)

Approach the configuration of the current output as follows:



Danger

### Danger to life from electric shock!

The installation may only be carried out by qualified electricians.

- Electric shock.
- Only open the device when free of voltage.

1. Disconnect the EVU voltage.
2. Loosen the three screws (Fig. 11, Pos. 2) on the front panel

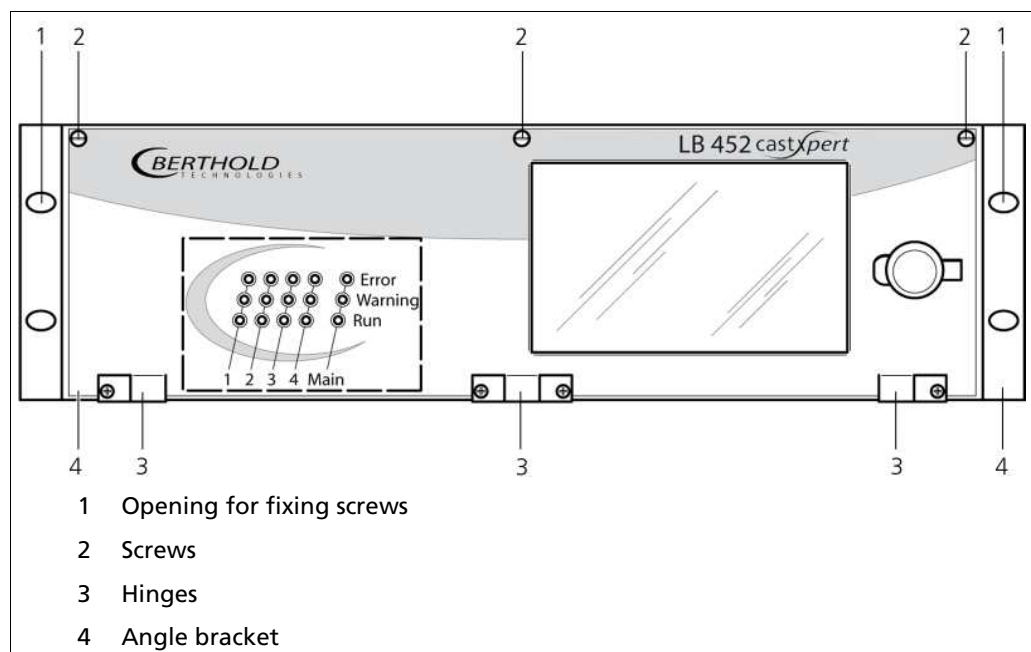


Fig. 11 Assembly Front View

3. Fold down the front panel.
4. Pull all modules (Fig. 10, Pos. 3) of the measurement channel out **at the same time** and remove the flat ribbon cable(s) if needed (Fig. 10, Pos. 2).

## Configuring the Current Output on the Basic Module (Continued)

- Set the desired position at the changeover switch (Sink Mode (Fig. 12, Pos.1) or Position Source Mode (Fig. 12, Pos. 2)).

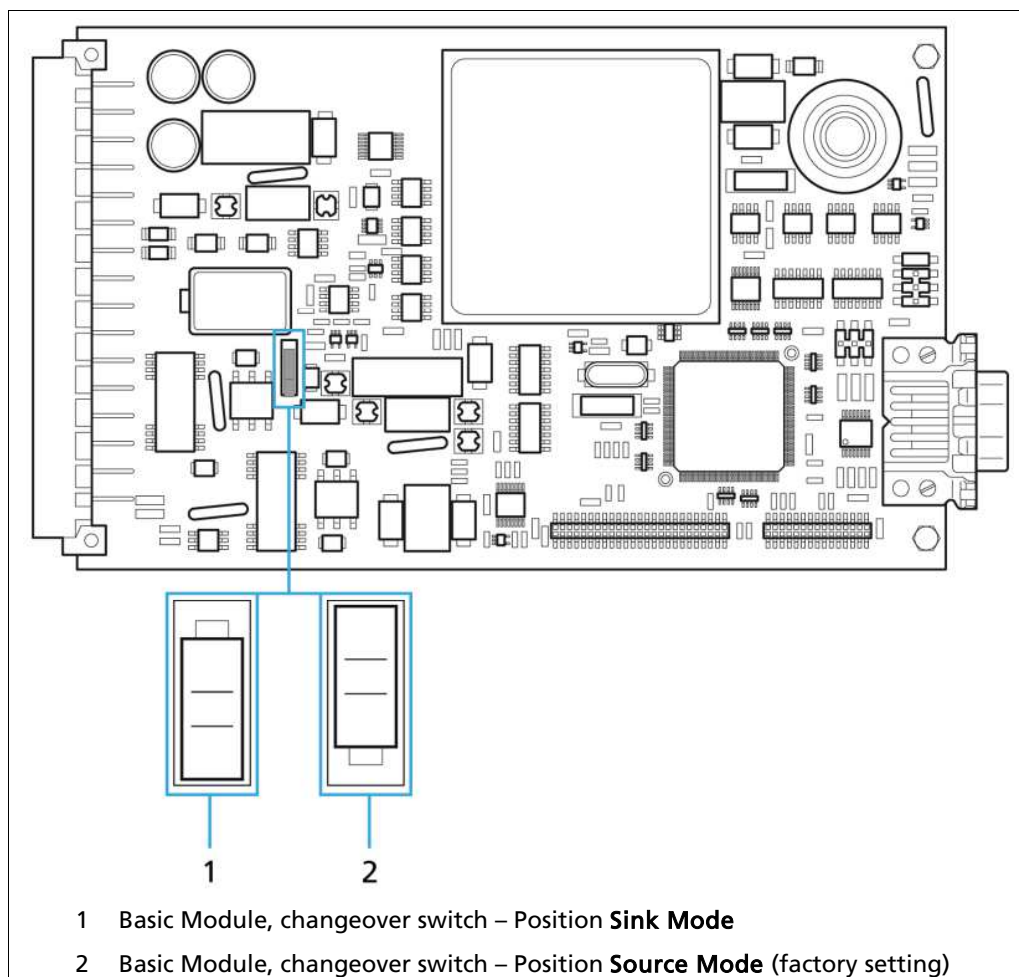


Fig. 12 Switching on the Basic Module Current Output at the Changeover Switch

- Connect the module with the flat ribbon cable again.
- Push all the modules (Fig. 10, Pos. 3) of the measurement channel in again **at the same time**.
- Fold the front panel up again.
- Tighten the screws again.



Note

Ensure that the position at the changeover switch on the basic module and on the extension module is the same!

- Use **the same** current output configuration on the basic and extension modules.

### 4.3.2 Configuring the Current Output on Extension Module

1. Disconnect the EVU voltage.
2. Loosen the three screws on the front panel (Fig. 11, Pos. 2).
3. Fold down the front panel.
4. Pull all modules (Fig. 10, Pos. 3) of the measurement channel out **at the same time** and remove the flat ribbon cable(s) if need be (Fig. 10, Pos. 2).
5. Set the desired position at the changeover switch (**Sink Mode** (Fig. 13, Pos.1) or Position **Source Mode** (Fig. 13, Pos. 2)).
6. Connect the module with the flat ribbon cable again if need be.
7. Push all the modules (Fig. 10, Pos. 3) of the measurement channel in again **at the same time**.

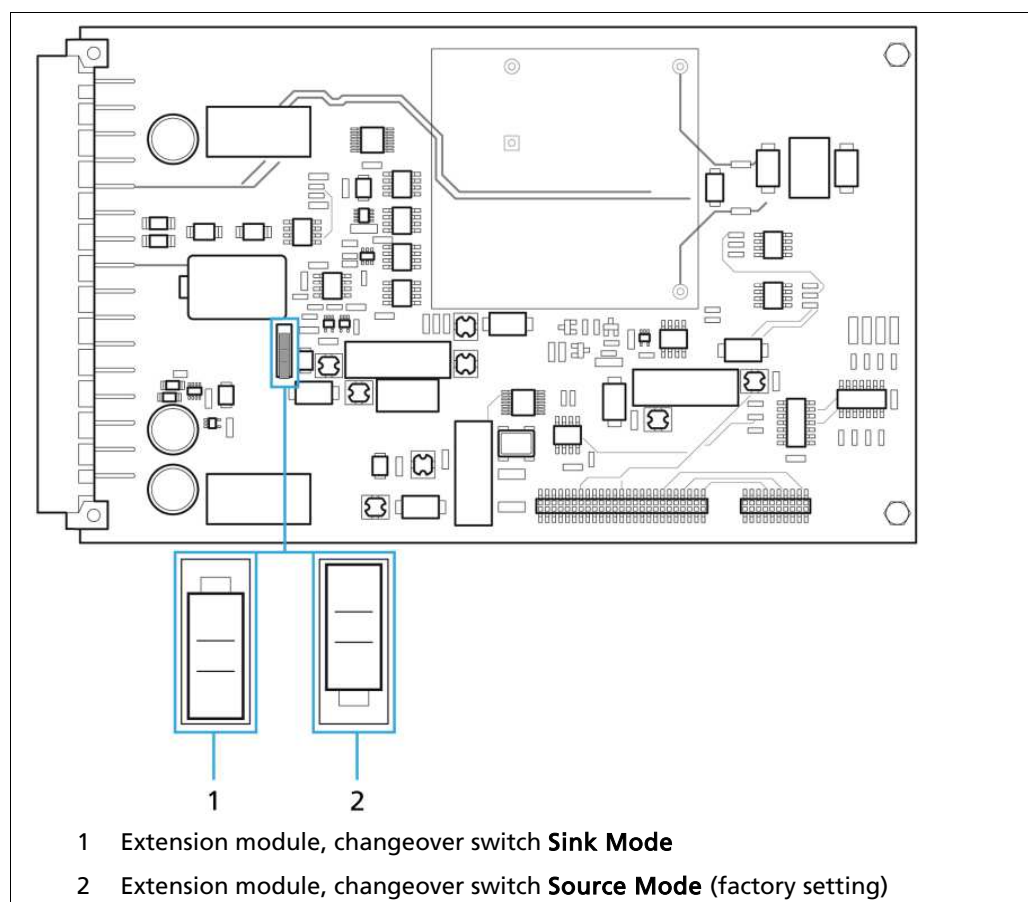


Fig. 13 Extension Module, Setting the Current Output at the Changeover Switch

8. Fold the front panel up again.
9. Tighten the three screws again.

## 4.4 Data Definition Profibus DP

### Cyclic Output Data

Variable name	Description	Type	Size
Mould Level	Current Mould Level unit: %/mm/inch (selectable)	Float	32 Bit
Detector Raw Value	Current Detector Raw Value unit: GAMMAcast - Pulses per Second (CPS) ECcast – Millivolt (mV)	Float	32 Bit
Detector Temperature	Current Detector Temperature Unit: °C/°F (selectable)	Float	32 Bit
Calibration Index	Currently used calibration [0 ... 7] (decimal) (Calibration curve, alarm thresholds, time constant, etc.)	Byte	8 Bit
System Status	<p>System Status. This field contains binary coded information:</p> <p><b>Bits 0-2: Main state of the system</b>                      Bit 0; 0x1 (1): RUN/MEASUREMENT RUNNING                      Bit 1; 0x2 (2): STOP                      Bit 2; 0x4 (4): ERROR</p> <p><b>Bit 3: Warning</b>                      Bit 3; 0x0 (0): NO WARNING                      Bit 3; 0x1 (1): WARNING</p> <p><b>Bits 4-11: Stop condition</b>                      Bit 4-11; 0x00 (0): Not in STOP state                      Bit 4; 0x01 (1): No detector found                      Bit 5; 0x02 (2): Detector Offline                      Bit 6; 0x04 (4): Test Mode                      Bit 7; 0x08 (8): Calibration running                      Bit 8; 0x10 (16): Full Adjustment running                      Bit 9; 0x20 (32): Empty Adjustment running</p> <p><b>Bits 12-19: Alarms</b>                      Bit 12-19; 0x00 (0) No alarm running                      Bit 12; 0x01 (1): Detector Over Temperature                      Bit 13; 0x02 (2): Min. Fill Level                      Bit 14; 0x04 (4): Max. Fill Level                      Bit 15; 0x08 (8): Gating mode (time constant)                      Bit 16; 0x10 (16): Trim Adjust Up running [only ECcast]                      Bit 17; 0x20 (32): Trim Adjust Down running [only ECcast]</p> <p><b>Bits 20-31: Error number</b>                      A 12 Bit unsigned integer number representing the number of the actual error                      Error# &lt; 1000: LB 452 error                      Error# &gt; 1000: Detector error</p>	Unsigned Integer	32 Bit
			136 Bit = 17 Bytes

### Cyclical Input Data



Variable Name	Description	Type	Size
Calibration Index	Currently used calibration [0 ... 7] (decimal) (Calibration curve, alarm thresholds, time constant, etc.)	Byte	8 Bit
Function Actuation	By writing a number in this field functions on the EVU can be actuated: 0x0 (0) Idle (do nothing) Bit 0; 0x1 (1): Empty Adjust Bit 1; 0x2 (2): Full Adjust Bit 2; 0x4 (4): Trim Adjust Up (One Step) [only ECcast] Bit 3; 0x8 (8): Trim Adjust Down (One Step) [only ECcast] Bit 4; 0x10 (16): Start Automatic Calibration [only ECcast] Bit 7; 0x80 (128): Acknowledge Actual Error	Unsigned Integer	32 Bit
			40 Bit = 5 B



Note

Only cyclic data will be transferred.



Attention

### Device is not working correctly!

Fieldbus Module Data is not being received.

- Install the driver (GSD file) into the control centre in order to be able to receive the fieldbus module data!
- Check the Profibus ID (Profinet IP address)

The fieldbus module can be distributed in the following versions:

**Version 1:** RS-485 port (Profibus DP) or

**Version 2:** RJ-45 Ethernet port (Profinet IO) (planning stage)

## 4.5 Mounting an SD Card



Attention

### Material damage to the device or the system!

System crashes.

- Never install or remove an SD card while in running operation.

You have the possibility of saving data, error reports and adopted settings on an SD card. In order to do so, you must install an SD card in the control unit.

For the saving of data, see chapt. 6.3.2 and 6.4.

Approach the installation of the SD card as follows:

1. Disconnect the EVU voltage.
2. Loosen the screws on the front panel (Fig. 11, Pos. 2) and fold down the front panel.

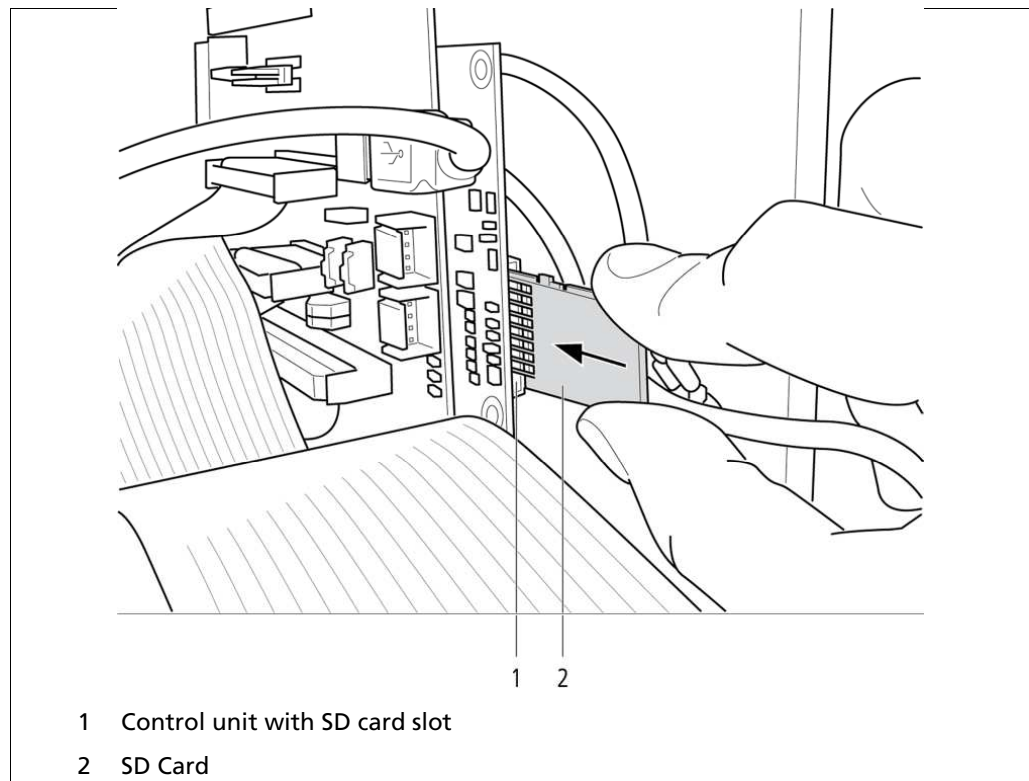


Fig. 14 Control Unit, Installation of the SD Card

3. Push the SD card (Fig. 14, Pos. 2) ) into the SD card slot (Fig. 14, Pos. 1) on the control unit until the SD card snaps into place.
4. Fold the front panel up again and tighten the three screws.

# 5 Operation of the Software

In this chapter, the operation of the software and the different setting options of the EVU are explained.

The EVU does not have a separate on and off switch. As soon as the energy supply is connected, the system and the EVU start up.

During the start-up process, the start screen with the version number of the installed software is shown on the display (Fig. 15, Pos. 1).

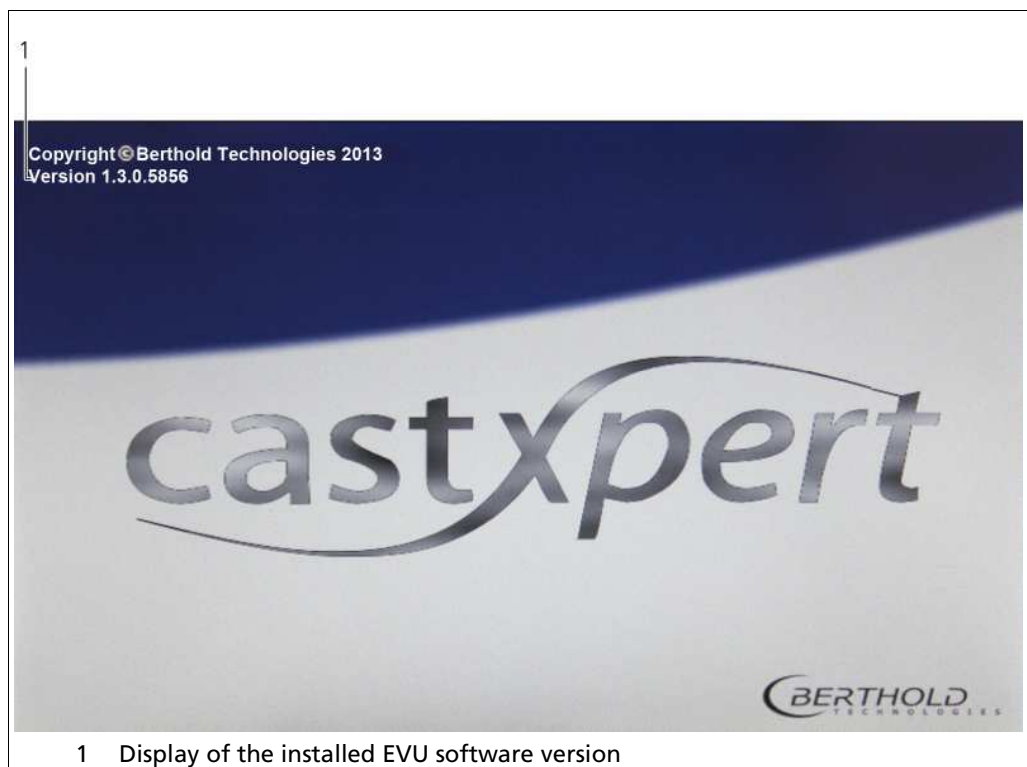


Fig. 15 Software Display Screen when Switching on the EVU

## 5.1 Overview of the Standard Display

If the system is fully loaded and running, the start page of the measurement system is displayed (Fig. 16).

The display varies depending on which measurement channels are installed. For example, two measurement channels are shown in Fig. 16.



As soon as several detectors are connected to the individual measurement channels, these are automatically represented on the standard display.

Note

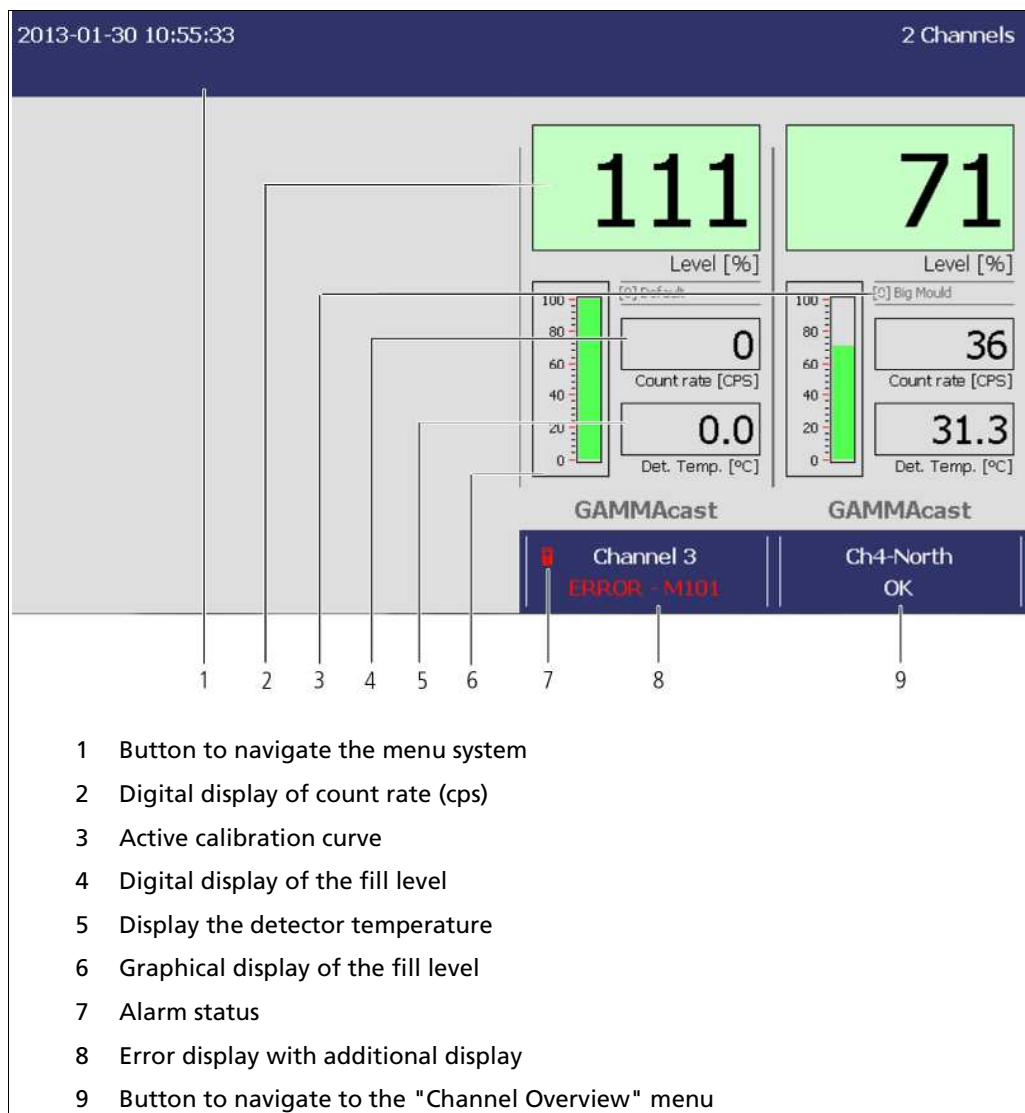


Fig. 16 Standard display of the EVU

Click on the top blue bar (Fig. 16, Pos. 1) to reach the system menu (chap. 6 „The System Menu“).

Under the display for the measurement channels, there is a button that leads to its respective "Channel Overview" menu (see chapt. 7 "Channel Overview" Menu Menu) .

Positions 2 to 9 give you a view of graphical information for the fill level (Fig. 16, Pos. 6), of the detector temperature (Fig. 16, Pos. 5), of the fill level (Fig. 16, Pos. 2) and the count rate (Fig. 16, Pos. 4).

In case of failure, the error number is displayed (Fig. 16, Pos. 8). All castXpert LB 452 error messages have the identifier "M" and all GAMMAcast LB 67xx error messages have the identifier "D".

In addition, the following additional information is displayed:

- Identification of the measurement channel (Fig. 16, Pos. 9)
- Identification of the calibration curve (Fig. 16, Pos. 3)
- Alarm status (Fig. 16, Pos. 7)

## 5.2 Operation of the EVU

The following figures display the structural framework of the EVU (Fig. 17) and the input options (Fig. 18).

Operation Options:

- Via the touch display.
- With a mouse and a keypad which are connected at the USB port on the front panel (Fig.1, Pos. 3).
- With a mouse and a keypad, if the EVU is operated via remote control software.



If you would like to connect more than one USB device to the EVU, then use a USB hub.

Note

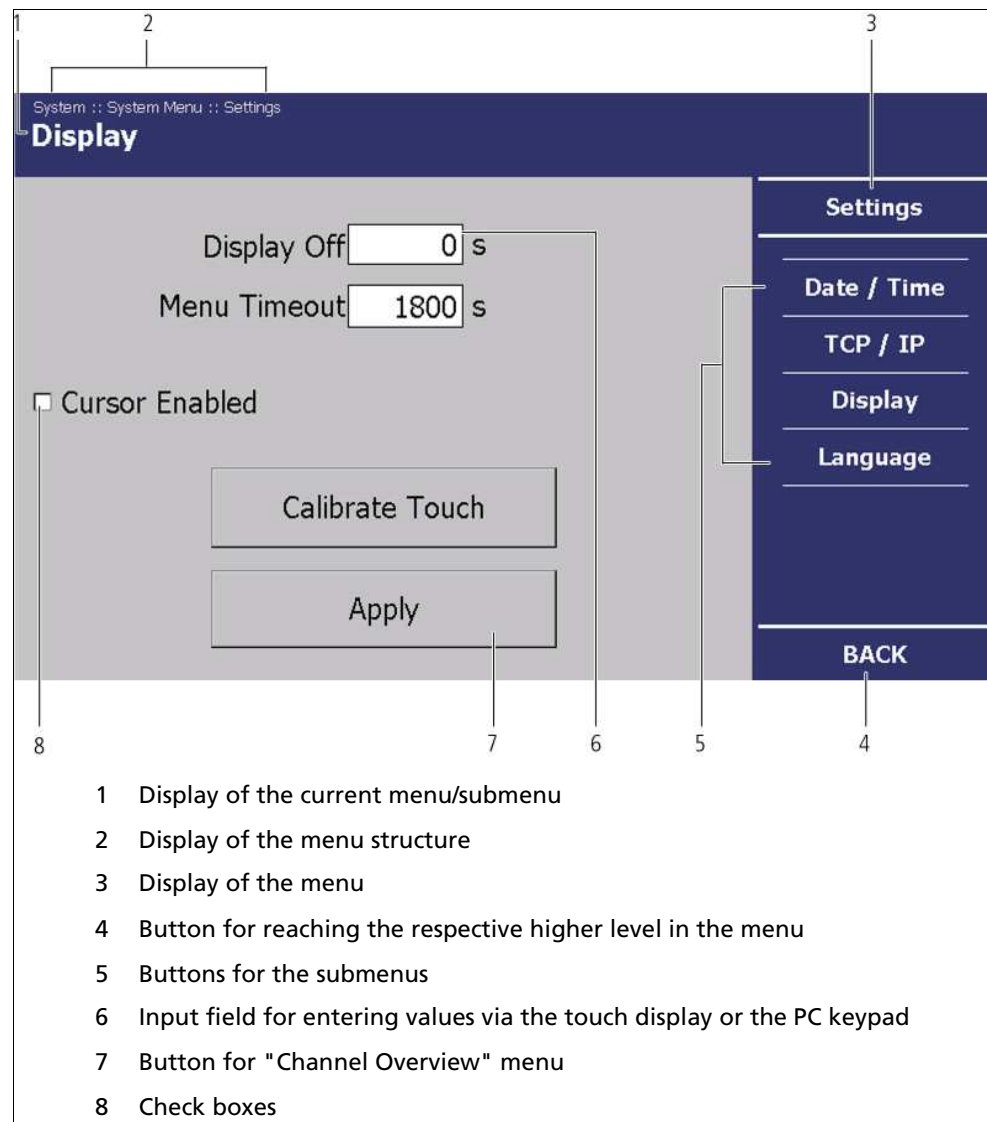


Fig. 17 Overview of a Menu with Buttons and Input Fields

### Operation of the EVU (Continued)

As soon as you click on an input field , the numeric keypad or the keypad is automatically displayed on the touch display.

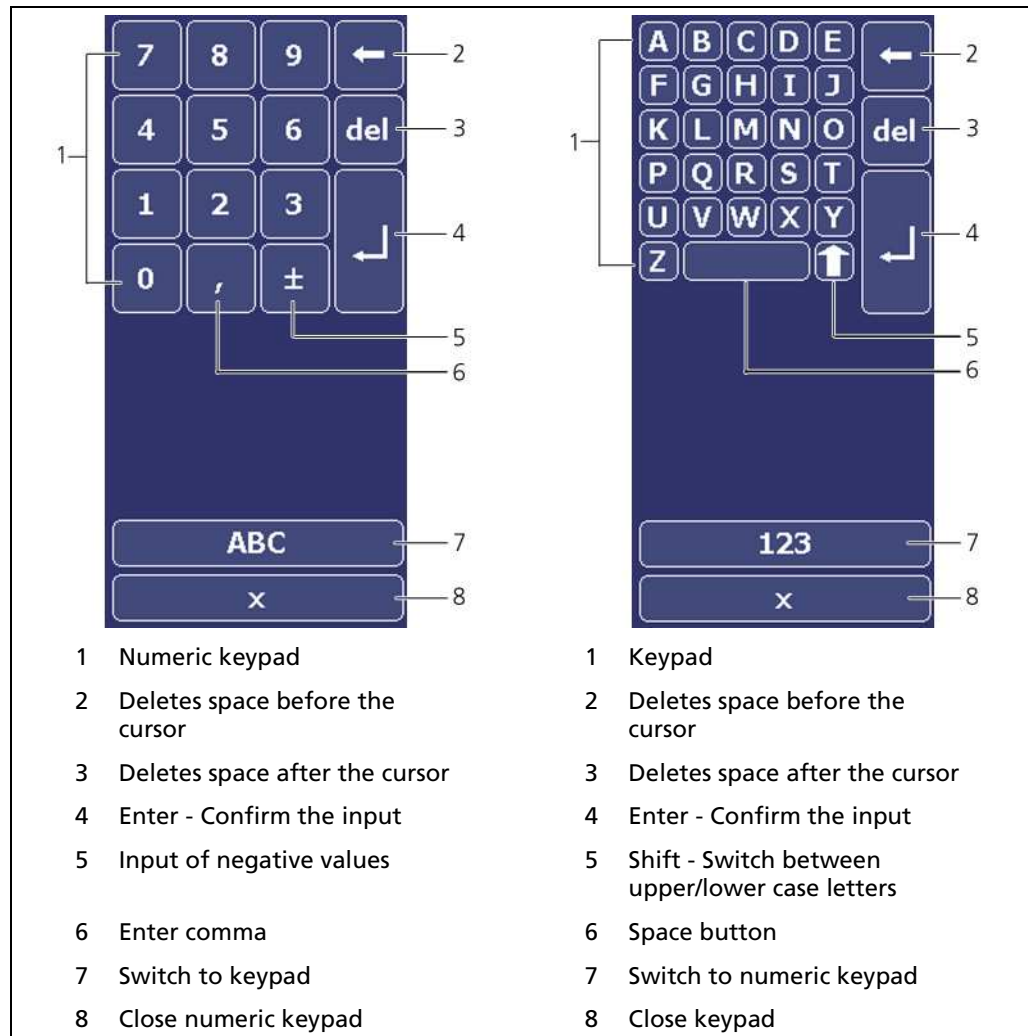


Fig. 18 Numeric Keypad and Keypad





# 6 The System Menu

In the system menu you can make system settings which apply to all measurement channels.

**The system settings do not affect the measurement!**

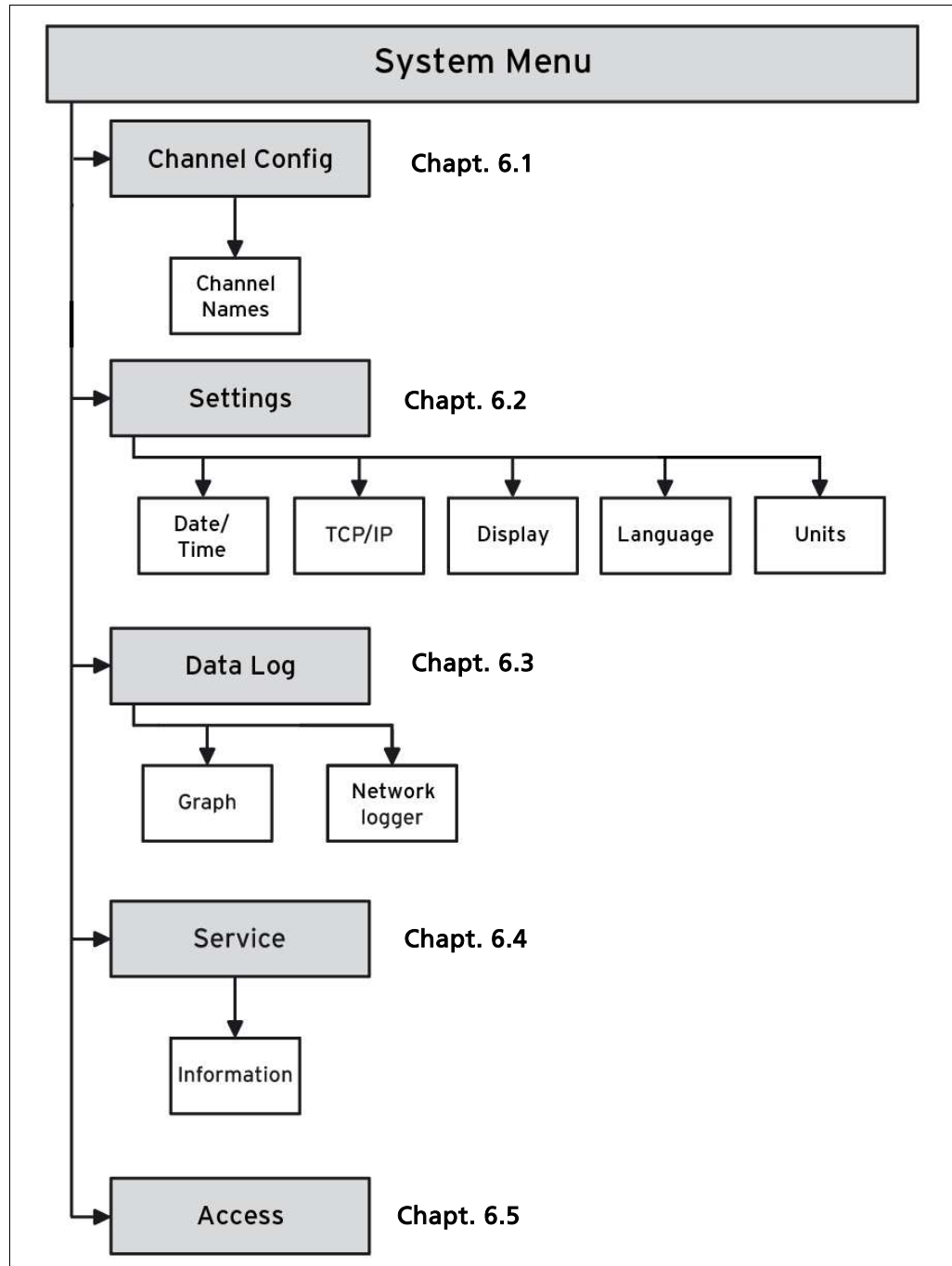


Fig. 19 Menu Structure of the System Menu

## System Menu (Continued)

To reach the system menu, click on the top blue bar on the standard display (Fig. 16, Pos. 1).

⇒ The System Menu (Fig. 20) is opened.

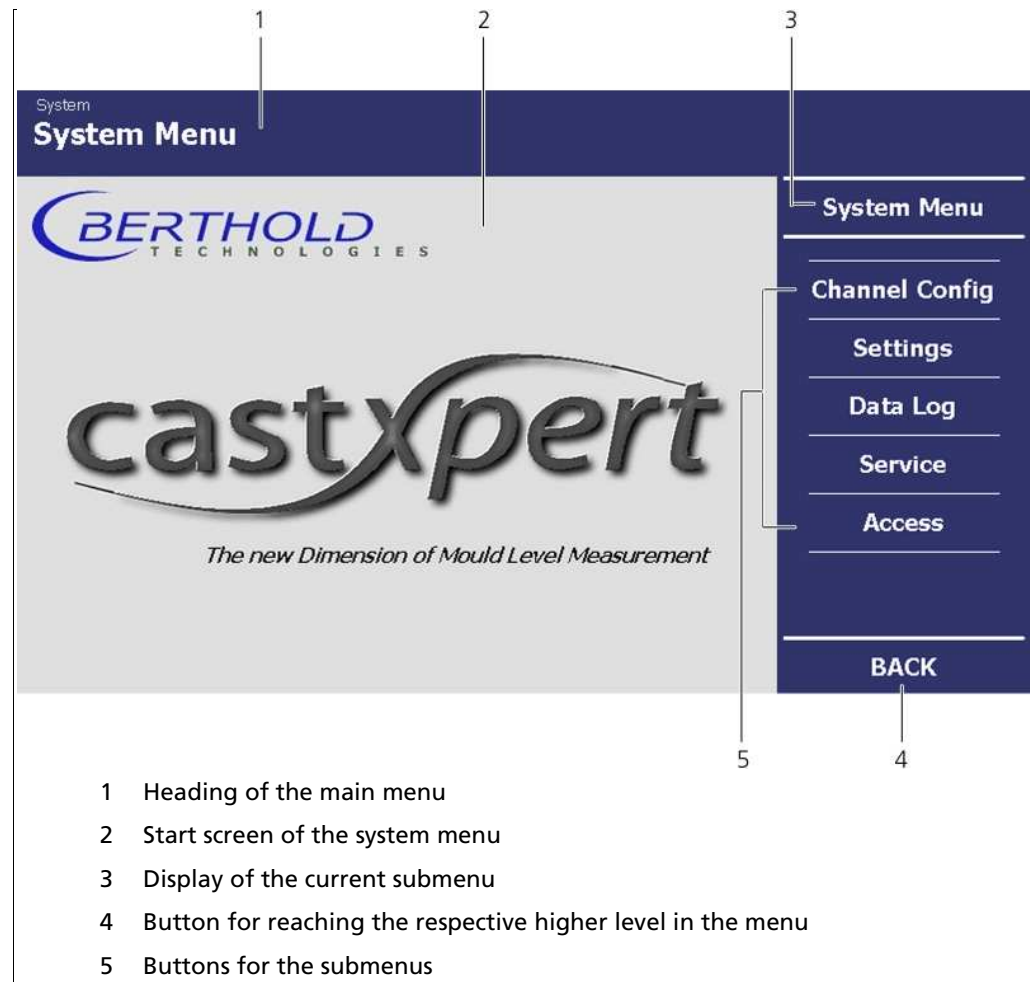


Fig. 20 System Menu, Start Page

In the system menu, you can make the following settings:

<b>Channel settings</b>	Setting of the channel assignment and the measuring method.
<b>Settings</b>	General settings like time, date and language.
<b>Data Log</b>	Setting of the log intervals and data export.
<b>Service</b>	Carrying out of updates for the evaluation unit, the measurement unit and the detectors.
<b>Access Level</b>	Allocation of user rights and passwords.

## 6.1 Channel Setting

In the channel setting submenu, you can set the channel assignment (Fig. 21, Pos. 4) and the measurement method (channel mode) for the different GAMMAcast detectors.



### Measurement not possible!

Attention

- There are two methods of measurement. Set the method according to the detectors you are using:
- **Radiometric** in conjunction with the GAMMAcast detectors, which are based on the radiometric method.
- **Eddy Current** in conjunction with the ECcast detectors, which are based on the eddy current measurement method.

System :: System Menu  
**Channel Config**

Channel 1 Channel 2 Channel 3 Channel 4

INSTALLED N/A N/A N/A

UID:  
0x5E000112

Software Version:  
1.1.0

ChannelMode:  
Radiometric  
Radiometric  
Eddy Current

Apply

Channel Config

Channel Names

BACK

1 2 3 4 5

- 1 Drop-down menu for the channel mode (measurement method)
- 2 Display of the software version and serial number of the measurement channel
- 3 Apply button for saving the settings
- 4 Drop-down menus for the channel assignment
- 5 Channel settings menu button

Fig. 21 System menu, Channel Settings

In the menu **<Channel Settings>** in the drop-down menu "Channel Mode" set the measurement method for the detectors used to **Radiometric** or **Eddy Current** (Fig. 21, Pos. 1).

### 6.1.1 Channel Names

A name can be assigned to each of the four measurement channels. This name is imported into the standard display and is used for all service files when they are exported.

Click in the System menu on <Settings | Channel Settings | Channel Names> in order to assign a name to a channel.

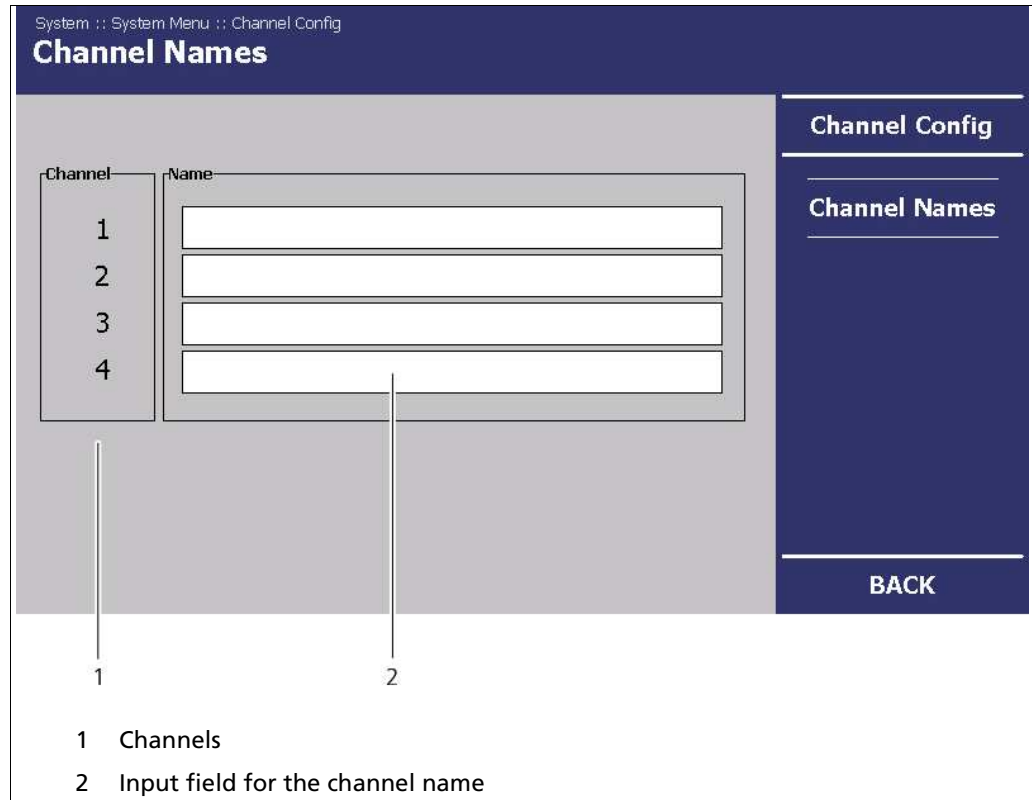


Fig. 22 System Menu, Channel Settings

## 6.2 Settings

In the **System Menu**, click on **<Settings>** (Fig. 20, Pos. 5), in order to reach the Settings submenu.

⇒ The submenu **Settings** is opened (Fig. 23).

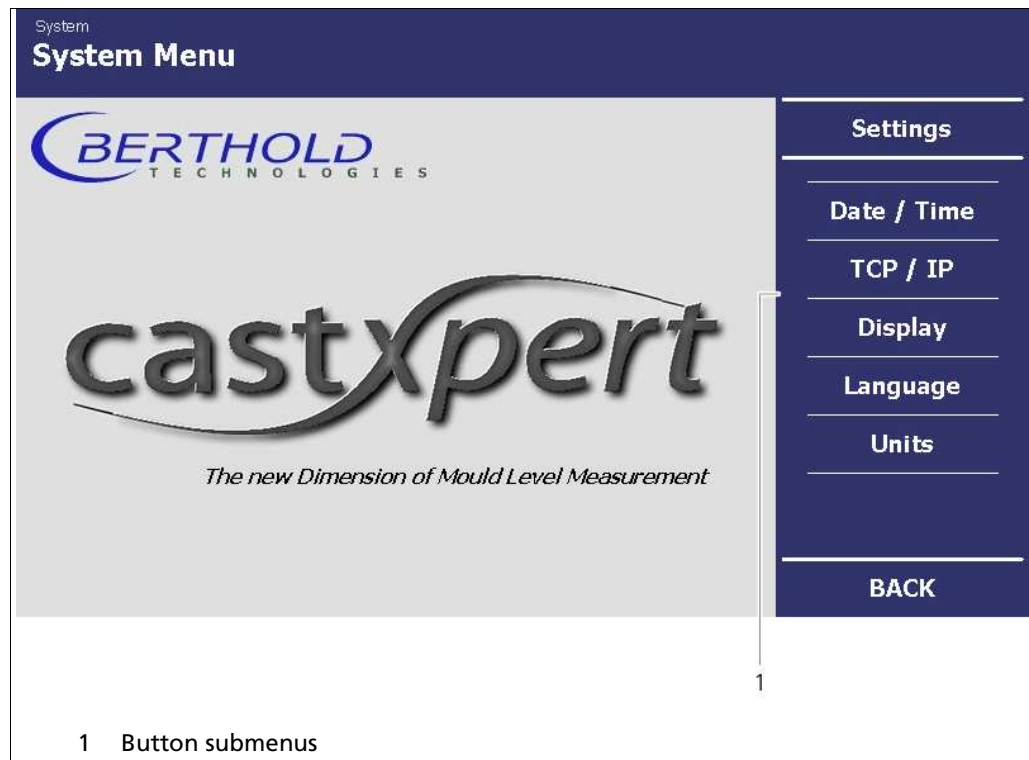


Fig. 23 System menu, Settings

In the **<Settings>** submenu, you have the following settings options:

- Setting the date/time
- Applying and viewing network settings
- Display Setting
- Setting the language
- Setting the units

### 6.2.1 Setting the Date/Time



Note

The date and time must always be set correctly so that all records (log files) have the right metadata.

1. In the **System Menu | Settings**, click on **<Date/Time>**, to reach the Date/Time submenu (Fig. 23, Pos. 1).

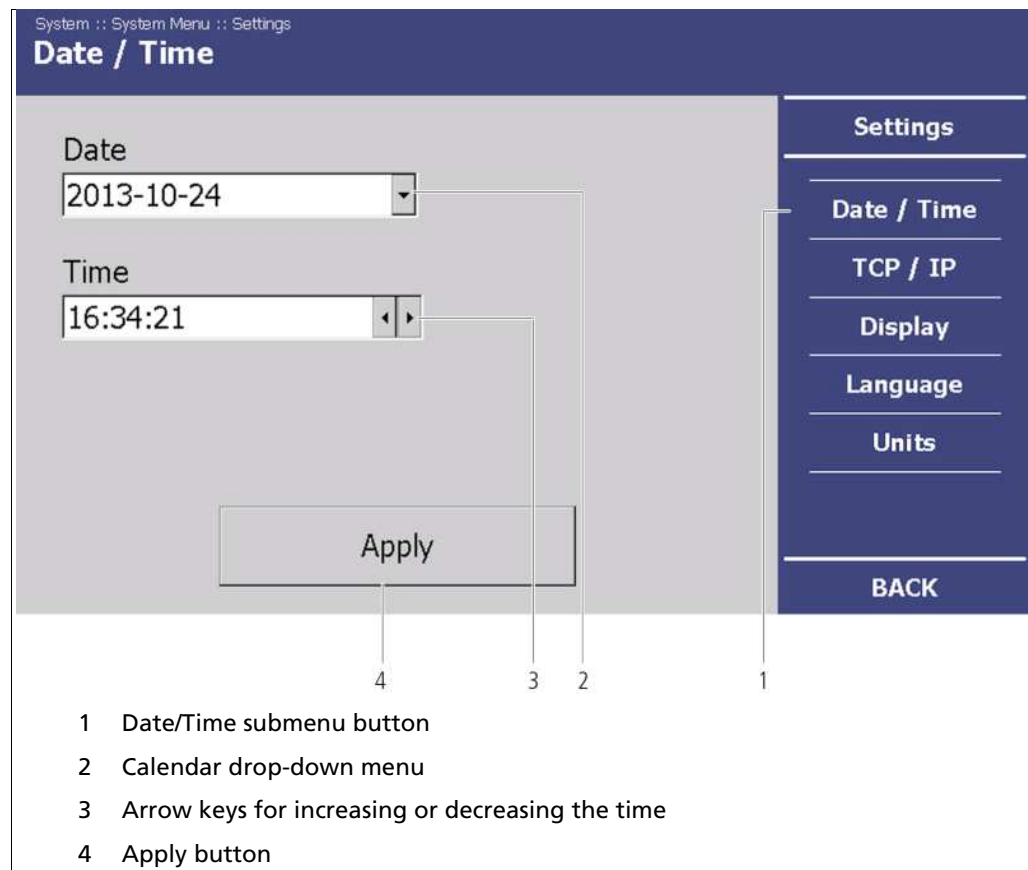


Fig. 24 System Menu, Settings - Date/Time

2. Click on the button drop-down menu (Fig. 24, Pos. 2), to change the date.  
⇒ The calendar is "opened".

## Setting the Date

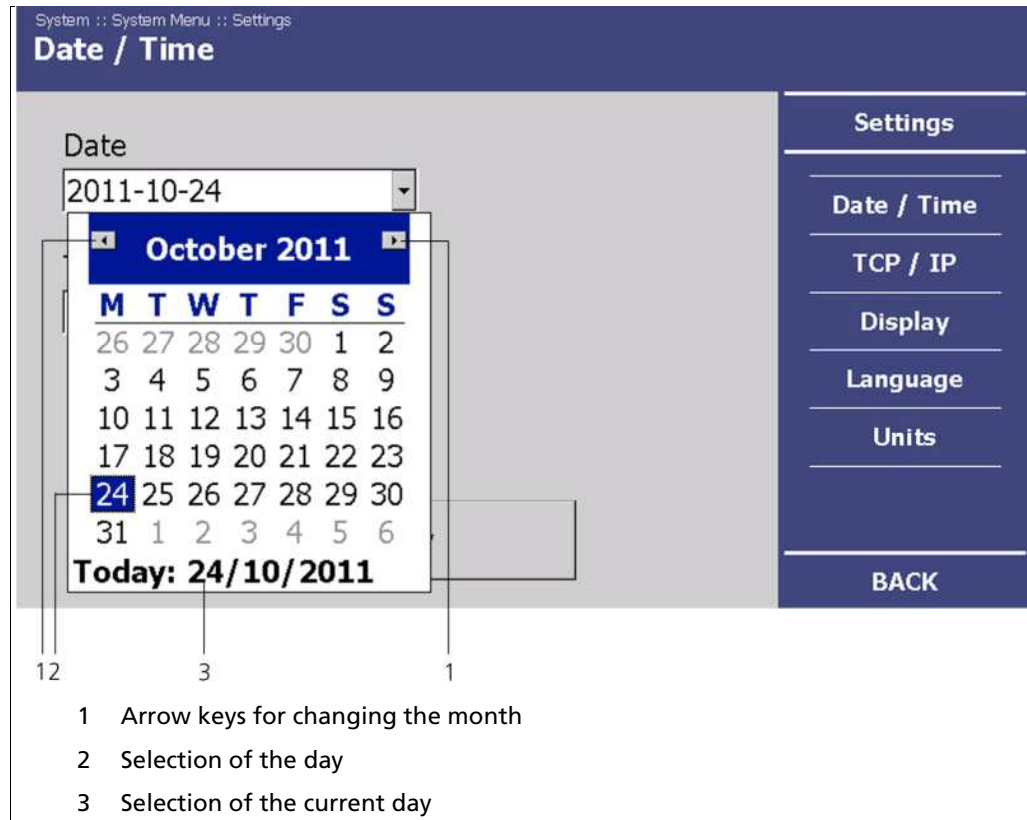


Fig. 25 System menu, Settings - Set Date

3. Set the month (Fig. 25, Pos. 1) by clicking on the arrow keys.
4. Set the day (Fig. 25, Pos. 2) by clicking on a number in the calendar. Alternatively, you can also set the current day by clicking on "Today" (Fig. 25, Pos. 3).
  - ⇒ The date set is displayed (Fig. 25, Pos. 3).

## Setting the Time

1. In the "Time" display field, click on (Fig. 26, Pos. 1) the time unit (hours, minutes, seconds), which you want to change.
2. Change the time by clicking on the arrow keys (Fig. 26, Pos. 1).

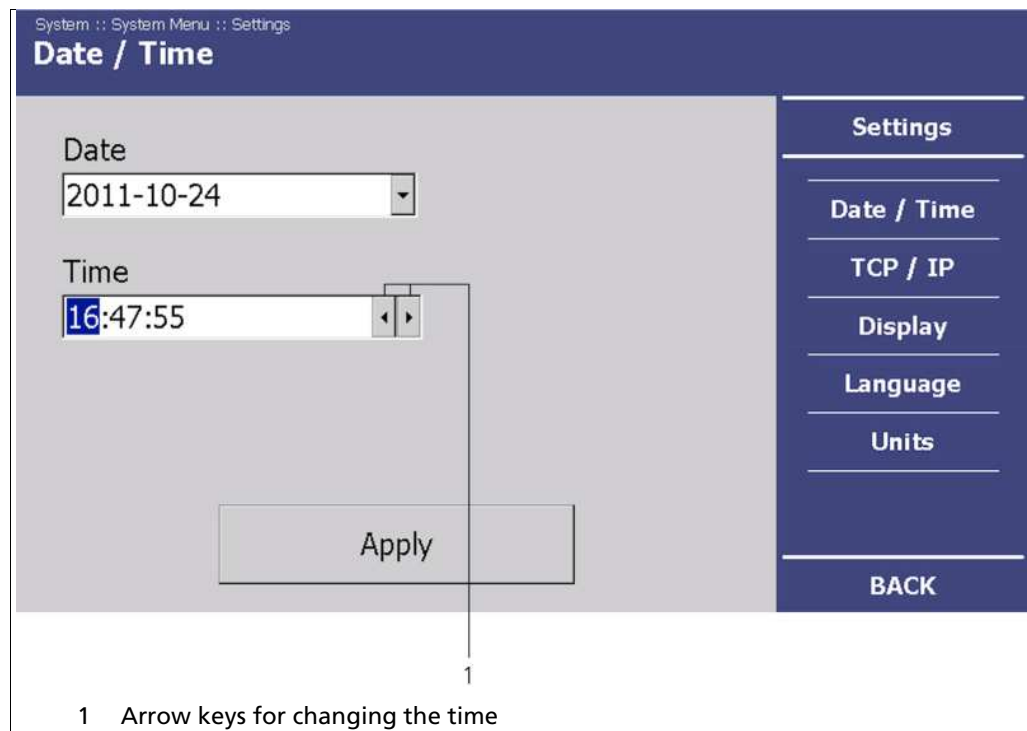


Fig. 26 System menu, Settings - Setting the Time

3. Click on <Apply>, to adopt the date and time settings.



Note

All settings applied must be confirmed by clicking on <Apply>, for the settings to become effective.



## 6.2.2 Applying Network Settings

In the network settings submenu, you can make changes to the network settings.

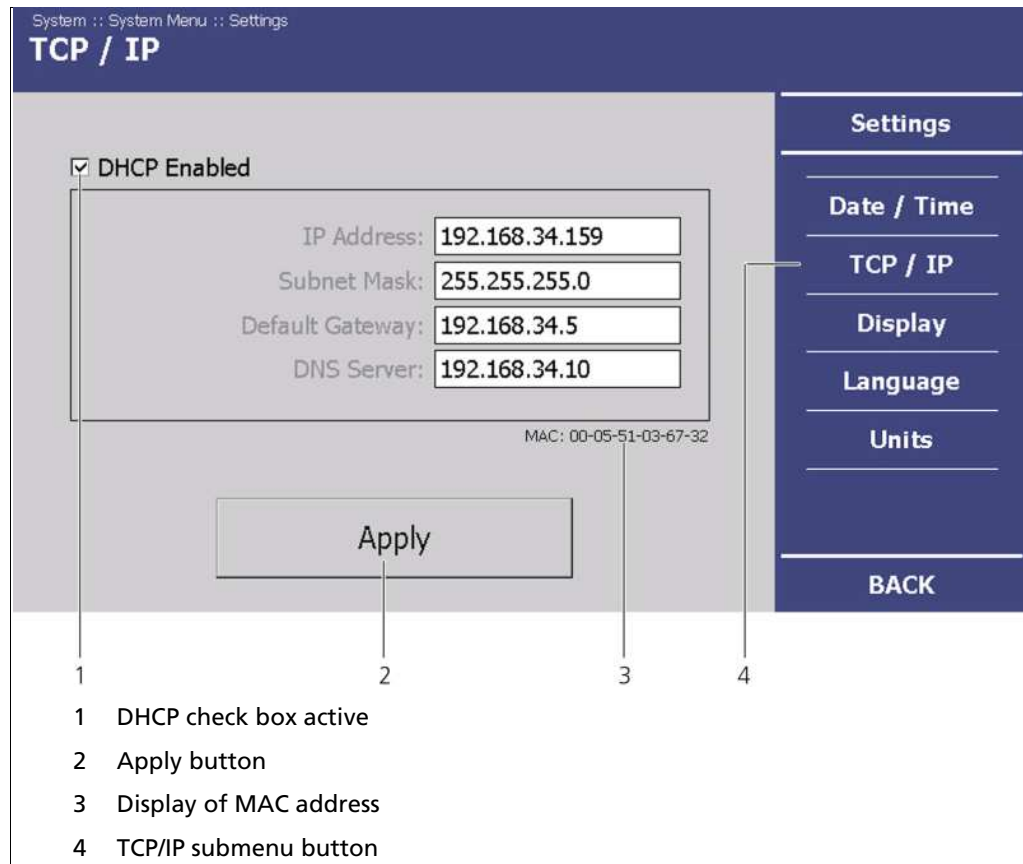


Fig. 27 System Menu, Settings - TCP/IP



Note

In the event of an automatic assignment of the IP address by a DHCP server, you can only look at the given IP address. A modification of the IP address is not possible.

On this site, you can also read the MAC address of the device (Fig. 27, Pos. 3).

## Applying Network Settings (Continued)



Note

### No communication via the remote control software!

The EVU cannot be accessed via the RC software.

- If you have not put a tick next to <DHCP active> (Fig. 27, Pos. 1), then check your applied network settings!

In the **System Menu | Settings** click on <TCP/IP> (Fig. 27, Pos. 4), to change the network settings.

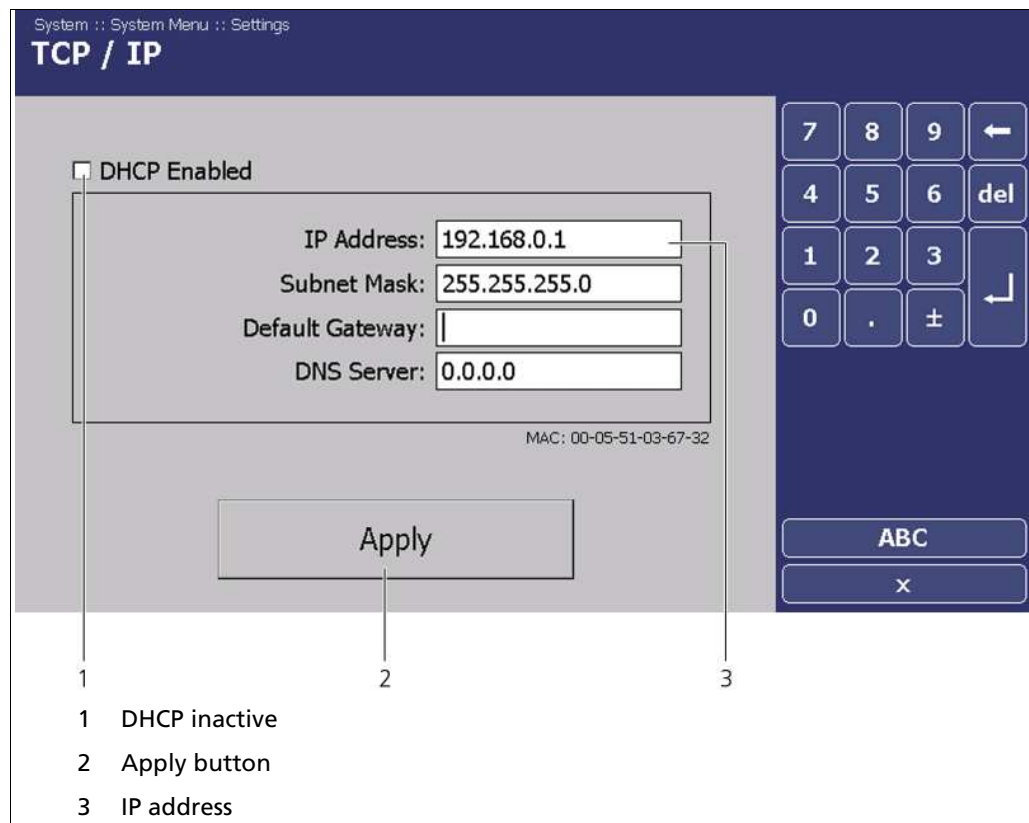


Fig. 28 System Menu, Settings - TCP/IP

You can set the network address either manually or using DHCP (automatic assignment). Put a tick next to <DHCP active> in the check box (Fig. 27, Pos. 1).

1. Click on <Apply>, to adopt the changes (Fig. 27, Pos. 2).

### 6.2.3 Display

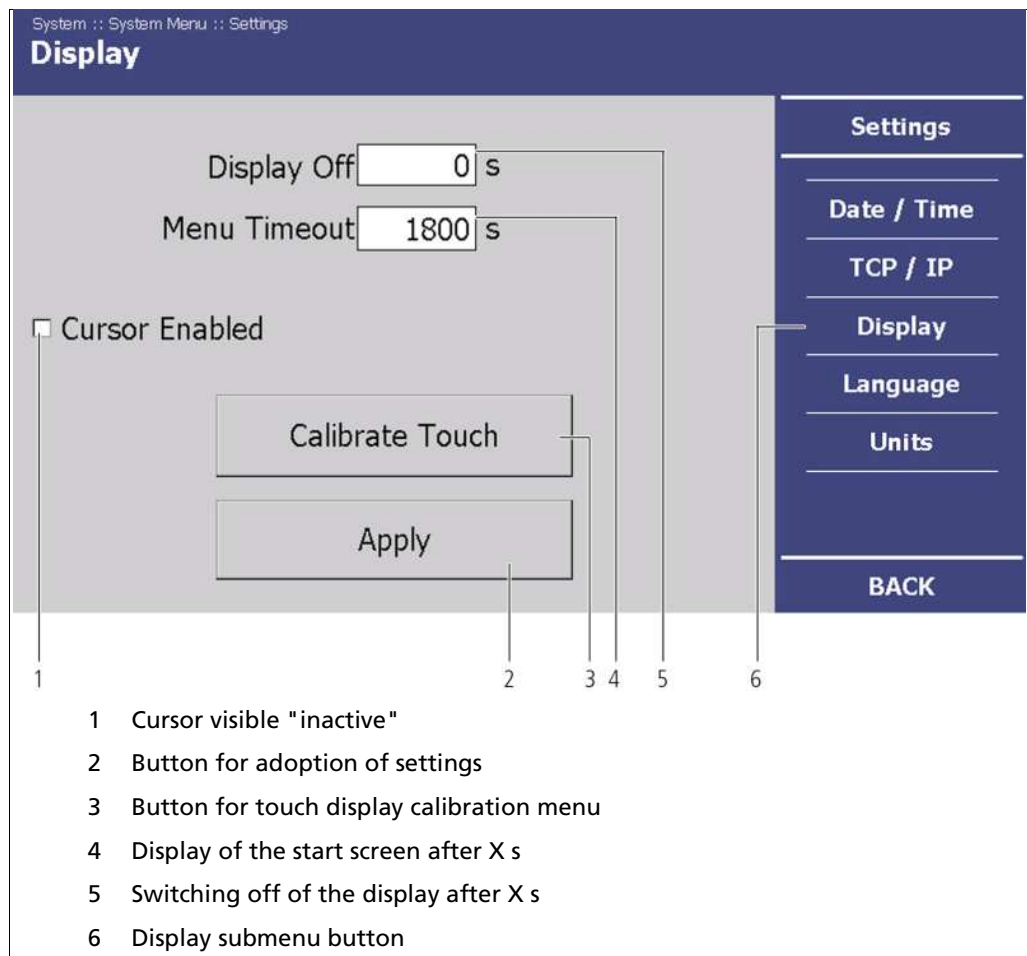


Fig. 29 System Menu. Settings - Display

In the **System menu | Settings** click on **<Display>** (Fig. 27, Pos. 4), to make changes to the display or to calibrate the touch display.

In the **<Display>** submenu, you can make the following settings:

<b>Display Off</b>	Here, the turn-off time of the display can be entered. For a value of <b>0 s</b> the display is always active.
<b>Menu Timeout</b>	Here, it is possible to enter the time after which the menu should be left if the user has not made an entry.
<b>Cursor Enabled</b>	If the EVU is to be operated with a mouse, a tick must be put in the "Cursor visible" check box (Fig. 29, Pos. 1). The cursor is visible even if there is no mouse connected and the EVU is operated via the touch display.
<b>Calibrate Touch</b>	When the <b>&lt;Calibrate Touch&gt;</b> button is clicked, a menu for touch display calibration is opened.



Note

The following settings described "Switch off display", "Leave menu" and "Cursor visible" can all be applied at the same time.

This way, it is only necessary to restart the EVU once.

### 6.2.3.1 Calibrate Touch Display



Note

The calibration may only be carried out with direct skin contact. Take gloves or any other protective equipment off your hands.

1. Click on <Calibrate touch pad> (Fig. 29, Pos. 3).  
⇒ The calibration screen opens (Fig. 30).
2. Press the middle of the displayed cross with your finger.  
⇒ If you take your finger off the cross again, the cross jumps to the top left corner (Fig. 30).

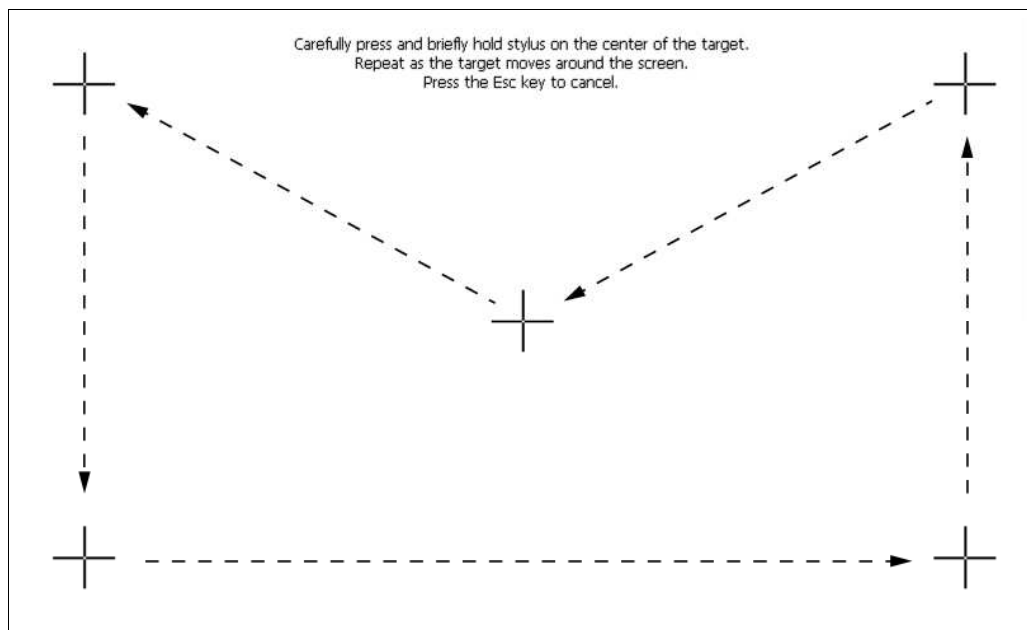


Fig. 30 System Menu. Settings - Display (Calibrate Touch Display)

3. Repeat the process until the cross is no longer displayed and the calibration is finished.  
⇒ After successful calibration, the "Display" submenu is displayed.

### 6.2.4 Setting Language

1. In the **System Menu | Settings** click on **<Language>**, to change the menu language. (Fig. 23, Pos. 1).
2. Click on the drop-down menu "Language" (Fig. 31, Pos. 2), to select the desired language.  
⇒ The drop-down menu opens.
3. Click on the desired language to select this as the user interface language.  
⇒ A confirmation message is displayed.
4. Click on **<OK>**, to restart the EVU.  
⇒ The EVU restarts. The measurement remains unaffected by this.

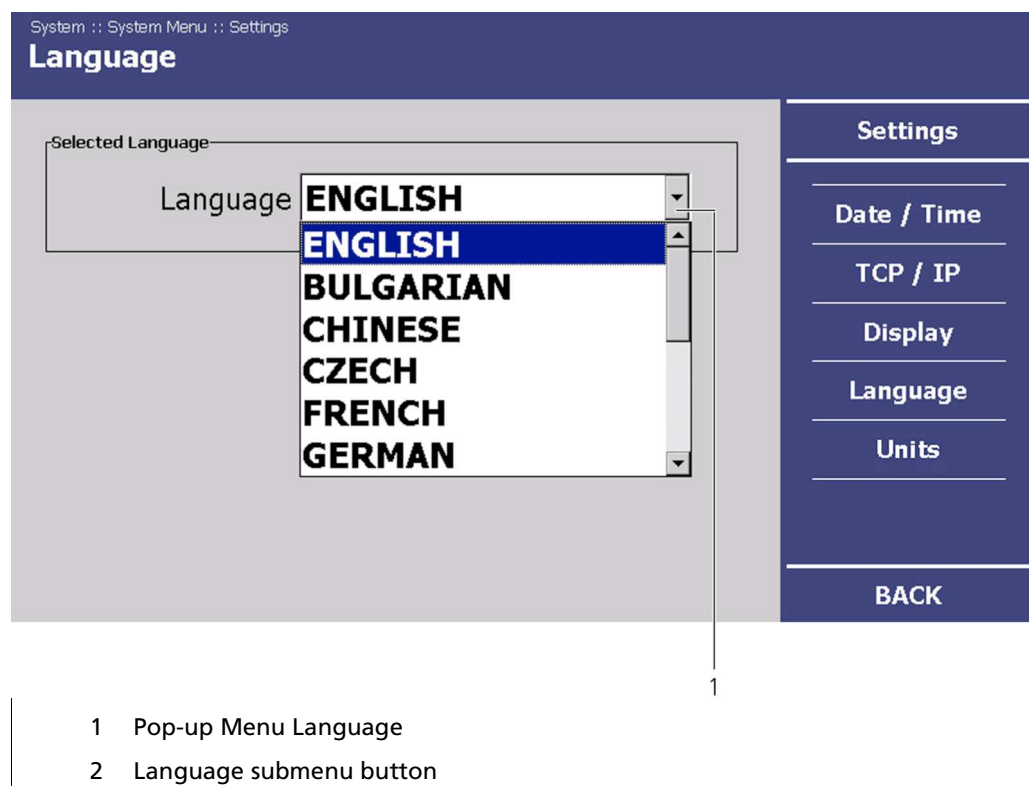


Fig. 31 System Menu. Settings - Language

## Setting Language (Continued)



Note

The standard languages Bulgarian, German, English, French, Italian, Portuguese, Romanian, Russian, Spanish, Czech and Hungarian are always installed.

These can be supplemented by the following languages:

Korean or

Chinese

The installation of these language packages is carried out using the control unit software update. Language files have the ending **.btw**. (Ex: **LB452CU\_FontUpdate\_.btw**)

See Control Unit Software Update (Chapt. 6.4.2).

### 6.2.5 Setting Dimensions and Temperature Unit

1. In the **System Menu | Settings** click on **<Units>**, to change the measurement unit. (Fig. 32, Pos 3).
2. Click on the drop-down menu "Fill Level" (Fig. 32, Pos. 1), to select the desired measurement unit.
  - ⇒ The drop-down menu opens.
3. Click on the desired measurement unit to select it.
  - ⇒ The measurement unit is set.

Carry out the selection similarly for the temperature unit (Fig. 32, Pos. 2).

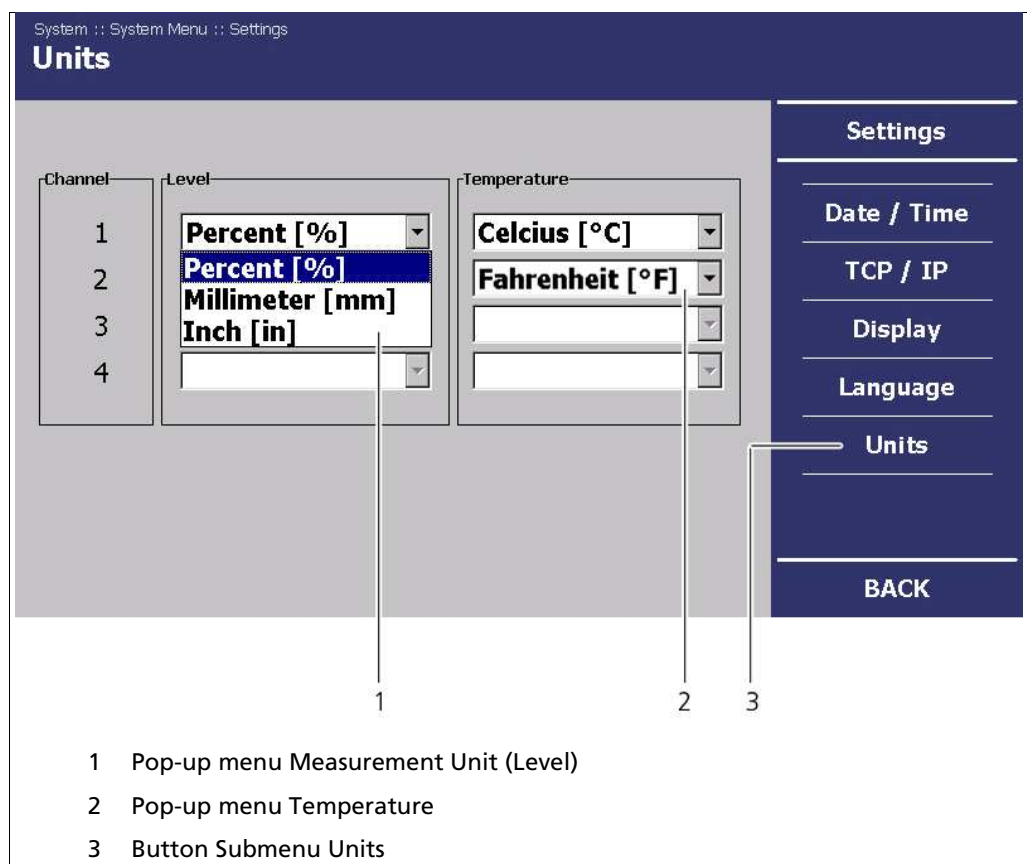


Fig. 32 System Menu, Settings - Units



Note

The assignment of unit length (mm or in) is mandatory, depending on whether the measurement is desired in mm or inches.

## 6.3 Data Log

In the **System Menu**, click on <Data Log> (Fig. 20, Pos. 5).

### 6.3.1 Graph

In the Graph submenu, the interval used for visualising the log data in the channel overview is set.

1. In the **System Menu | Data Log**, click on **Graph** (Fig. 33, Pos. 3).

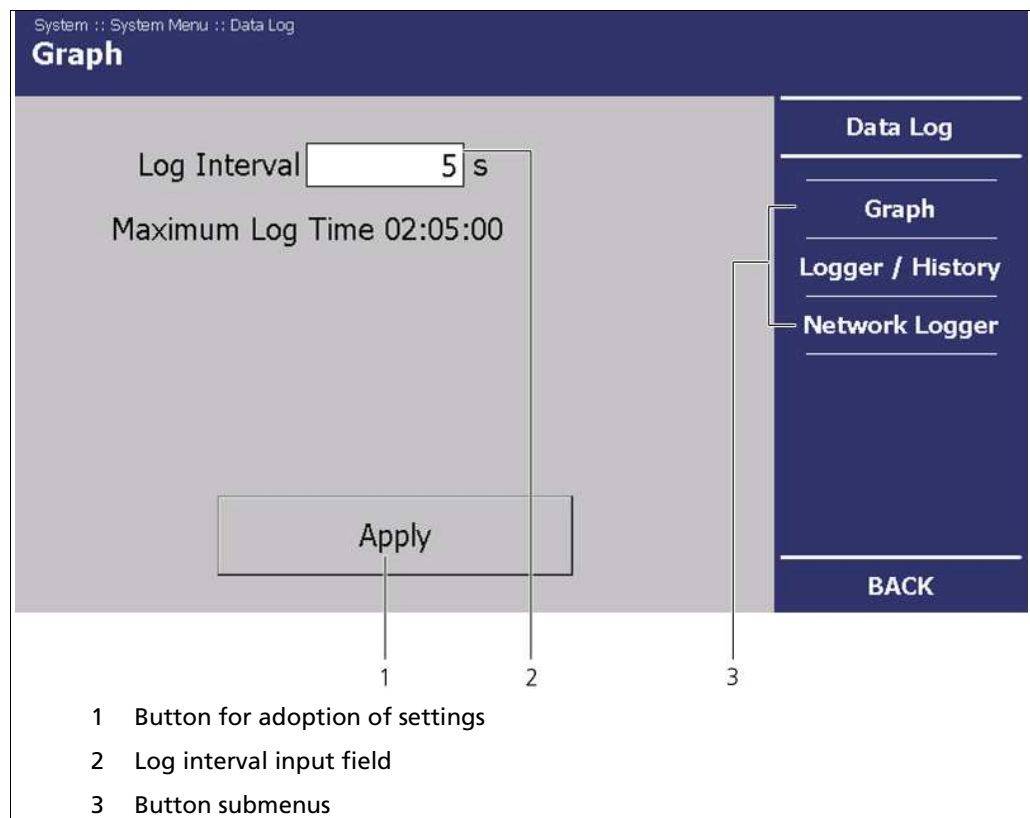


Fig. 33 System Menu. Settings - Data Log (Graph)



## Graph (Continued)



Note

In the "log interval" input field, set the interval in which the log data is to be saved (Fig. 33, Pos. 2).

The smallest log interval which can be set is 0.5 s.

2. Click on the input field to set the log interval (Fig. 33, Pos. 2).
  - ⇒ The numeric keypad opens (Fig. 18).
3. Set the desired log interval.
4. Click on the **<Apply>** button (Fig. 33, Pos. 1) to adopt the setting.
  - ⇒ A confirmation message is displayed.
5. Click on **<OK>** to restart the EVU.
  - ⇒ The EVU restarts.

### 6.3.2

## Data Logger



Note

The Data Logger submenu only appears if an SD card has been installed in the control unit.

To install the SD card, see chapt. 4.5.

In the Data Logger submenu, you have the option of setting the log and to export or delete the measurement values (log data).

In the "Data Logger" submenu, it is possible to save the log data on an SD Card.

The data logger records the following measured values:

- Date and time
- Fill level (mould level)
- Count rate
- Temperature of the GAMMAcast detector(s)
- Active calibration curve
- System status



Note

The data log is saved in the main directory of the SD card in the form of a .txt file.

If the tick (Fig. 34, Pos. 1) is not set at "active", no log data is saved on the SD card.

## Data Logger (Continued)

- In the **System Menu**, click on **Data Log | Data Logger** (Fig. 33, Pos. 3) to reach the Data Logger submenu.

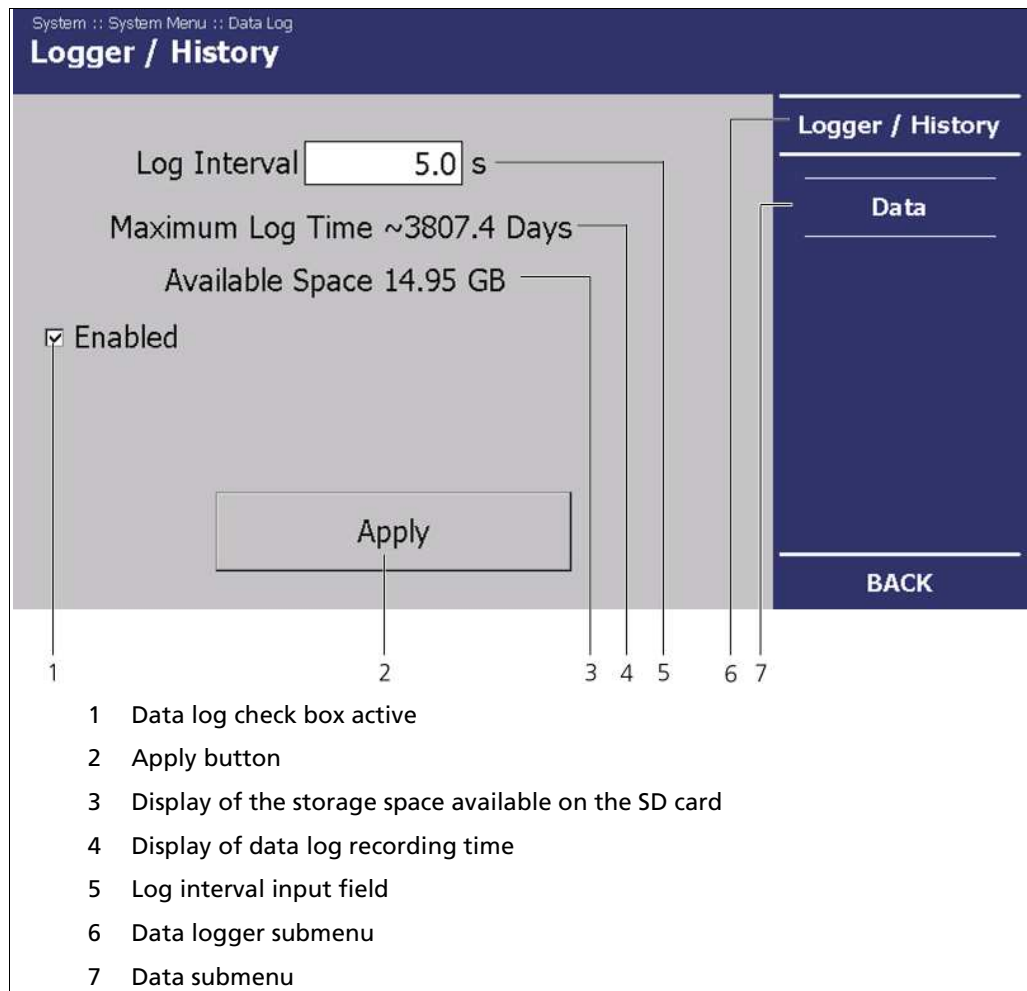


Fig. 34 System Menu, Data log - Data Logger

- Activate the data log saving by putting a tick in the "Active" check box (Fig. 34, Pos. 1).
- Click on **<Apply>** to initiate the data log saving (Fig. 34, Pos. 2).  
⇒ The data log is now activated and records the data on the SD card.

## Data Logger (Continued)

<b>Log Interval</b>	Shows the log data saving interval (Fig. 34, Pos. 5)
<b>Maximum Log Time</b>	Shows the maximum log data saving interval depending on the set log interval and the SD card storage capacity (Fig. 34, Pos. 4).
<b>Available Space</b>	Shows the free storage capacity of the SD card (Fig. 34, Pos. 3).

### 6.3.2.1 Exporting measurements

In the **System menu | Data log | Data logger**, click on **<Measurements>** (Fig. 35, Pos. 7), to export the log data to the SD card or to delete it from the SD card.

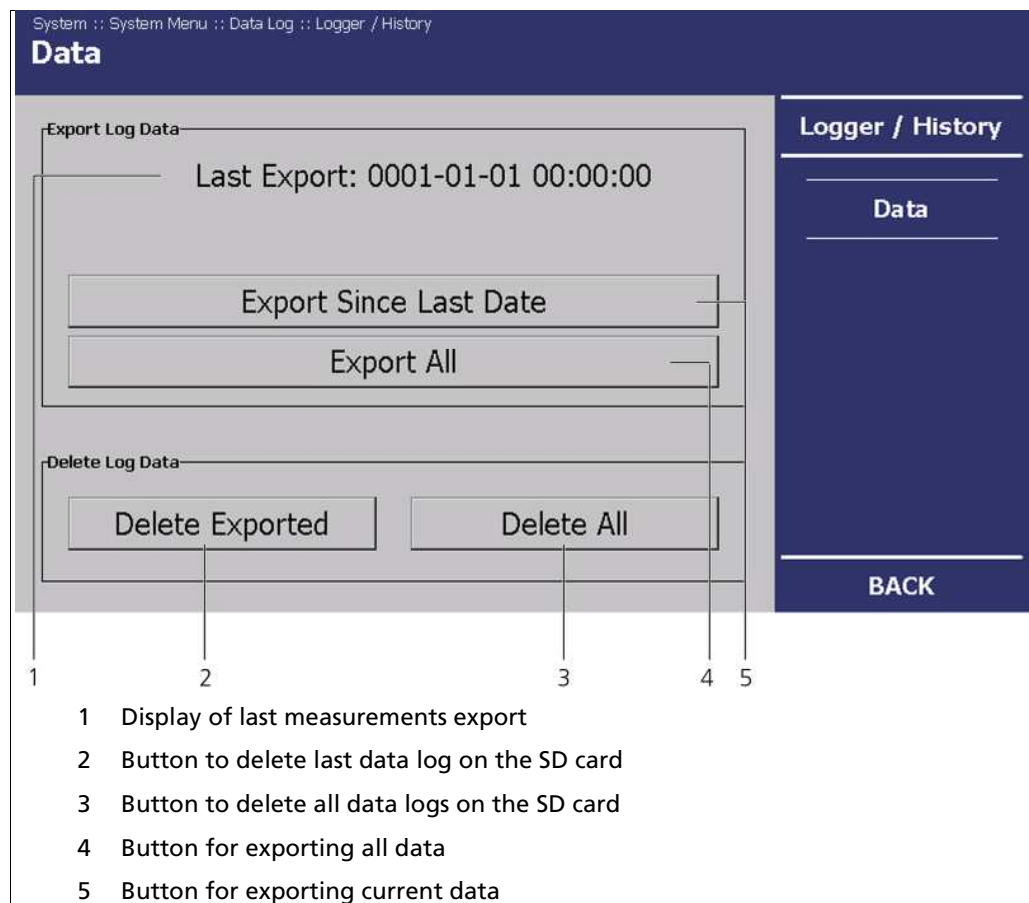


Fig. 35 System menu, Data log – Data logger (Measurements)

## Exporting Measurements (Continued)

In the "Measurements" submenu you can adjust the following settings:

<b>Last export</b>	Displays the date and time of the last export (Fig. 35, Pos. 1).
<b>Export from last time onwards</b>	Export of the current data log (Fig. 35, Pos. 5).
<b>Export all</b>	Exports the entire data log (Fig. 35, Pos. 4).
<b>Delete export</b>	Deletes the data log last exported on the SD card (Fig. 35, Pos. 2).
<b>Delete all data</b>	Exports all data logs onto the SD card (Fig. 35, Pos. 3).

### 6.3.3 Network Logger

In the System menu, click on **Data log | Network logger** (Fig. 33, Pos. 3).

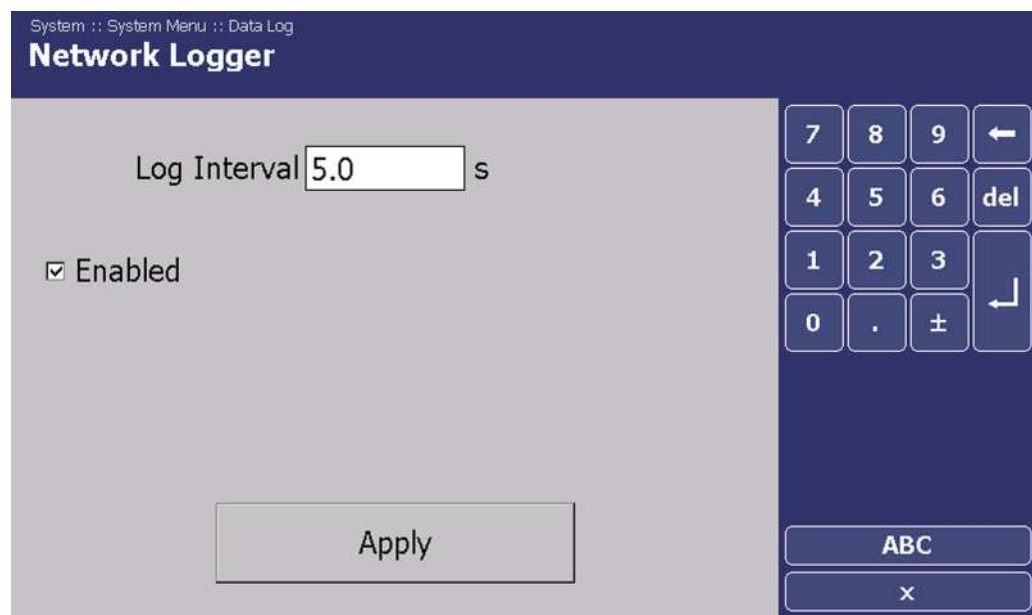


Fig. 36 System Menu, Data Log – Network Logger

## Network Logger (Continued)

In the "Network Logger" submenu, you can transmit log data to a computer.



Note

The fill level signal transmitted via the Ethernet is intended only for quality assurance purposes. Process regulation is not possible with this signal.

1. Set the desired log interval.
2. Activate the transmission of data via Ethernet, by placing a check mark in the selection box "Active".
3. Click on the **<Apply>** button to send the data via Ethernet.  
⇒ The data can be received on the network computer.



Note

The computer must be on the same network as the EVU.



Note

If the data are to be read out directly via TCP/IP, please contact the manufacturer.

### 6.3.3.1 Use of the Software "Data Log Viewer"

With the separately delivered software "Data Log Viewer" from BERTHOLD TECHNOLOGIES, the visualisation and saving of the log data on a computer is possible.

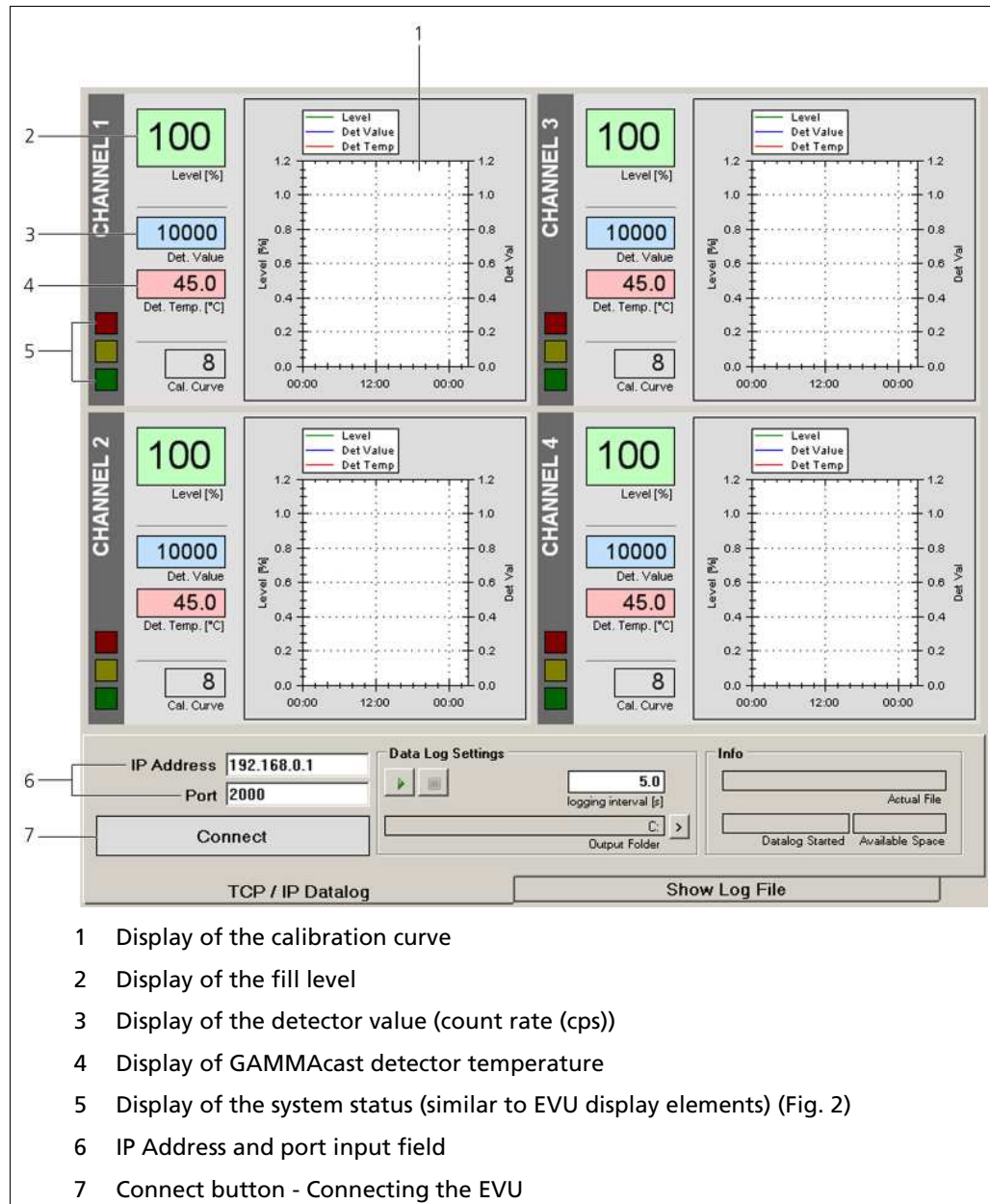


Fig. 37 Start Page, Data Log Viewer Software

### 6.3.3.2 Establishing Connection and Saving Data Log

The screenshot displays the 'CHANNEL 1' data log viewer interface. On the left, there are four data points: Level [%] at 100, Det. Value at 65, Det. Temp. [°C] at 31.5, and Cal. Curve at 0. A central graph plots Level [%] (green line), Det Value (blue line), and Det Temp (red line) over time from 16:08 to 16:18. The bottom section contains 'Data Log Settings' with fields for IP Address (192.168.34.159), Port (2000), logging interval (5.0 s), and Output Folder (C:). An 'Info' section shows 'Actual File', 'Datalog Started', and 'Available Space' (30.99 GB). A 'Disconnect' button and a checked 'TCP / IP Datalog' option are also present. Eight numbered callouts (1-8) point to specific UI elements: 1 (start recording), 2 (stop recording), 3 (storage location), 4 (select storage), 5 (log interval), 6 (last save time), 7 (available space), and 8 (data log file name).

- 1 Button for starting data log recording
- 2 Button for stopping data log recording
- 3 Display of log data storage location
- 4 Button for selecting storage location
- 5 Display of the log interval
- 6 Display of the time of the last save
- 7 Display of the storage space available on the hard drive
- 8 Display of the data log file name

Fig. 38 Start Page, Data Log Viewer Software (dial-up)

## Establishing Connection and Saving Data Log (Continued)

1. Enter the EVU IP address in the input field (Fig. 37, Pos. 6).
2. Click on **<Connect>** to establish a connection (Fig. 37, Pos. 7).
3. Click on the **<Select Saving Location>** (Fig. 38, Pos. 4) to specify a storage location.
4. Click on the **<Start Data Log Recording>** button (Fig. 38, Pos. 1) to record the data log.  
⇒ The data log starts.



Note

In order to be able to use the data log viewer, the tick in the check box in the "Network Logger" submenu (chapt. 6.3.3) must be set to "active". Otherwise, the visualisation and saving of the measurement data is not possible.



Note

The Data Log Viewer software is not suitable for parameterising the device. The use of this software is intended for quality assurance purposes. Process regulation is not possible with this signal.

---



## 6.4 Service Submenu

In the Service Submenu you can adjust the following settings and read information:

- Downloading of the **Remote Control Software (RC Software)**
- Carrying out of Updates for:
  - the control unit
  - the measurement of channels
  - the detectors
- Exporting the **complete service data**

In the **System menu**, click on **<Service>** (Fig. 20, Pos. 1), to reach the **<Service>** submenu.

⇒ The Service submenu opens.

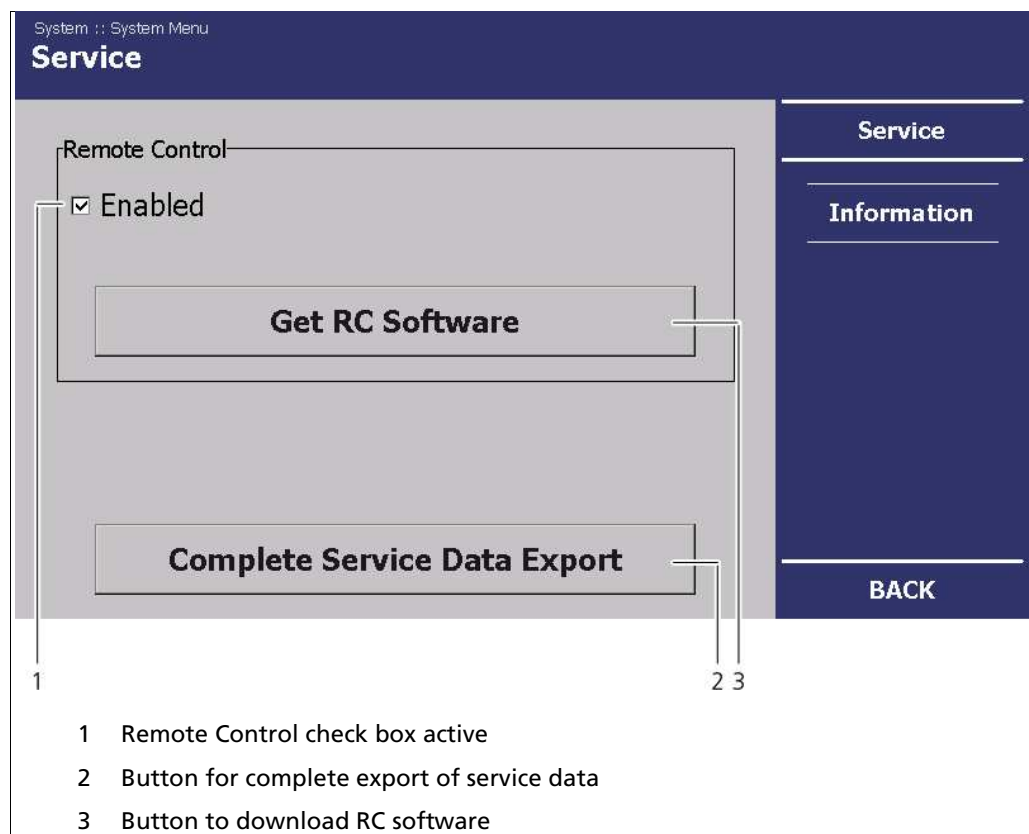


Fig. 39 System Menu, Service

## Service Submenu (Continued)

1. Stick the USB stick into the USB port of the front panel (Fig.1, Pos. 1).  
⇒ The two buttons appear with black lettering and are active.

### 6.4.1 Remote Control Software



The check mark must be set to "Active" in order for the Remote Control to function (Fig. 39, Pos. 1).

Note

1. Click on "Download RC Software" in order to download the RC software from the EVU to the USB stick (Fig. 39, Pos. 3).  
⇒ The file **LB452RemoteControl.exe** is downloaded from the EVU and saved in the main directory of the USB stick.
2. Take the USB stick from the USB port and stick the USB stick into a USB port of the computer on which you would like to install the RC software.
3. Summon the main directory of the connected USB flash drive.
4. Click on "**LB452RemoteControl.exe**" to start the program.

⇒ The program starts (Fig. 40).

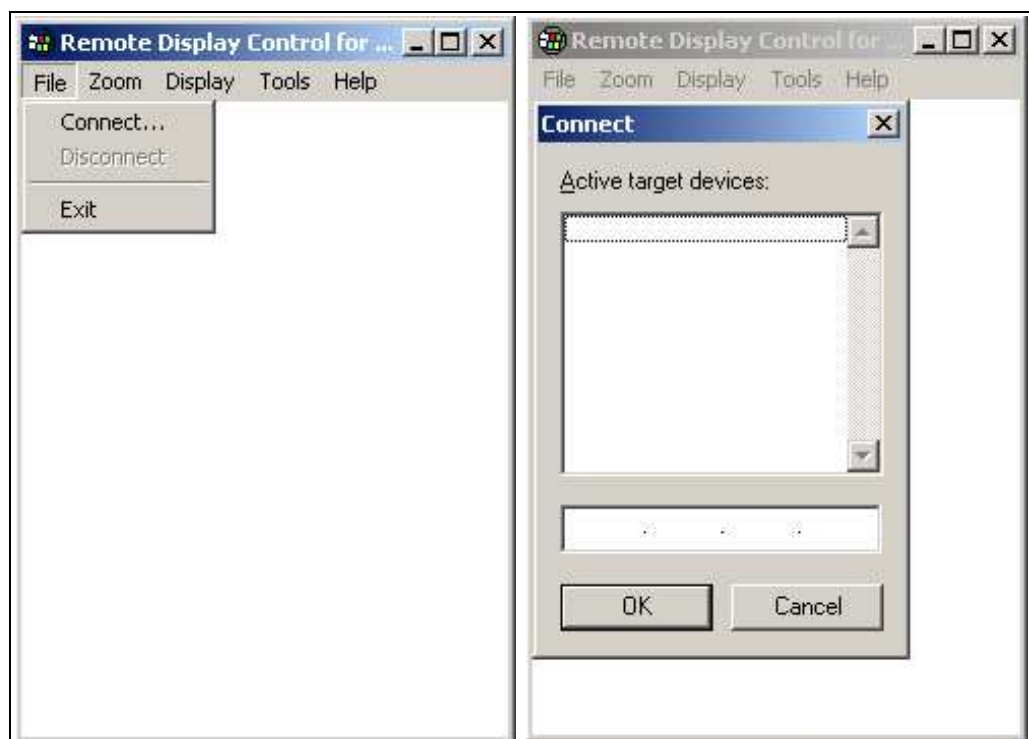


Fig. 40 Establish connection to the EVU using the RC software

## Remote Control Software (Continued)

5. Click on the <File> tab then on <Connect...> to establish a connection to the EVU.  
⇒ A new window "Connect" opens (Fig. 40).
6. Enter the EVU IP address into the input field. You can find out where you can read the IP address in chapt. 6.2.2.
7. Click on <OK>.  
⇒ The connection to the EVU is established.

### 6.4.2 Export Complete Service Data

1. Click on "Complete Service Data Export" to load the service data on the USB stick (Fig. 39, Pos. 2).  
⇒ The service data of all installed measurement channels and connected detectors are downloaded from the EVU and saved in the main directory of the USB stick.

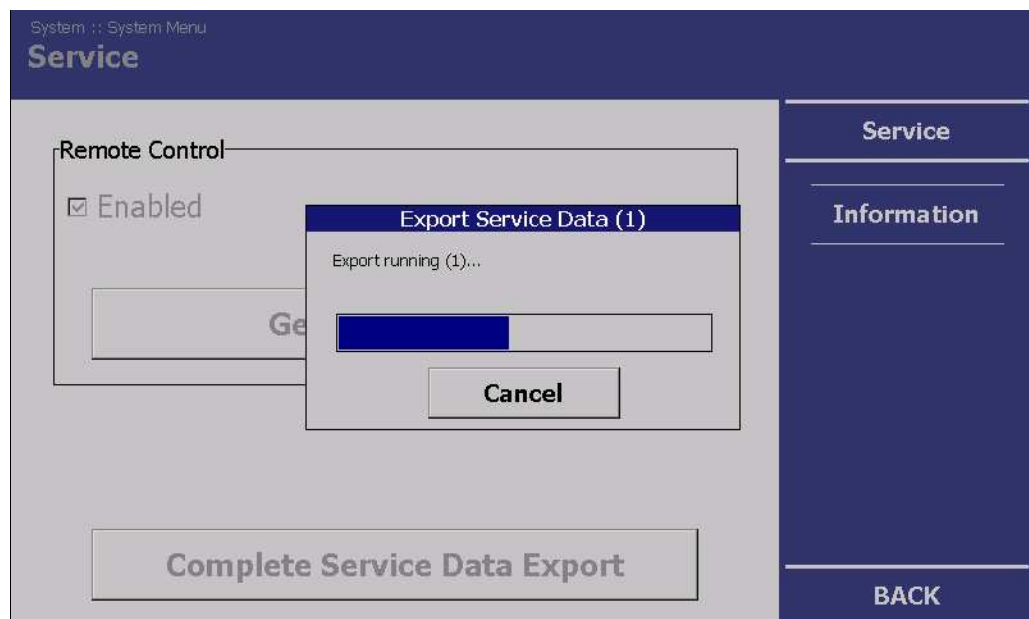


Fig. 41 System Menu, Service - Export of the service data

### 6.4.3 Software update

In the "Information" submenu, information about the installed modules and the software installed on them is given. All updates are carried out via this page.



Note

#### Data loss during the measurement!

The measurement is interrupted during a software update.

- Only carry out software updates when the measurement is not currently being used for process control.



Note

#### Malfunction!

##### Devices are not recognised!

The software versions of the LB 452 control unit, the LB 452 measurement channels (measurement unit) and the GAMMAcast detectors must be compatible with one another; otherwise the components will not be recognised by the system.

- Please adhere to the prescribed sequence of the updates:
  1. LB 452 Control Unit (EVU)
  2. LB 452 Measurement Channels
  3. GAMMAcast Detectors
- Control unit (CU) and measurement channels (MU) must have the same software version.



Note

#### Malfunction!

Before software which has a version number greater than 1.0.2 can be installed on the EVU, the software version 1.0.2 must be installed.



Note

#### Settings are deleted!

If the first or second figure of the version of an update changes (e.g. from version 1.0.1 to version 1.1.0), the settings are lost.

- Before the update, carry out a back-up of the measurement channel settings (chapt. 6.4.2, Fig. 41) and then import the backed-up settings after a successful software update.



Note

The update files must be located in the main directory of the USB flash drive.

The following information is also visible:

<b>Software version</b>	The software version and publication date of the update.
<b>UID</b>	Serial number of the measurement channels and the GAMMAcast detector(s)

### 6.4.3.1 Software Update Control Unit



Update files for the control unit begin with **LB452CU** and end with **.btw**.

Note

1. Connect the USB flash drive with files to be installed to the USB port of the front panel (Fig.1, Pos. 3).
2. In the **System menu** click on **Service | Information**. (Fig. 42, Pos. 4)

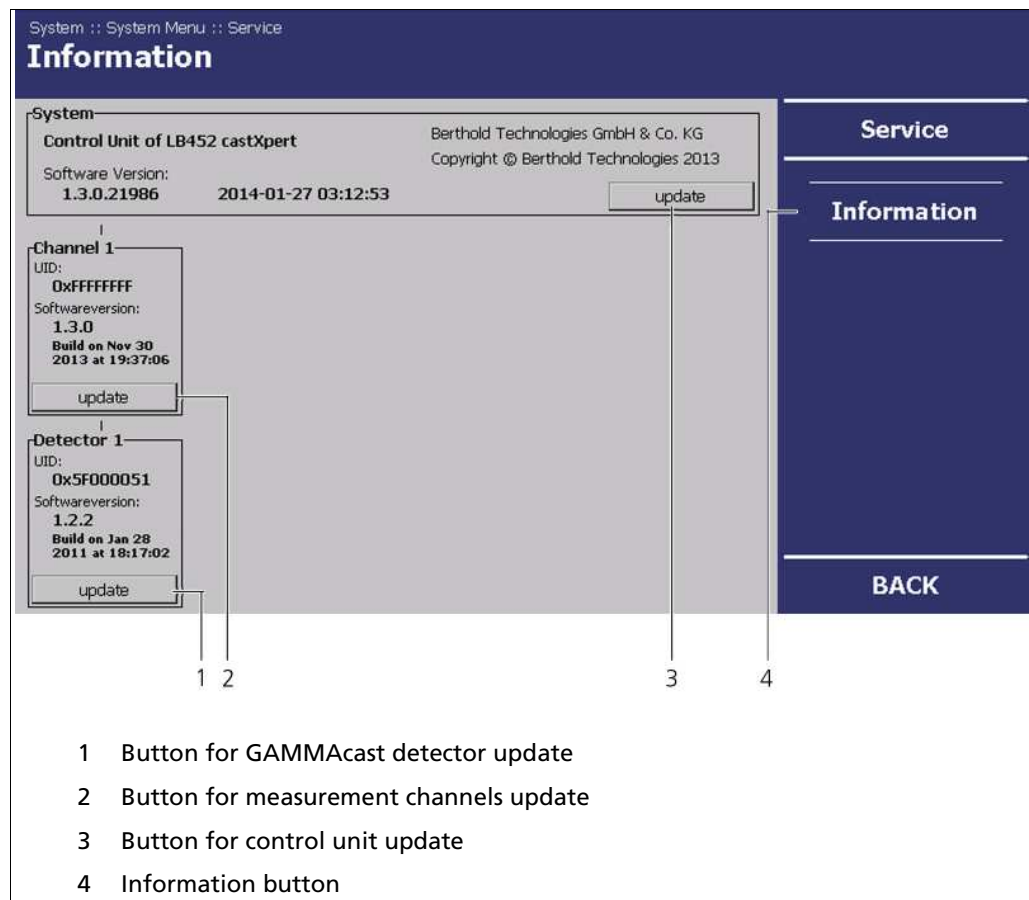


Fig. 42 System menu, Service – Information

3. Click on **<update>** (Fig. 42, Pos. 3), to carry out a control unit update.  
⇒ Update files are displayed on the USB stick.

## Software Update Control Unit (Continued)

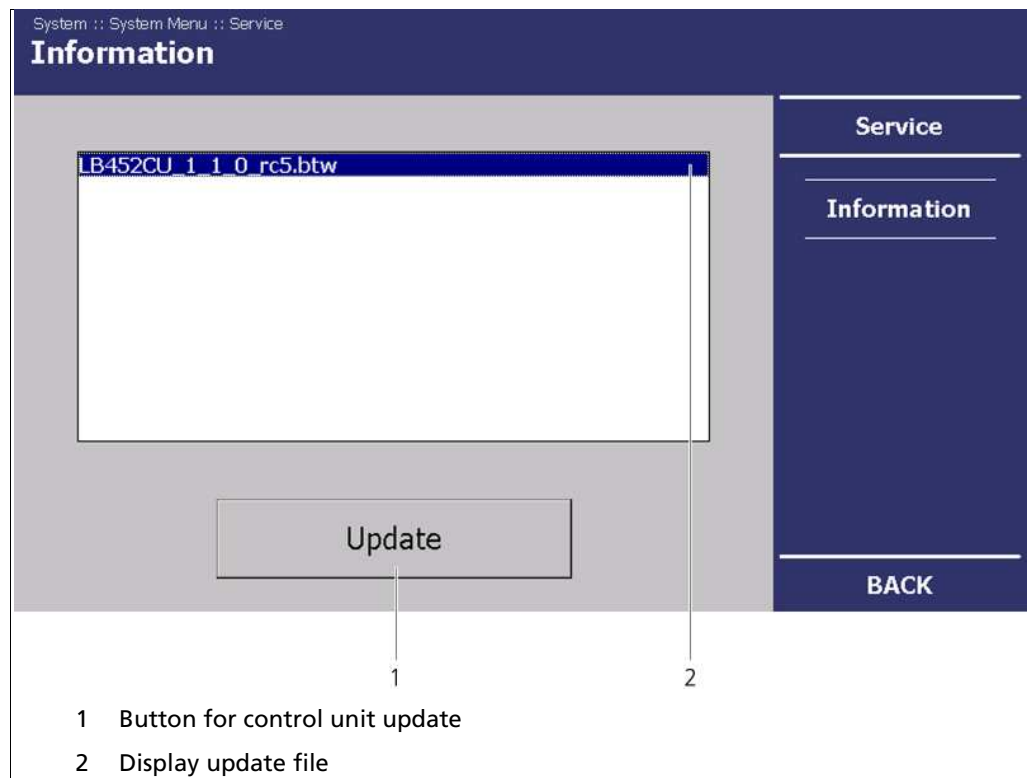


Fig. 43 System Menu, Service - Information (Control unit update)

4. Select the appropriate update file (Fig. 43, Pos. 2).
5. Click on <Update> (Fig. 43, Pos. 1).  
⇒ A confirmation message opens.
6. Click on <OK> in the confirmation message.  
⇒ The software update is carried out.  
⇒ The EVU is then restarted.

### 6.4.3.2 Measurement Channels Software Update



Update files for the measurement channels start with **LB452MU** and end with **.bta**.

Note

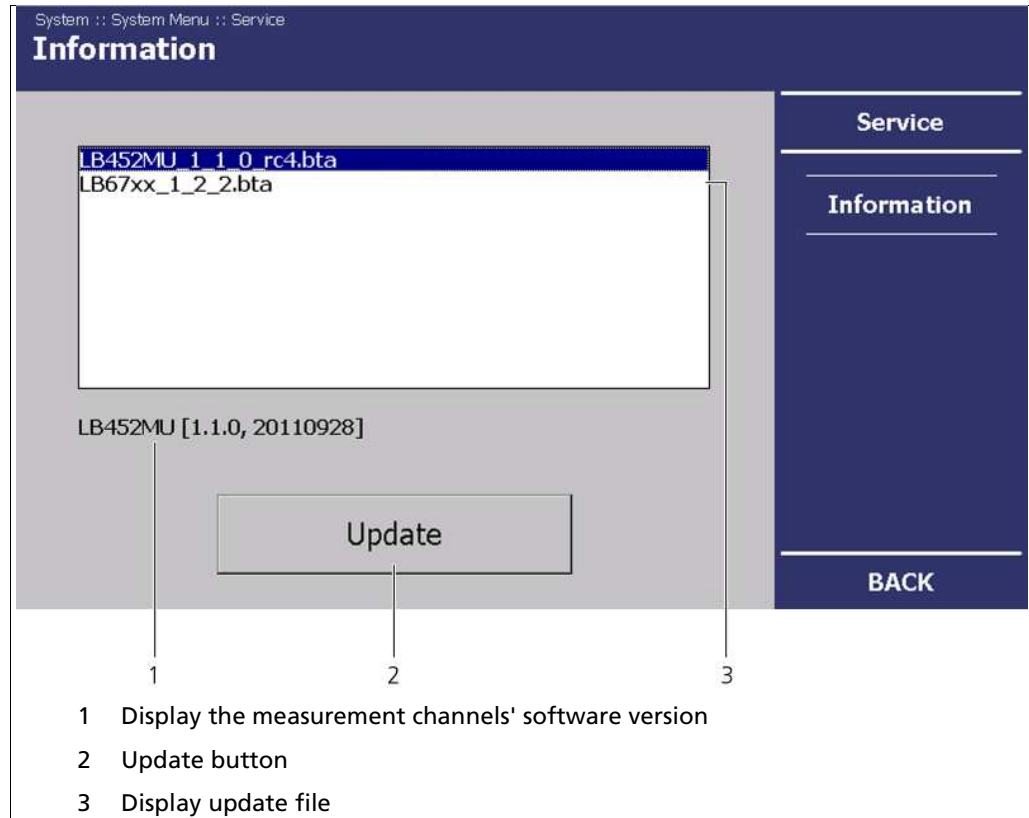


Fig. 44 System Menu, Service - Information (Measurement channels update)

1. In the **System menu** click on **Service | Information** (Fig. 42, Pos. 4).
2. Click on **<Update>** (Fig. 42, Pos. 2), to carry out a measurement update.
  - ⇒ Update files are displayed on the USB flash drive.
3. Select the appropriate update file (Fig. 44, Pos. 3).
4. Click on **<Update>** (Fig. 44, Pos. 2).
  - ⇒ A confirmation message opens.
5. Click on **<OK>** in the confirmation message.

## Software Update Measurement Channels (Continued)

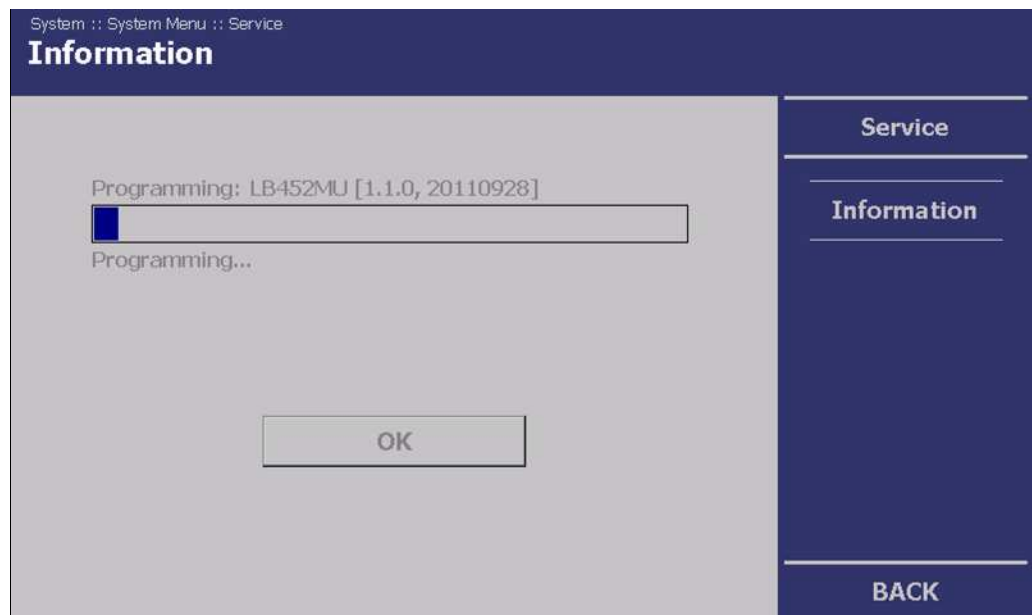


Fig. 45 System Menu, Service - Information (Measurement channels update)

- ⇒ The software update is carried out.
  - ⇒ After a successful update, the message "Programming finished" appears.
6. Click on <OK> to finish the update process.
- ⇒ The measuring channel then restarts afterwards.



Note

During an update where the first or second digit of the version changes, it is necessary to reset the measurement channel to factory settings (chapt.6.1).



### 6.4.3.3 GAMMAcast Detectors Software Update



Update files for the GAMMAcast detectors start with **LB67XX** and end with **.bta**.

Note

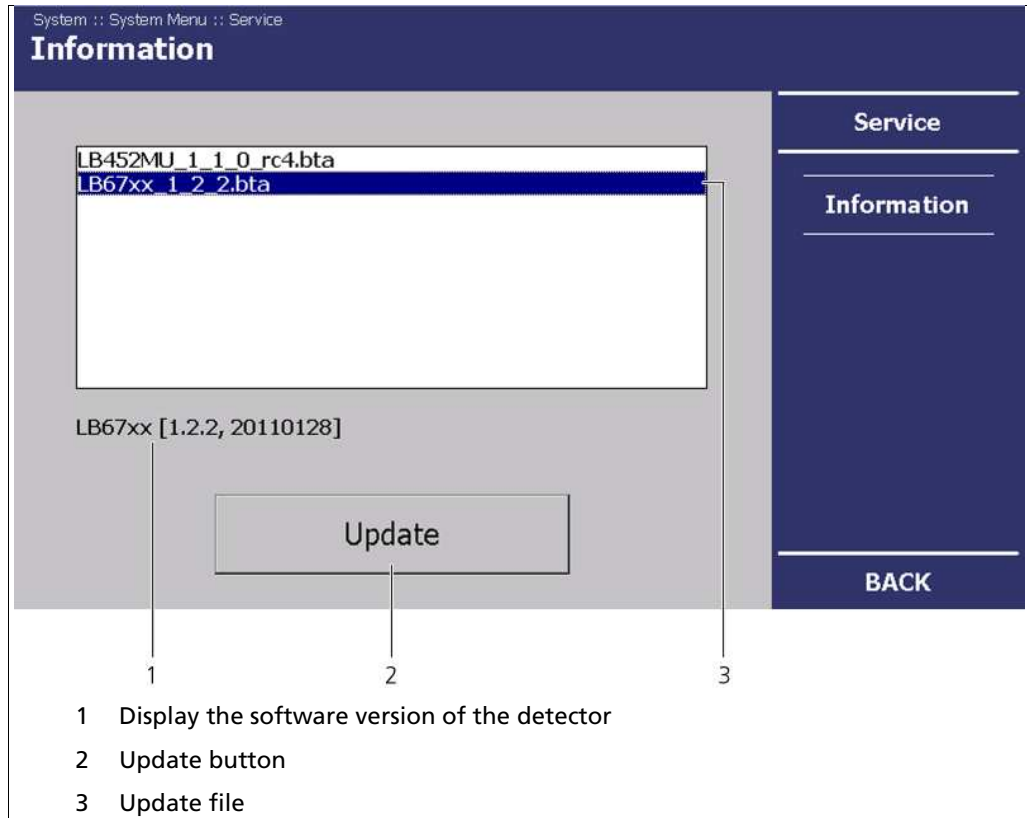


Fig. 46 System Menu, Service - Information (GAMMAcast detector update)

1. Click on **Service | Information** (Fig. 42, Pos. 4).
2. Click on **<Update>** (Fig. 42, Pos. 1), to carry out the GAMMAcast detector update.  
⇒ The update files of the USB stick are displayed.
3. Select the appropriate update file (Fig. 46, Pos. 3).

## Software Update GAMMAcast Detectors (Continued)

4. Click on <Update>.
  - ⇒ A confirmation message opens.
5. Click on <OK>in the confirmation message.
  - ⇒ The software update is carried out (Fig. 45).
  - ⇒ After a successful update, the message "Programming finished" appears.
6. Click on <OK>to finish the update process.



Note

If the first or second figure of the version of an update changes, the detector must be reset to its factory settings (see manual "48452BA1", chapt. 6.3.5).

## 6.5 Access Level

In the Access Level submenu, you can set the user rights via the user levels and assign passwords. The system can be protected by a password against unauthorised changes. Password entry takes place via the <Access Levels>submenu.

The following user levels are available to you:

<b>User Level Basic</b>	You can see all important data but cannot make any changes.
<b>User Level Standard</b>	You can change all data necessary for operation (e.g. filter, calibration).
<b>User Level Admin</b>	This user level is only intended for system administrators of the company BERTHOLD TECHNOLOGIES.
<b>Automatic log out</b>	The access level Standard is automatically reset to Basic if the system jumps back to the start screen or the display switches off (see times in the menu "System menu   Settings   Display" chapt.6.2).

## Access Level (Continued)



Attention

### Damage to the device!

### Damage due to incorrect operation!

Incorrect measurement and calibration parameters can be set through unauthorised inputs. These can possibly lead to production losses and damage in the system.

- Protect the measurement system against unauthorised inputs with a password.

1. In the **System Menu**, click on **<Access Level>** (Fig. 20, Pos. 5).

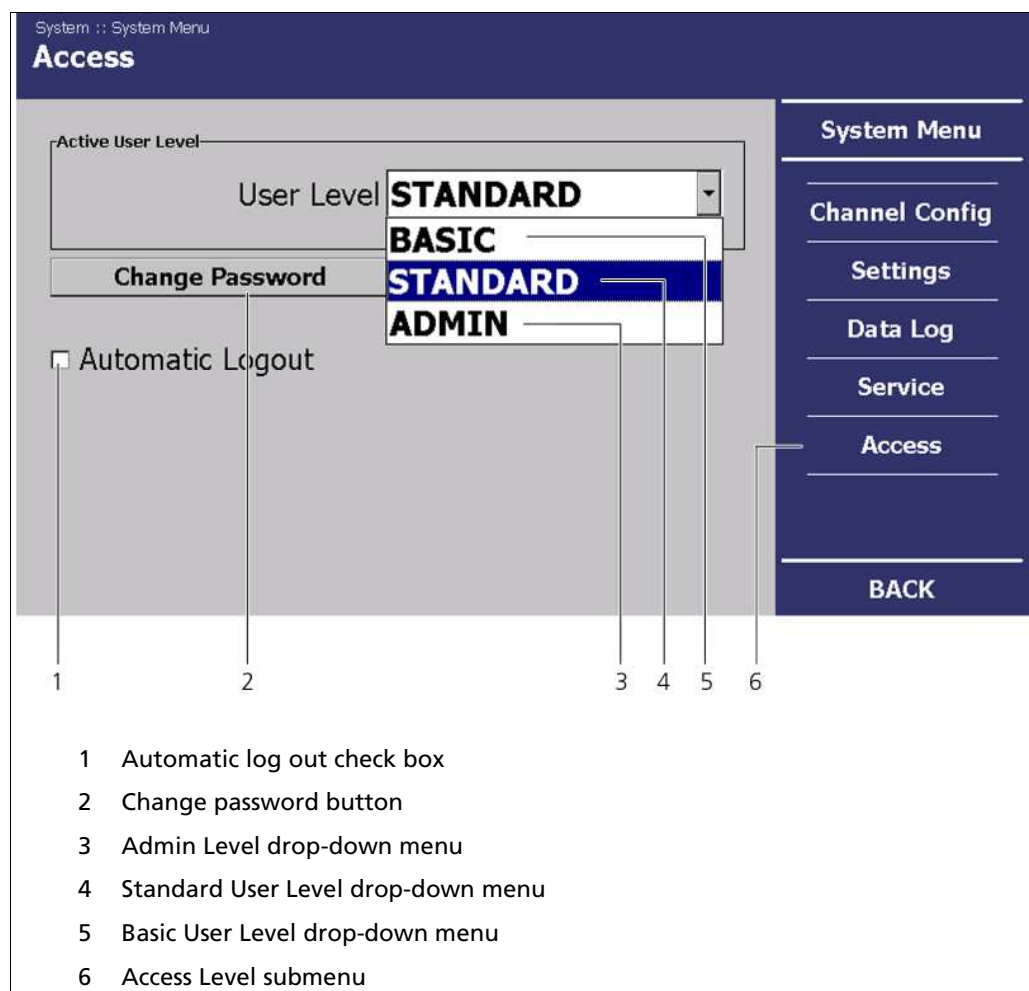


Fig. 47 System Menu, Access Level

2. Select **Standard** in the drop-down menu of the "User Level" field (Fig. 47, Pos. 5).
3. Click on **<Change Password>** (Fig. 47, Pos. 2).

**Access Level** (Continued)

4. Click in the "Password" input field to create a password or to change it.  
⇒ The keypad opens.
5. Enter a password and confirm your entry with ENTER.  
(Fig. 18, Pos. 4).
6. Click on <OK> to finish the password entry.

# 7 "Channel Overview" Menu

In the channel overview, you can set values relating to the measurement task.  
 In Fig. 48, the menu structure of the "Channel Overview" menu is represented.

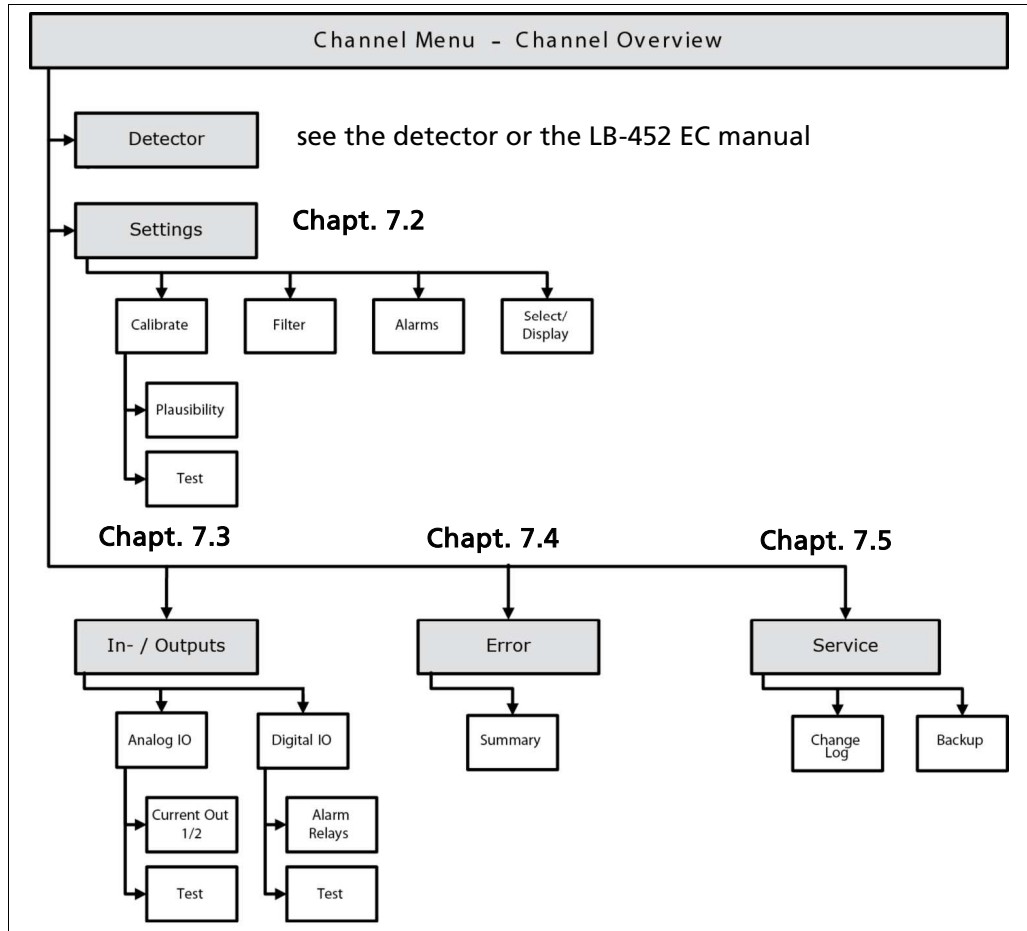


Fig. 48 "Channel Overview" menu structure

"Channel Overview" Menu (Continued)

Click on <Channel XY> in the standard display (Fig. 16, Pos. 1) to reach the "Channel Overview" menu.

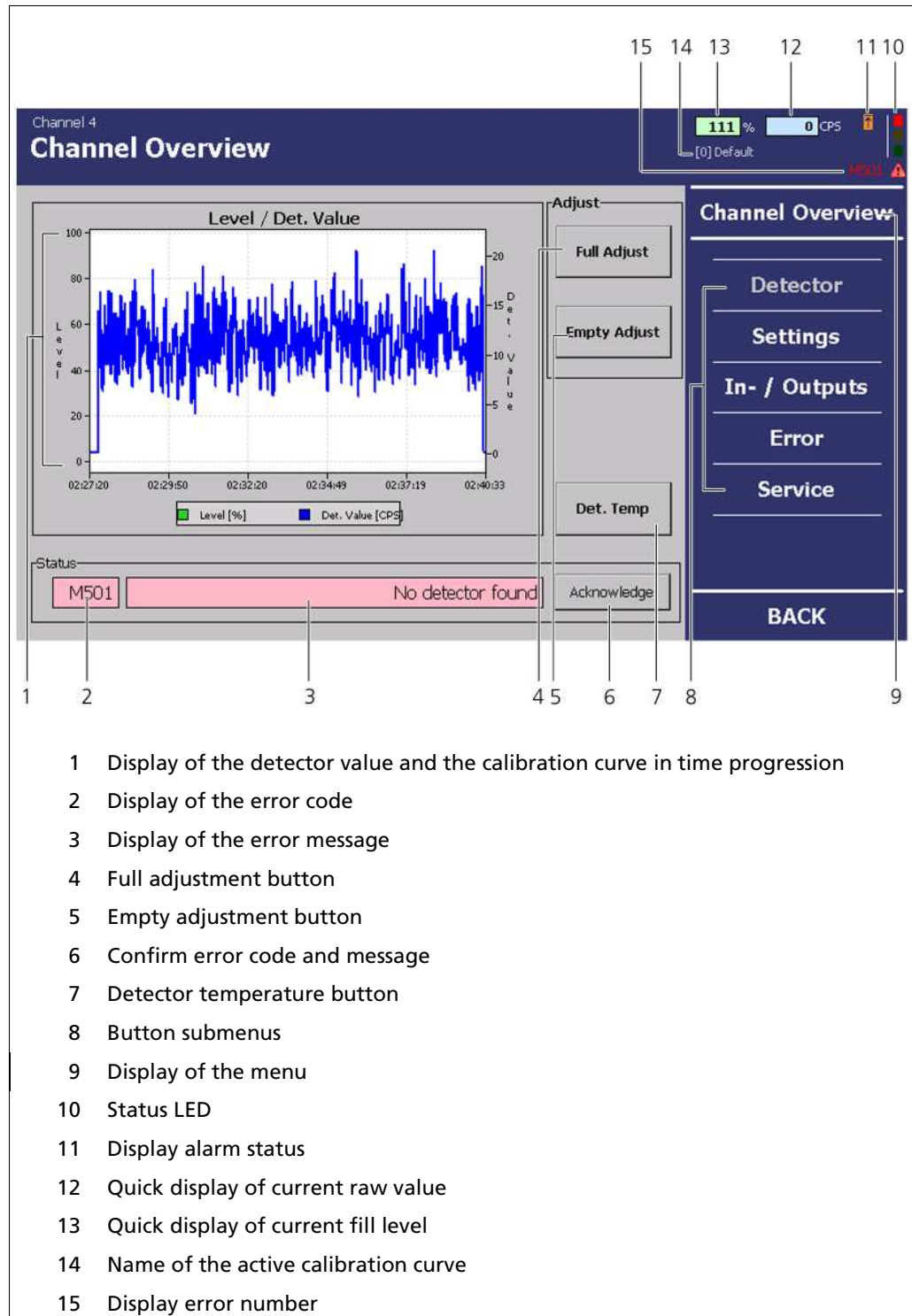


Fig. 49 Menu "Channel Overview"

## "Channel Overview" Menu (Continued)

### "System Status" Display Field:





The "System Status" display field shows you the current status of the EVU. All castXpert LB 452 errors have the prefix "M", all GAMMAcast LB67xx errors the prefix "D". The error code (Fig. 49, Pos 2) and error text (Fig. 49. Pos. 3) are displayed here. For troubleshooting, see chap. 8:

- Display field highlighted in red = an error has occurred
- Display field highlighted in yellow = a warning has occurred
- Display field highlighted in green = no error (Fig. 49, Pos. 3)

### Fill Level/Detector Value or Fill Level/Detector Temperature

The measured count rate (detector value - IPS) and the fill level are represented in the graph. By pressing the <Det.-Temp.> button (Fig. 49, Pos. 7), the detector temperature is displayed as opposed to the count rate.

### Display Field "Alarm Status"

- |                    |   |   |
|--------------------|---|---|
| <b>Start-up</b>    |    | Indicates that the start-up time constant is used (see chapt. 7.2.2).   |
| <b>Max. Alarm</b>  |  | Indicates that a max. fill level alarm is applied (see chapt. 7.2.3).   |
| <b>Min. Alarm</b>  |  | Indicates that a min. fill level alarm is applied (see chapt. 7.2.3).   |
| <b>Temperature</b> |  | Indicates that a temperature alarm is applied when the set alarm threshold in the <b>Menu Detector   Temperature</b> is exceeded (see detector manual). |

## "Channel Overview" Menu (Continued)

### Troubleshooting

The error number (or warning) is displayed on each side of the channel menu above right under the status indicator (red/orange) is displayed.

If you click on the error number, a pop-up message appears. Here you can confirm/acknowledge the error.

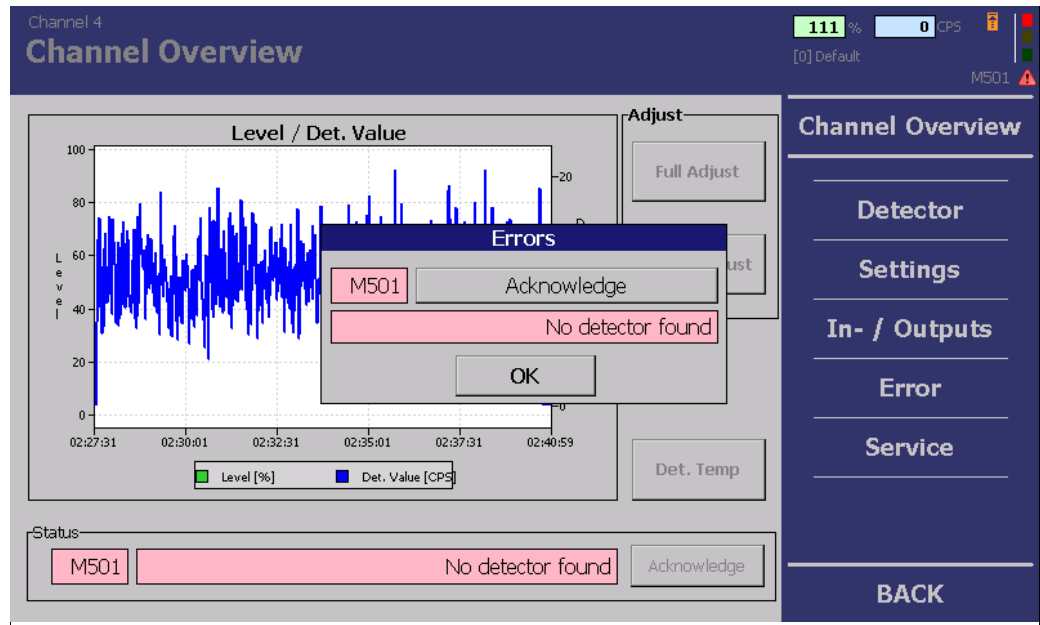


Fig. 50 Error display

The "Channel Overview" menu offers the following setting options:

<b>Detector</b>	Settings for the detector (see detector manual)
<b>Settings</b>	General measurement-related settings
<b>In/Outputs</b>	Settings for the analogue and digital power outputs
<b>Error</b>	View and confirm error codes and error messages
<b>Service</b>	Export of service data and reset of the settings



## 7.1 Empty and full adjustment

The measuring system must be adapted to the specific environmental conditions before the start of casting. This is done via an empty and full adjustment. Follow this sequence before the start of every casting:

- Empty adjustment (always necessary)
- Full adjustment with cold block (recommended)



Note

BERTHOLD TECHNOLOGIES recommends that the adjustment mode be set to **"dynamic"** (Fig. 55, Pos. 5) if only an empty adjustment is carried out before casting.

If both an empty and a full adjustment are carried out, the recommended mode is **"fixed"**.

For the full calibration, a metal mould filled with liquid metal must be simulated. This is done by inserting a cold block into the mould, made from steel for example.

To avoid measurement errors, the cold block must fill the beam path exactly (as would be the case with liquid metal). If the cold block is inserted in such a way that it does not cover the entire beam path, radiation which was not weakened by the steel can sometimes reach the GAMMAcast detector through the gap. This will cause a too high count rate to be measured for the 100% point. In this case, too high a steel level will be displayed during casting.

For the empty adjustment, the recommended count rate from the detector is measured when the mould is empty.

1. Click on the button **<Channel XY>** in the standard display (Fig. 51, Pos. 1) to reach the "Channel Overview" menu.  
⇒ The "Channel Overview" menu (Fig. 52) opens.

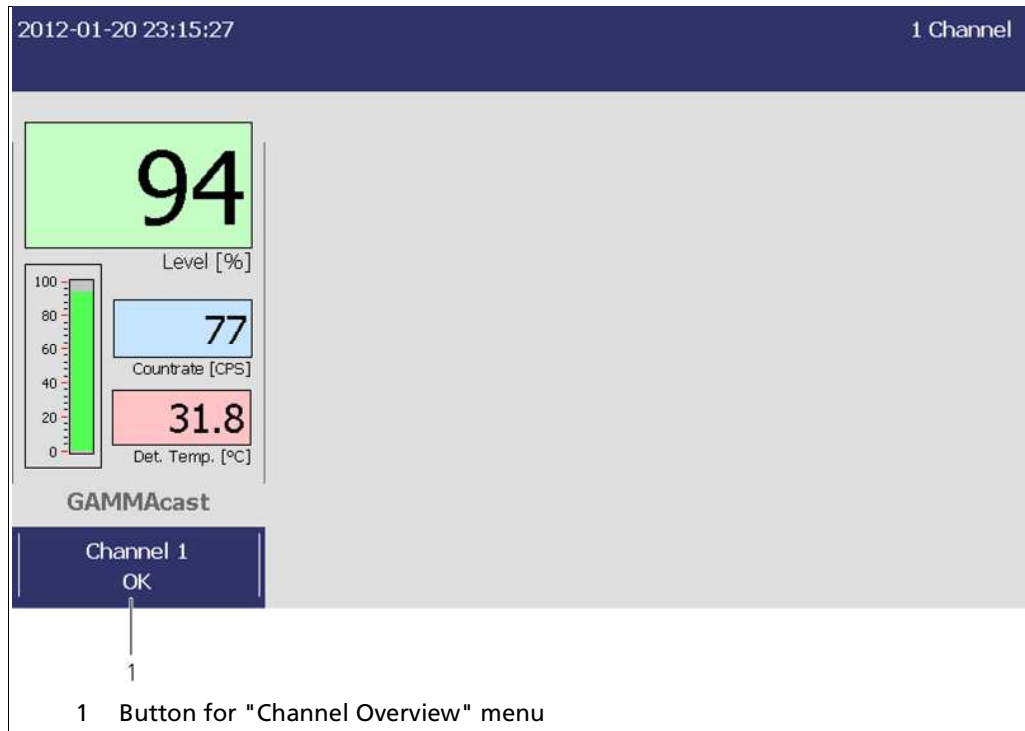


Fig. 51 Start page with a channel

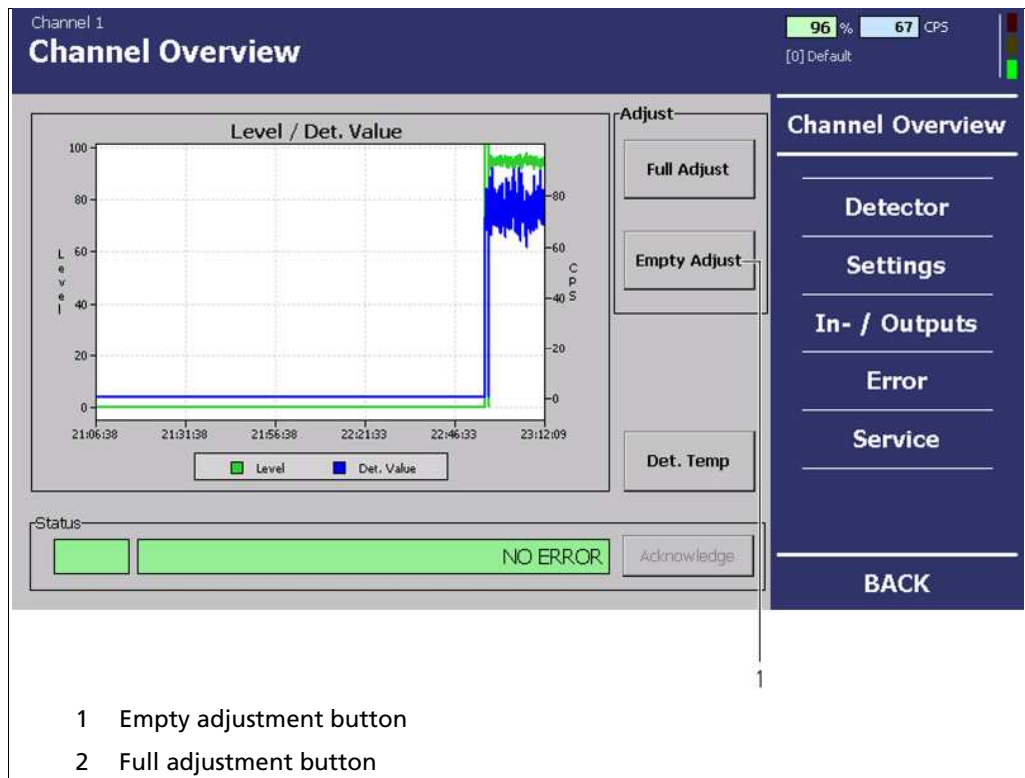


Fig. 52 Menu "Channel Overview", Adjust

## Empty and Full Adjustment (Continued)

1. Click on <Empty Adjustment> to carry out an empty adjustment (reading in the 0% value) (Fig. 52, Pos. 1). Alternatively, you can close digital input 1. In this case, no confirmation message opens and the empty adjustment can be started directly from the casting platform.
2. If a full adjustment (100% value) is carried out, click on <Full Adjustment> (Fig. 52, Pos. 2). Alternatively, you can close digital input 2. In this case, no confirmation message opens and the empty adjustment can be started directly from the casting platform.
3. Click on <OK> in the confirmation message.
  - ⇒ The current count rate is read in (Fig. 53, Pos. 2). The duration of the full adjustment depends on the settings applied in the menu **Settings | Calibration | Plausibility**. Further information on the settings can be found in chapt. 7.2.1.3 in the "Plausibility" submenu. You can cancel the full adjustment and the reading of values by clicking on the <Cancel> button (Fig. 53 Pos. 3). **Manual cancelling is not recommended.**

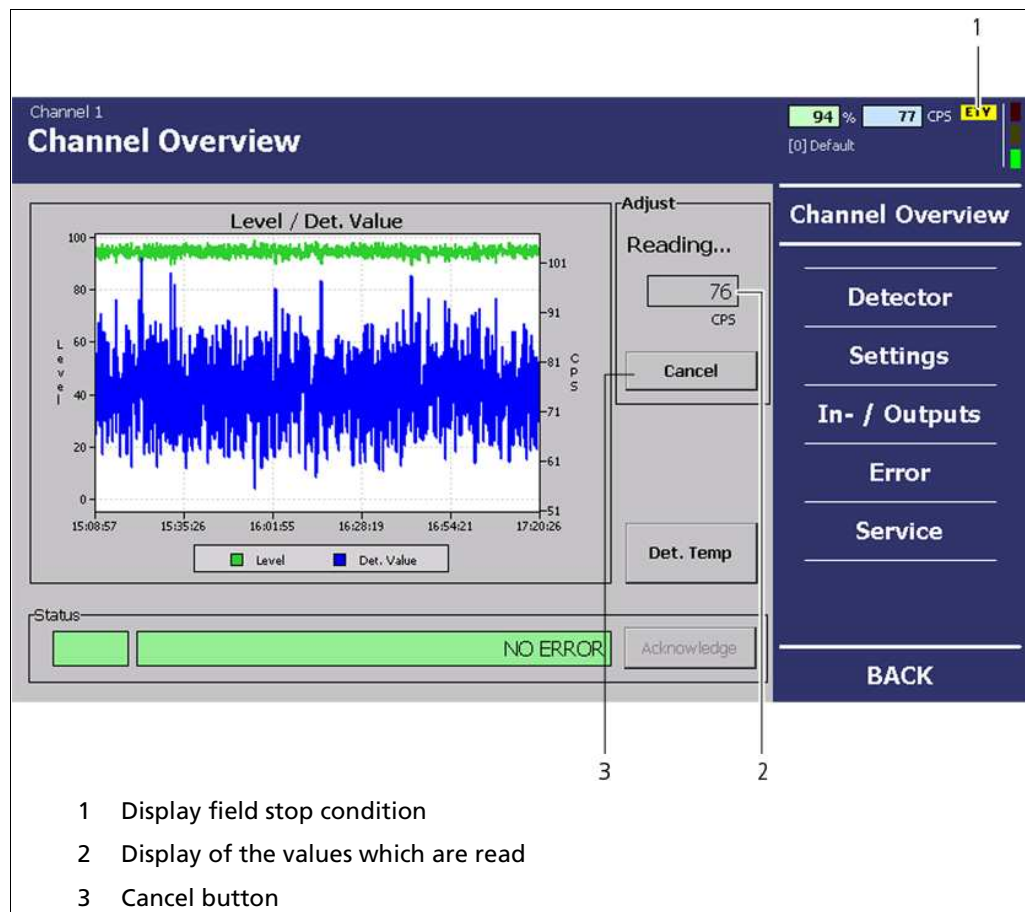


Fig. 53 Menu "Channel Overview", Adjustment - Reading in the values

## Empty and Full Adjustment (Continued)

### Display field "Stop Condition"

<b>TST</b>	The device is in test mode
<b>FUL/ETY</b>	A calibration routine is running in the device: FUL: Full adjustment ETY: Empty adjustment



The evaluation unit is in the "empty adjustment" mode as long as the abbreviation **"ETY"** is displayed and is in "full adjustment mode" as long as the abbreviation **"FUL"** is displayed (Fig. 53, Pos. 1).

Note

Do not adjust any EVU settings while the empty adjustment is taking place.

---



Note

While the device is in test mode or in a calibration routine, the current output is switched to the error mode. The behaviour in error mode can be set under "In/Outputs | Analogue IO | Current Output".

---

## 7.2 Settings

The following information can be seen in the "Settings" submenu:

<b>Active Settings</b>	Display of the selected calibration curve and settings (Fig. 54, Pos. 9)
<b>Calibration</b>	Display of adjustment mode (Fig. 54, Pos. 1) Display of the latest change to the calibration settings (Fig. 54, Pos. 2) Display of the calibration curve (Fig. 54, Pos. 3)
<b>Fill level alarm</b>	Fill level alarm display (Min.) (Fig. 54, Pos. 8) Fill level alarm display (Max.) (Fig. 54, Pos. 7)
<b>Filter</b>	Display of the time constant (Fig. 54, Pos. 4) Display of the start-up time constant (Fig. 54, Pos. 5) Display of the start-up threshold (Fig. 54, Pos. 6)

In the "Settings" submenu, you can adjust the following settings:

<b>Calibration</b>	Changing of the calibration curve(s)
<b>Filter</b>	Changing of the filter settings (time constant and start-up time constant) and the start mode (start threshold and start hysteresis)
<b>Alarms</b>	Setting of the alarm threshold before the minimal fill level of the mould is reached ( <b>Low Alarm</b> ) Setting of the alarm threshold before the maximum fill level of the mould is reached ( <b>High Alarm</b> )
<b>Option/Display</b>	Selection of the calibration curves (in case several have been created) and display of the settings (fill level alarm and filter settings)

## Settings (Continued)

In the "Channel Overview" menu, click on <Settings> (Fig. 49, Pos. 8), in order to reach the "Settings" submenu.

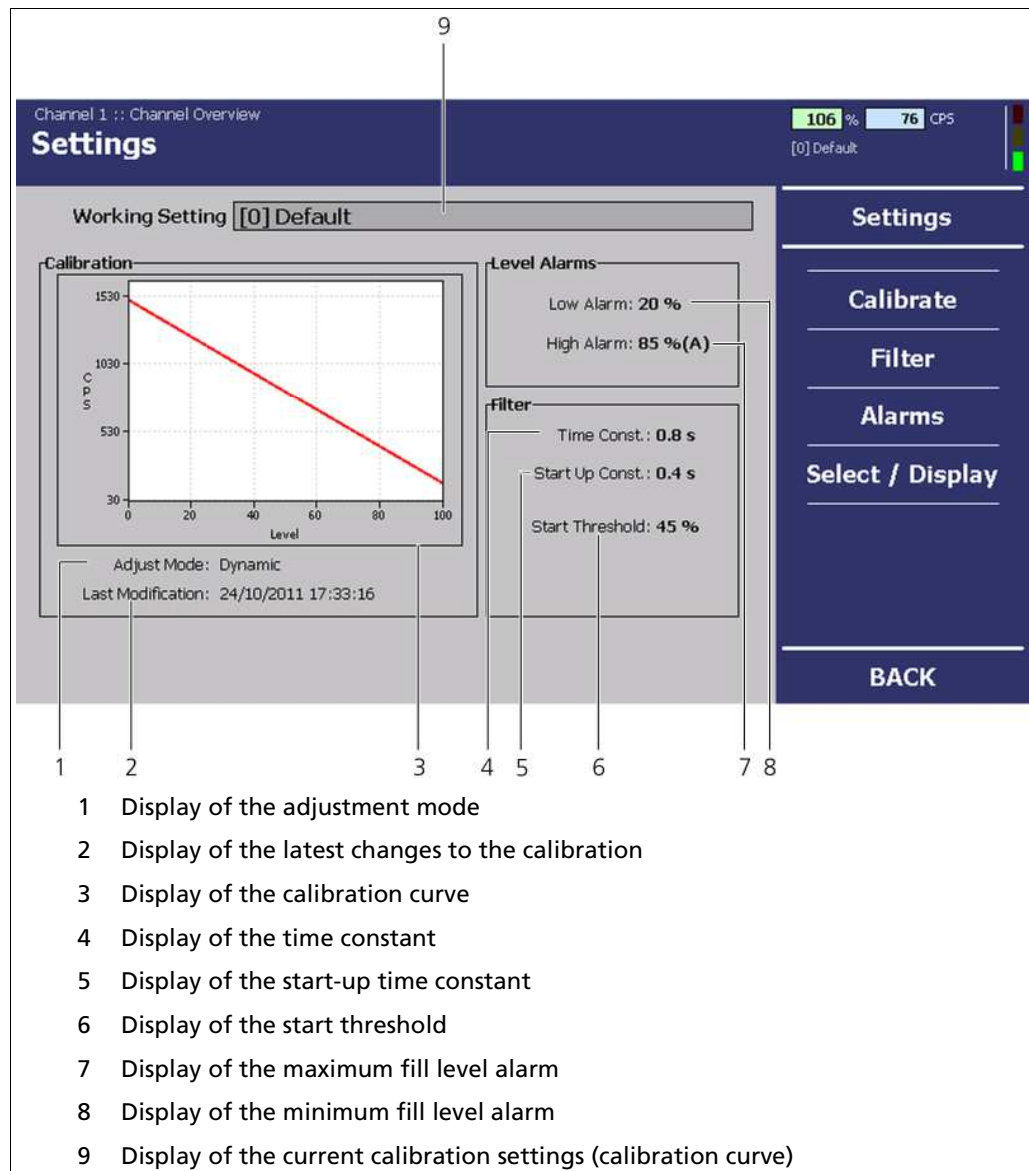


Fig. 54 "Channel Overview" Menu, Settings

## 7.2.1 Calibration

In the "Channel Overview" menu, click on Settings | Calibration (Fig. 54) in order to reach the "Calibration" submenu.

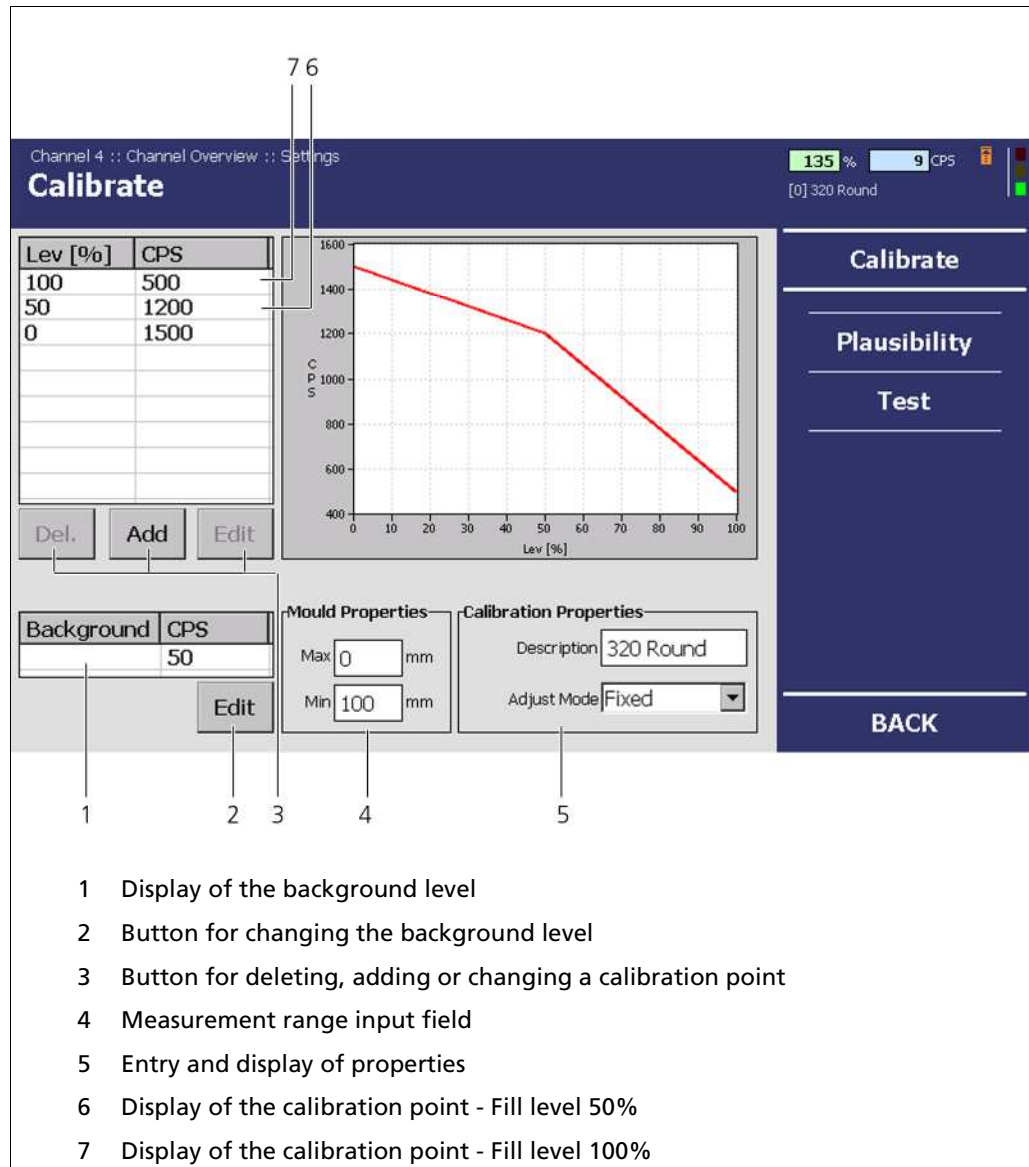


Fig. 55 "Channel Overview" Menu, Settings - Calibration

The calibration submenu serves for the adaptation of the measurement system to the relevant environmental conditions like e.g. the thickness of the mould, the actual radiation activity or the adaptation of the background radiation (background level). The background radiation can vary from location to location.

You can also carry out a multi-point calibration. This is indispensable for operation with an activity-optimised radiation source (AOS) for factoring in the varying rises of the calibration profile between 0% - 50% and 50% - 100%, also leading to increased accuracy with commonly designed sources of radiation.

### Calibration (Continued)

The following information can also be seen:

<b>Display of the calibration points</b>	Fig. 55, Pos. 6 and 7
<b>Curve description</b>	Display of calibration curve description (Fig. 55, Pos. 4)
<b>Adjustment mode</b>	The adjustment mode adjusts the calibration to the changed environmental conditions (e.g. change of the mould or the source). Two different modes are available for calculating the new calibration curve (Fig. 55, Pos. 5):



Note

BERTHOLD TECHNOLOGIES recommends that the calibration mode be set to **"dynamic"** (Fig. 55, Pos. 5) if only an empty calibration is carried out before casting.

If both an empty and a full calibration are performed, the recommended mode is "fixed".

Dynamic	Fixed
In the dynamic adjustment mode, the 100% value is mathematically interpolated using the newly read 0% value during an empty adjustment and the whole calibration is adjusted accordingly.	In the fixed adjustment mode, the 0% value is read anew during an empty adjustment. However, the 100% value remains unaltered. The points in between are adjusted accordingly.

<b>Background Level</b>	The background level indicates the natural background radiation if no radiation source is installed.
<b>Measurement Range</b>	Assignment of the 0% and 100% values for the fill level measurement, if the unit for measuring the fill level is a unit length (mm or inch). The setting can be performed under <System menu   Settings   Units>.



### 7.2.1.1 Adding and Changing Calibration Points

For correct calibration, at least two points (usually 0% and 100%) are required.

An empty mould and a mould with a cold block are usually used to determine the count rate at 0% or 100% fill level.

In order to increase the accuracy of the measurements, the natural background radiation (background level) can be offset.

A multi-point calibration is always possible for increasing the accuracy of measurements and for factoring in any profile non-linearities if needed. When using an activity-optimised radiation source (AOS), this is **indispensable**. In this case, you must also calculate a calibration point at a fill level of 50%.

The activity-optimised radiation source (AOS) enables the increasing of accuracy in the upper part of the measurement range - where a higher level of accuracy contributes to an improvement in quality.

An increase in accuracy can be achieved through optimised-activity distribution without an increase in radiation activity being necessary for this. On the other hand, if the current measurement accuracy is retained, the radiation activity can be significantly reduced.



Note

If it is not possible to use a cold block which simulates a fill level of 50%, then use the count rate which was used in the reading of the AOS. You can find this in your documents.

1. In the "Channel Overview" menu click on **Settings | Calibration** (Fig. 54).
2. Mark the pair of values to be changed (calibration point) by clicking on the corresponding field (Fig. 55, Pos. 7).
3. Click on **<Change>** (Fig. 55, Pos. 2) or on **<New>** (Fig. 55, Pos. 3) if an additional point should be added.
  - ⇒ The input field "Adapt Calibration Point" opens (Fig. 56).

## Adding and Changing Calibration Points (Continued)

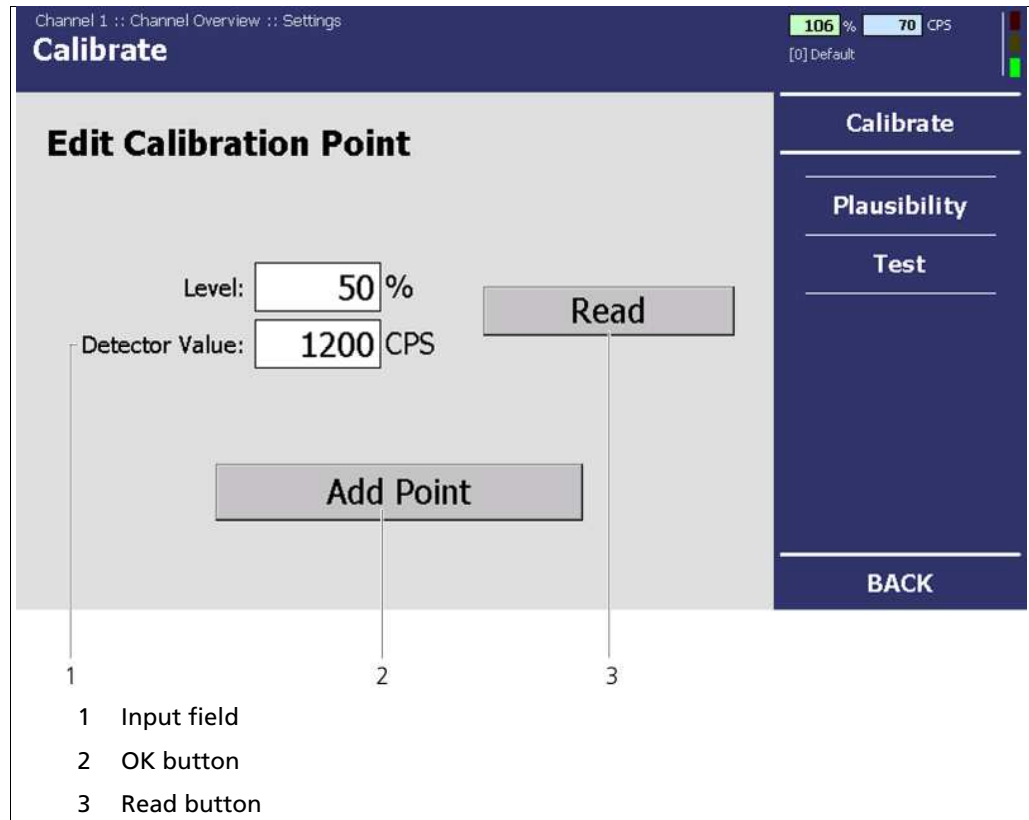


Fig. 56 System Menu, Settings - Calibration (Adapt Calibration Point)

4. When you add a new point, click on the input field "Fill Level" (Fig. 56, Pos. 1) and enter the corresponding fill level (e.g. 50% or 100 mm).
5. Click on **<Read in>** (Fig. 56, Pos. 3) to read in a new calibration point or enter the count rate into the "Detector Value" input field manually (Fig. 56, Pos. 1).
  - ⇒ By clicking on **<Read in>**, the calibration point is automatically read in (Fig. 57). The duration of the read-in process depends on the settings applied in the menu **Settings | Calibration | Plausibility**. Further information on the settings can be found in chapt. 7.2.1.3 in the "Plausibility" submenu.

## Adding and Changing Calibration Points (Continued)

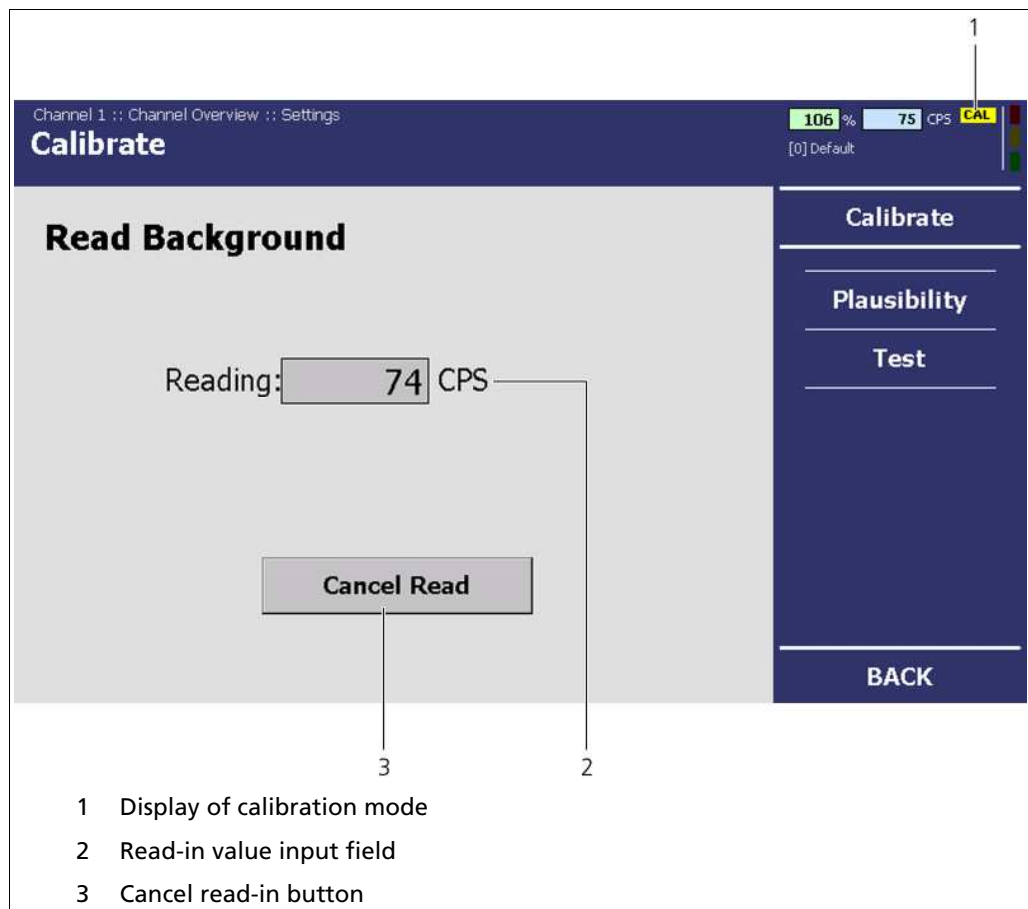


Fig. 57 System Menu, Settings - Calibration (reading in calibration point)

- ⇒ The EVU is in "Calibration (CAL)" mode (Display in Fig. 57, Pos. 1), as long as calibration is being carried out.
- ⇒ The calibration point is automatically created and the current calibration curve displayed.



Note

Carry out the calibration of the mould level in the same way for 100%.



Note

Ensure that the calibration curve is strictly monotonically increasing. If not, correct the points or delete them by clicking on the <Del> button (Fig. 55, Pos. 3).

Up to 20 calibration value pairs can be entered.

### 7.2.1.2 Setting of the Background Level

1. Click in the "Channel Overview" menu | Settings | Calibration (Fig. 54, Pos. 2).  
⇒ The "Background Level" menu opens (Fig. 58).

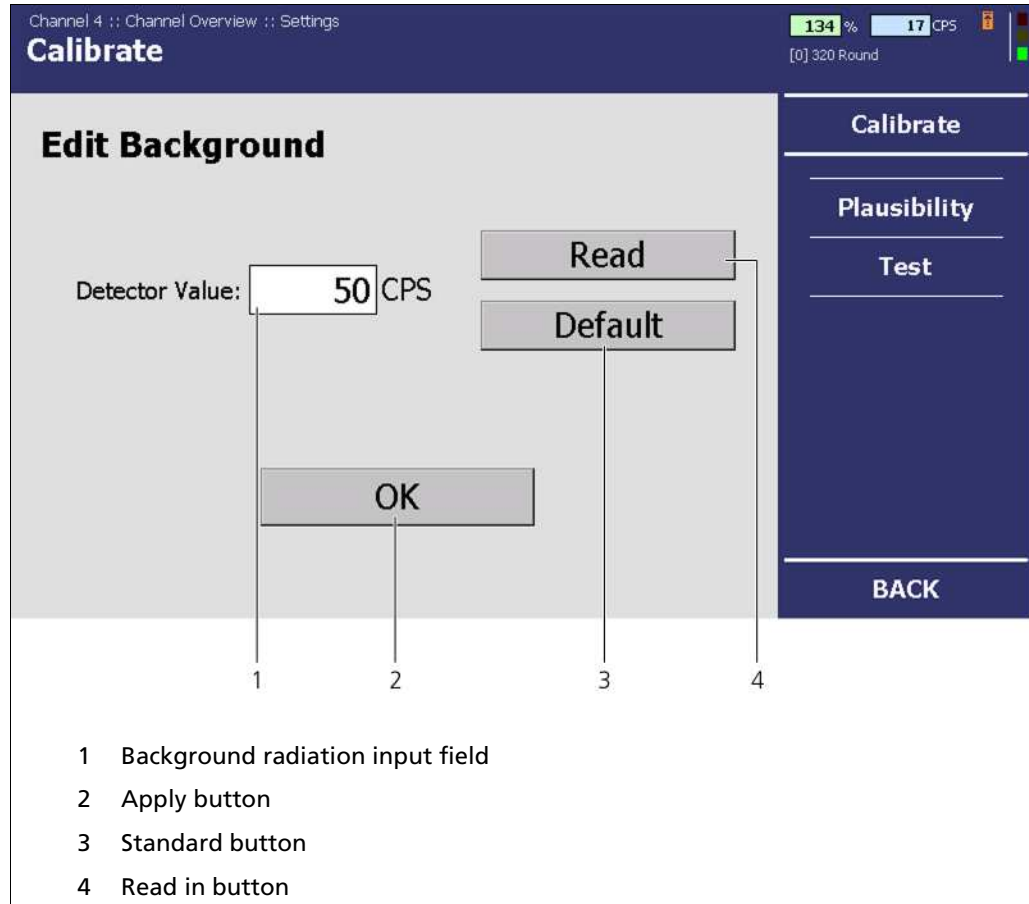


Fig. 58 "Channel Overview" Menu, Settings - Calibration (Background Level)

2. Remove the radiation source from the GAMMAcast detector. Otherwise, the measuring of the background radiation is disrupted.
3. Click on <Read in> (Fig. 58, Pos. 4) to read in the background level or click on <Standard> (Fig. 58, Pos. 3), to use the standard value of 50 cps (preset).
4. Confirm your entry by clicking on <OK> (Fig. 58, Pos. 2).

### 7.2.1.3 Plausibility

In the "Channel Overview" menu click on Calibration | Plausibility (Fig. 59, Pos. 1).



Fig. 59 "Channel Overview" Menu, Settings - Calibration (Plausibility)

In the "Plausibility" menu, the applied settings can be examined. If the settings are not plausible, an error is triggered. You have the following setting options:

<b>Min. empty/full ratio</b>	If the ratio of the empty count rate to the full count rate is smaller than the ratio entered, an error is triggered.
<b>Maximal Tolerance Empty Adjust</b>	If the newly read in count rate for 0% fill level differs from the value of the last adjustment by more than the percentage given, an error is triggered.
<b>Maximal Tolerance Full Adjust</b>	If the newly read in count rate for 100% fill level differs from the value of the last adjustment by more than the percentage given, an error is triggered.

**Plausibility (Continued)**

- Maximum Read-in time**      Maximum time waited when reading in a count rate during calibration or an adjustment. A minor average value error results if the time is longer.
  
- Read-in Statistic Threshold**      The reading in of a count rate during calibration or an adjustment is cancelled as soon as this statistical variation limit of the count rate is fallen short of.

**7.2.1.4 Test**

In the "Channel Overview" menu click on Settings | Calibration | Test (Fig. 59, Pos. 1).

In the "Test" submenu, you can enter a test count rate (Fig. 60, Pos. 3) which is used instead of the count rate of the GAMMAcast detector to calculate the fill level. As long as this test count rate is in effect, the background of the input field will be shown in red. The calculated fill level is displayed (Fig. 60, Pos. 3).

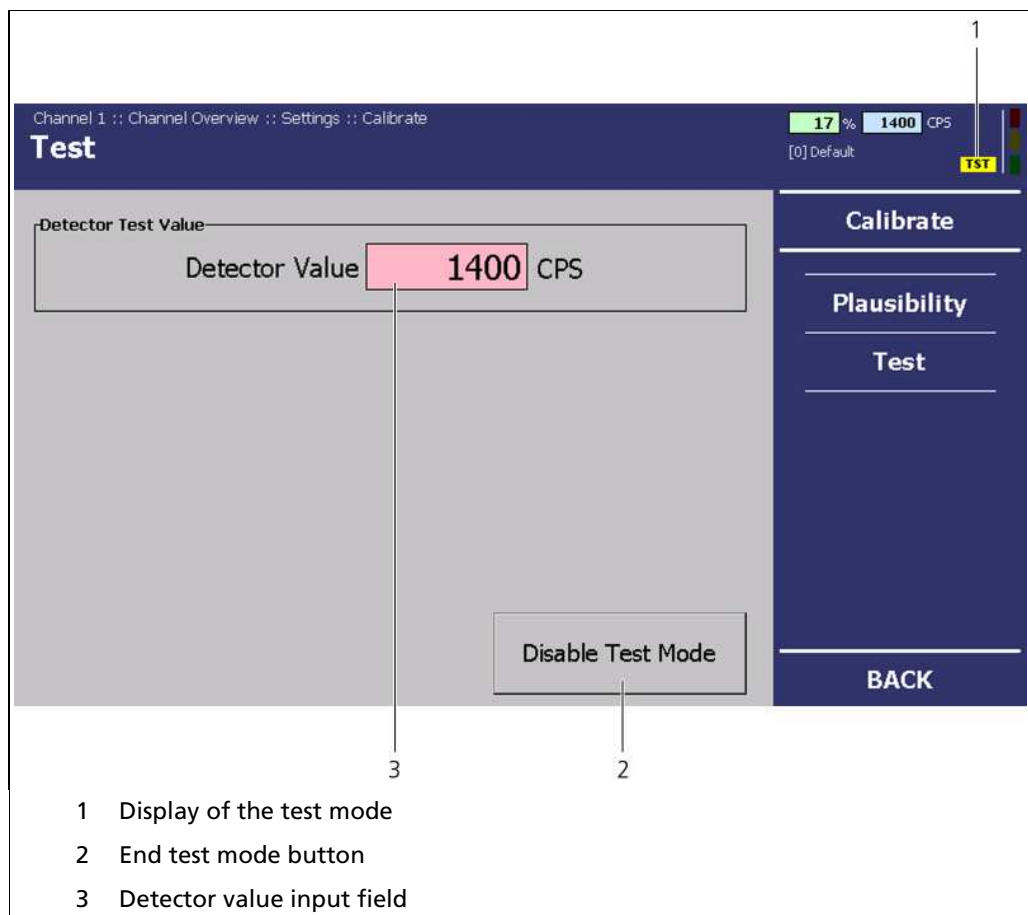


Fig. 60 "Channel Overview" Menu, Settings - Calibration (Test)

**Test (Continued)**

1. Click in the input field (Fig. 60, Pos. 3).  
⇒ The numeric keypad opens (Fig. 18).
2. Enter a test count rate.
3. Confirm your entry by clicking on "Enter".  
⇒ The test mode is started (Fig. 60, Pos. 1).
4. Click on <End test mode> to end the test.



Note

The current output switches to the fault current (see chapt. 7.3.1).



Note

The test count rate ends automatically after 5 minutes. If the test count rate is to be activated again, the value must be entered in the input field again.

**7.2.2****Filter**

In the "Channel Overview" menu, click on Settings | Filter (Fig. 54, Pos. 4).

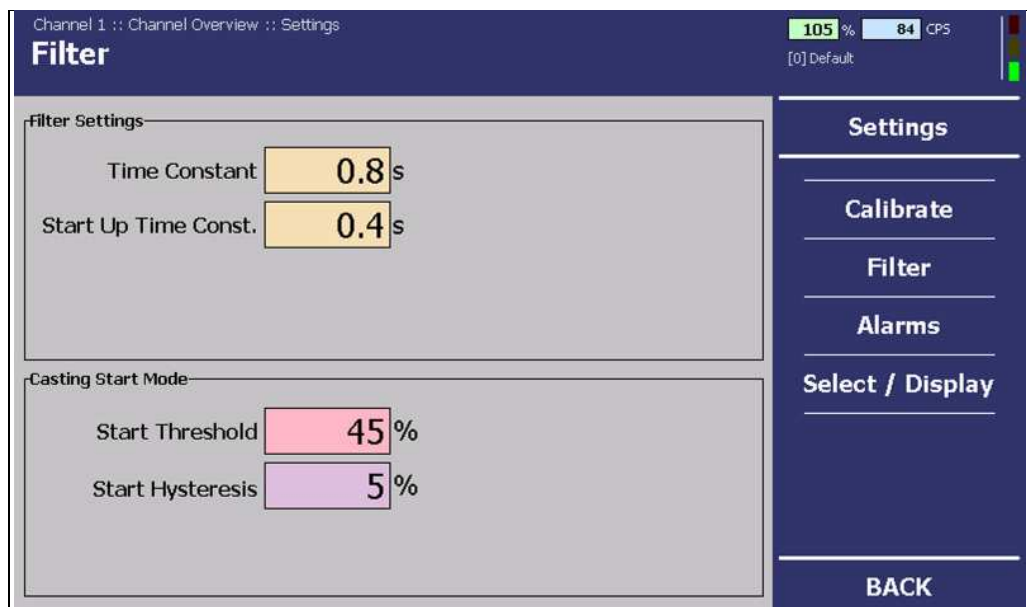


Fig. 61 "Channel Overview" Menu, Settings - Filter

## Filter (Continued)

In the "Filter" submenu, you can set the time constants for filtering the gross count rate and settings for the start mode.

### **The Setting of Two Different Time Constants:**

The setting of the time constant helps to balance out statistical variations, mainly from the statistical nuclear decay of the radionuclide. A large filter time leads to a calmer signal but also to a slower reaction of the fill level signal to physical fill level changes.

The time constant entered as start-up time constant works within the fill level range of 0% to the "start threshold" (here 45%). This switch-over point has a hysteresis which can also be adjusted freely (for an explanation of the hysteresis see chapt. 7.2.3).

In the remaining range, the value entered as "time constant" is used.



### 7.2.3 Alarms



The submenu "Alarms" is only displayed if an extension module is installed.

Note

In the "Channel Overview" menu click on Settings | Alarms (Fig. 54).

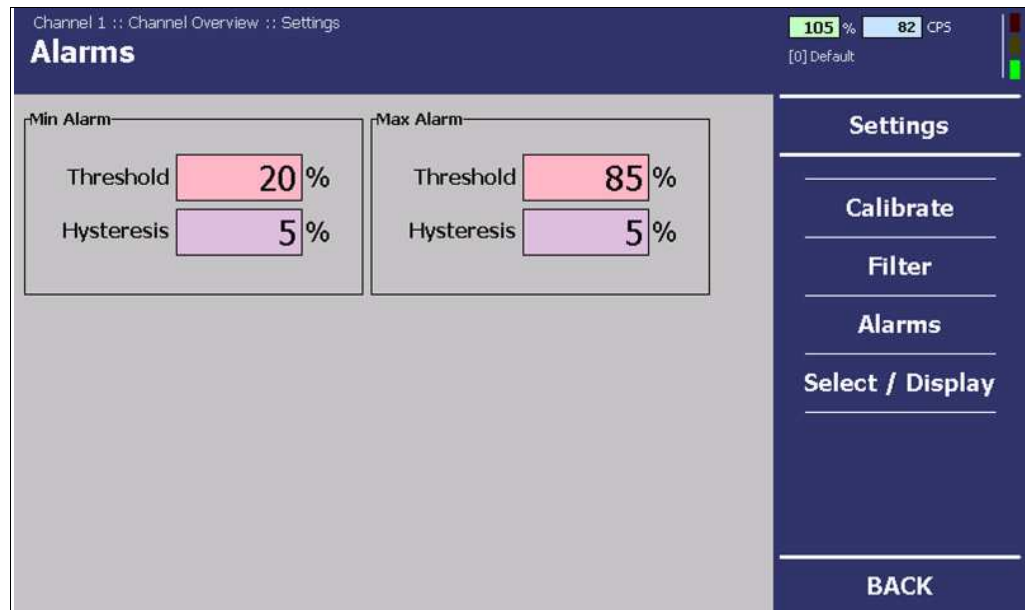


Fig. 62 "Channel Overview" Menu, Settings - Alarms

In the "Alarms" submenu, you can change the values for the fill level alarms (max. and min.) and the hysteresis of these. These values are required for the alarm relays on the extension module.

### Hysteresis

Hysteresis is defined as the tolerance range of the alarm trigger which occurs at a predefined threshold of the fill level (e.g.: 20% and 85%).

- In the event of a **rising fill level**, the high alarm is triggered when a fill level of (here) 85% is exceeded. If the fill level falls again, then the alarm does not switch off again until the fill level falls below (here)  $85\% - 5\% = 80\%$ .
- In the event of a **falling fill level**, the low alarm is triggered when the fill level falls below (here) 20%. If the fill level rises again, then the alarm does not switch off again until the fill level exceeds (here)  $20\% + 5\% = 25\%$ .

## 7.2.4 Option/Display

In the "Channel Overview" menu click on Settings | Select/Display (Fig. 54).

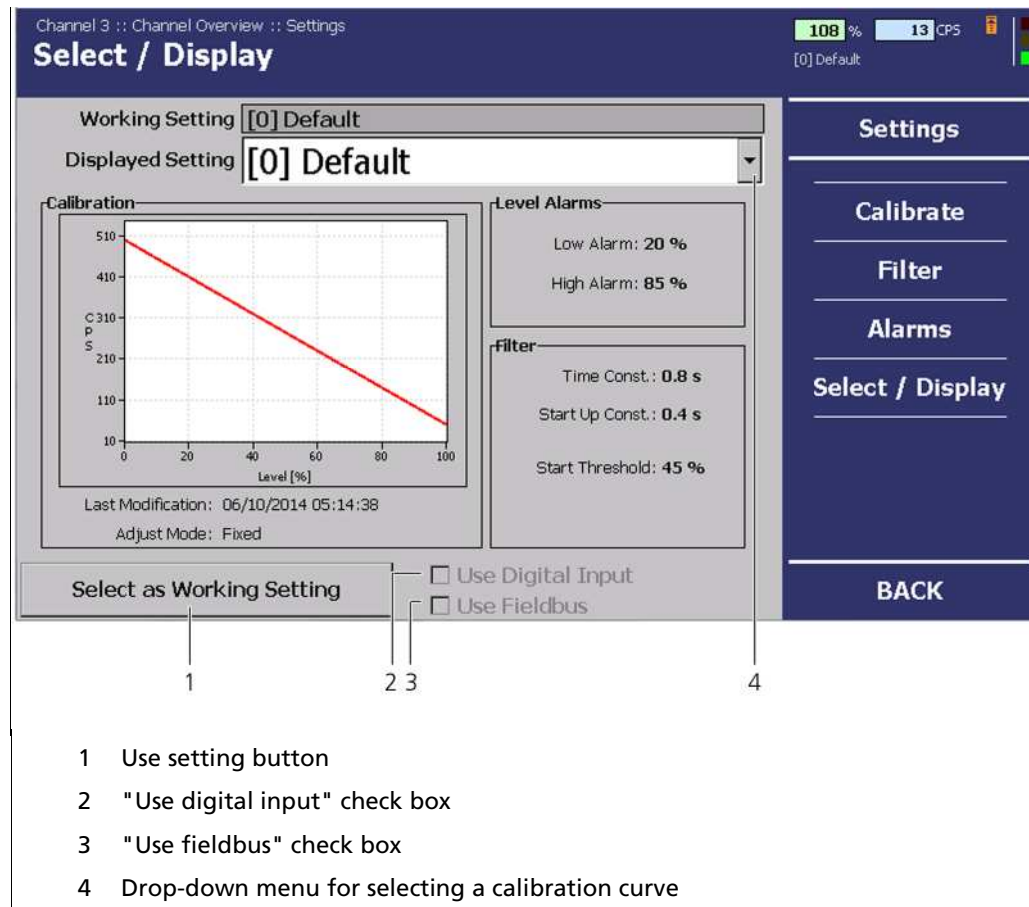


Fig. 63 "Channel Overview" Menu, Settings- Select/Display

In the "Select/Display" submenu, you can view the applied calibration, fill level alarms and filter settings. You can also select calibration curves in the drop-down menu (Fig. 63, Pos. 3) as long as additional ones have been created.

1. Click on the button drop-down menu (Fig. 63, Pos. 3).
2. Select a calibration curve.
3. Confirm your entry by clicking on <Use Settings> (Fig. 63, Pos. 1).

**Dig. Use input:**

If there is a tick, then the selection of the calibration curves is converted to the digital inputs.

**Use fieldbus:**

If there is a tick, then the selection of the calibration curves is converted to the fieldbus module.

Select/Display (Continued)

The selection works through the digital inputs as is described in the following:

Select Calibration curve	Digital Input 3	Digital Input 4
0	open	open
1	closed	open
2	open	closed
3	closed	closed

7.3 In/Outputs

1. In the "Channel Overview" menu click on <In/Outputs> (Fig. 49, Pos. 8).
2. Click on <Analogue IO> or <Digital IO> (Fig. 64, Pos. 1).

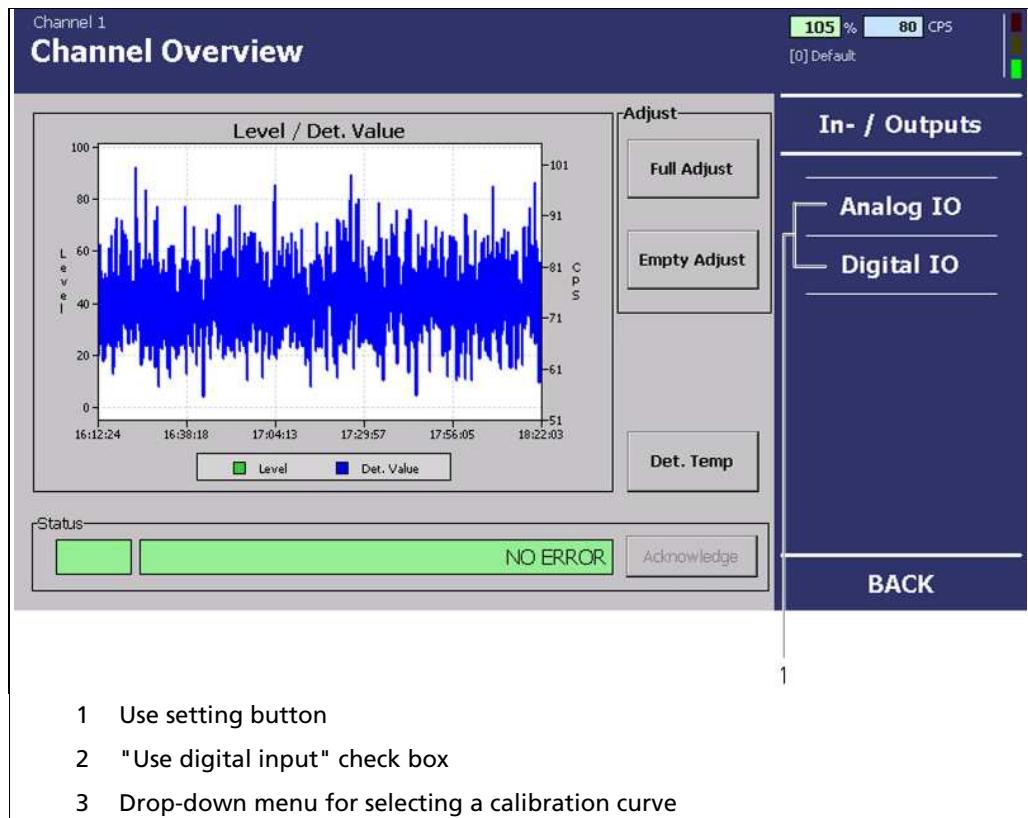


Fig. 64 "Channel Overview" Menu, Settings - In/Outputs

## In/Outputs (Continued)

In the "In/Output" submenu, you can configure the analogue current outputs, the digital inputs, the alarm relays (only with the extension module) and the the fieldbus module (if installed).

The current output itself is continually monitored and reports malfunction via a redundant current path at a constant current of 24 mA.

### 7.3.1 Analog IO

You have the following setting options:

<b>4 mA</b>	Output value (e.g. fill level) at 4 mA
<b>20 mA</b>	Output value (e.g. fill level) at 20 mA
<b>Error mode</b>	The error mode defines the behaviour of the error relays in the event of an error.
<b>Calibration of the Current Output/Current Outputs</b>	If you find any discrepancies between the setpoint and the actual value of the current signal, then you can calibrate the current output again.



Note

In order to calibrate the current outputs, you will need an ammeter (not included in the delivery contents), which is to be connected to the relevant current output.



Note

BERTHOLD TECHNOLOGIES recommends calibrating the current outputs whenever a module has been installed/replaced or if a software update has been carried out.

---

### 7.3.1.1 Setting of the Current Outputs

1. In the "Channel Overview" menu, click on e.g. In/Outputs | Analogue IO | Current Output 2 (Fig. 65, Pos. 8).

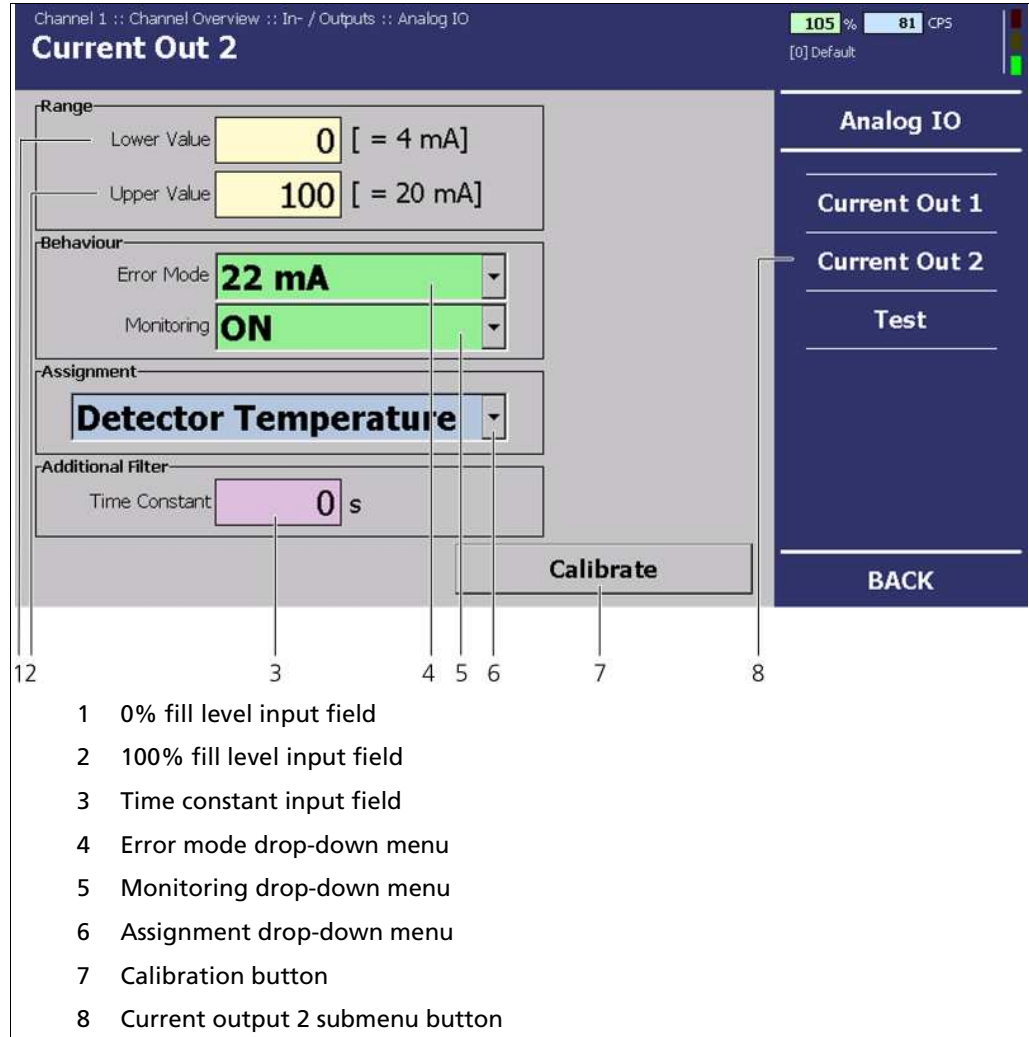


Fig. 65 "Channel Overview" menu, In/Outputs - Analogue IO (Current Output 2)

## Setting of the Current Outputs (Continued)

You have the following options for configuring the current outputs:

- Range**            The current output signal is between 4 mA and 20 mA. The corresponding values (e.g. fill level) can be freely assigned.
- Lower value:**  
The lower value is the value at a current output signal of 4 mA.
- Upper value:**  
The upper value is the value at a current output signal of 20 mA.



Note

The value which is assigned to a current output signal of 4 mA must be smaller than the value which is assigned to that of 20 mA.

- Behaviour**        **Error Mode:**
- Here, settings can be made concerning the way the current output is to behave if the EVU or the GAMMAcast detector reports an error. In the event of an error, the error relay is de-energised (see there), a message appears in the channel menu and the red measurement channel LED lights up. The current output also switches to error mode.
- There is a choice between:
- Constant 2 mA
  - Constant 22 mA
  - Freezing the last measured value



Note

If the last measured value is frozen, a measurement system error cannot be seen in the process control system on the current output signal.



Note

As long as the device is in test mode or in a calibration routine, the current output is switched to the error mode.

## Setting of the Current Outputs (Continued)



Note

Do not activate the "monitoring" (Fig. 65, Pos. 5) until the measurement has been fully wired. By doing so you will avoid the error alarm.

### Monitoring

If the "monitoring" is activated, the current output will be monitored. Here, the output current is compared with the current which has run right through the conductor loop. In the event of a variation e.g. owing to an error in the hardware, too large a load or a disruption in the loop, an error message is triggered. The error relay is de-energised.

Additional settings options in an installed extension module for current output 2 are:



Note

The Current Output 2 submenu is only displayed when an extension module is built in.

### Assignment (only for current output 2)

#### Fill Level:

The second current output also transmits the fill level. An additional time constant can be set (see below).

#### Detector Value:

The second current output also transmits the measured count rate (CPS value).

#### Detector temperature:

The second current output transmits the temperature measured in the detector.



Note

If the second current output is assigned to the detector temperature or the detector value (cps), it is particularly important to adhere to an appropriate setting of the current output values for 4 or 20 mA.

### Additional filter (only for current output 2)

An additional filter time constant can be applied to the second current output. This is added to the time constant set under "Filter" in case fill level is selected. The signal is thereby smoother but slower as a result.

### 7.3.1.2 Calibration of the Current Outputs

1. Before calibrating the current outputs, connect an ammeter (not included in the delivery contents) to the relevant current output.
2. Click on **<Calibration>** (Fig. 65, Pos. 7).  
⇒ A confirmation message opens.
3. Click on **<Next>** in the confirmation message.  
⇒ The device switches to test mode.  
⇒ A command prompt opens.
4. Click on the input field to enter a value for the 4 mA calibration point.  
⇒ The numeric keypad opens (Fig. 18).
5. Enter the value transmitted by the ammeter.
6. Click on **<Next>** in the confirmation message.
7. Carry out the calibration for 20 mA calibration point in the same way.  
⇒ A confirmation message with the notification "Calibration finished" opens.
8. Click on **<Next>** to finish the calibration.



### 7.3.1.3 Test

In the "Test" submenu, you can enter your own current value for the sake of the test (Fig. 66, Pos. 4). As long as this test current is in effect, the background of the input field will be shown in red. In the "Actual" display field, the actual current is displayed. This value cannot be changed.

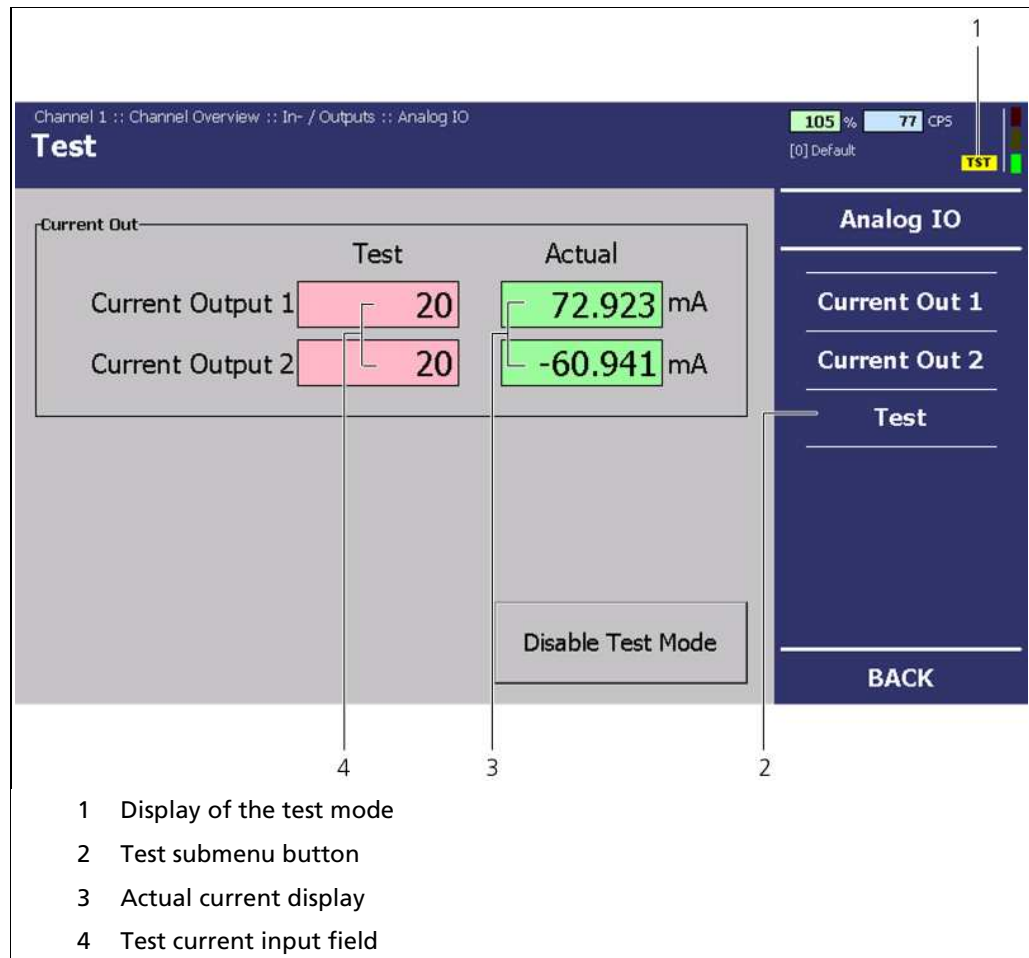


Fig. 66 "Channel Overview" menu, In/Outputs - Analogue IO (Test)

1. In the "Channel Overview" menu click on In/Outputs | Analogue IO | Test (Fig. 66, Pos. 2).
2. Click in the input field (Fig. 66, Pos. 4).  
 ⇒ The numeric keypad opens (Fig. 18).
3. Enter a test current and confirm your entry by clicking on "Enter".

## Test (Continued)

If the entered value is accepted, the background of the input field will be shown in red. In the "Actual" field, the read-back current which is also used for the current output monitoring is displayed. If the conductor loop is not closed, no real measured value will be displayed.

⇒ The test mode is started (Fig. 66, Pos. 1).

4. Click on **<End test mode>** if you would like to end the test current.



Note

The test function ends automatically after around 5 minutes. If the test function is to be reactivated, the value must be re-entered.



Note

If only one current output is being tested, the other current output switches automatically to error mode.

### 7.3.2

## Digital IO

In the Digital IO submenu, you can set the two different alarm signals for the alarm relays.

### 7.3.2.1

## Alarm Relay



Note

The Alarm Relay submenu is only displayed if an extension module is installed.

**Alarm Relay (Continued)**

In the "Channel Overview" menu click on In/Outputs | Digital IO | Alarm Relay (Fig. 67, Pos. 2), to reach the Alarm Relay submenu.

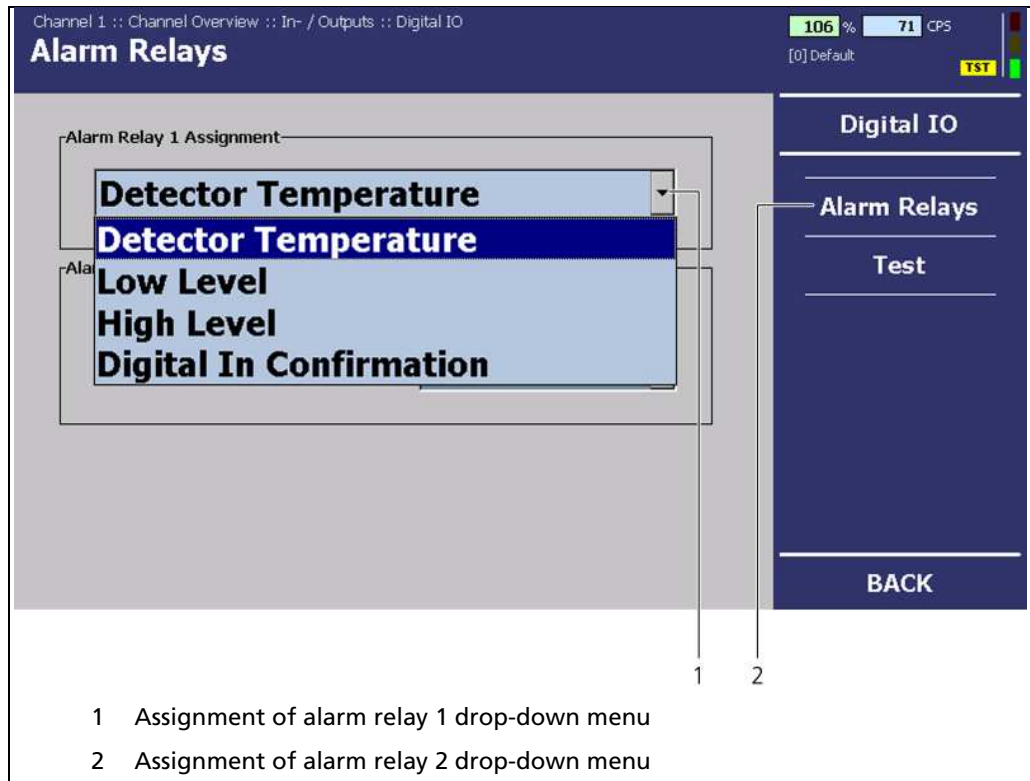


Fig. 67 "Channel Overview" Menu, In-/Outputs - Digital IO (Alarm Relay)

The alarm relays 1 and 2 can be assigned to the following functions in the event of an alarm:

- |                                |  |
|--------------------------------|--|
| <b>Detector temperature</b>    | The relay switches if the alarm threshold set in the <b>Menu Detector   Temperature</b> is exceeded (see detector manual).     |
| <b>Low level</b>               | The relay switches if the value set under <b>Channel Overview   Settings   Alarms</b> chapt. 7.2.3 is <b>fallen short of</b> . |
| <b>High level</b>              | The relay switches if the value set under <b>Channel Overview   Settings   Alarms</b> chapt. 7.2.3 is <b>exceeded</b> .        |
| <b>Digital in confirmation</b> | This relay switches if the digital input is switched.  |

## Alarm Relay (Continued)



Note

The alarm relay 1 is a contact (SPDT).

The behaviour of alarm relay 1 can be freely configured ("CLOSED", i.e. switching to the normally-open contact or "OPEN",

i.e. the normally-closed contact, in the case of an alarm).

### Behavior for software versions earlier than 1.2.0:

The relay always closes in the event of an alarm, i.e. it switches on the normally open contact.



Note

Alarm relay 2 is a simple switch (SPST NO). The behaviour in the event of an alarm can be freely configured ("CLOSED" or "OPEN" in the case of an alarm).

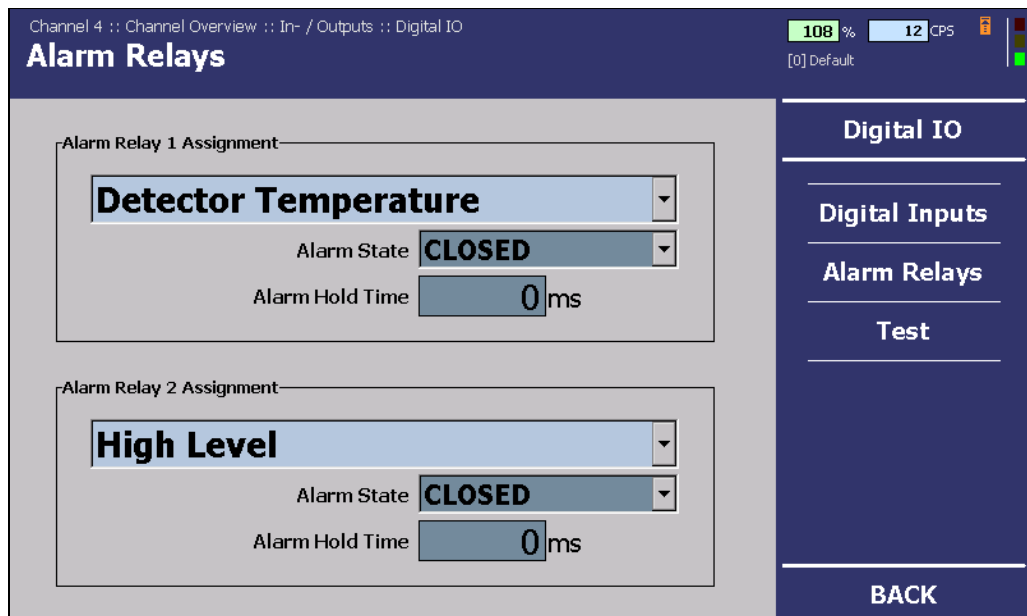


Fig. 68 "Channel Overview" Menu, In/Outputs - Digital IO (Alarm Relay)

### Alarm Hold Time

An alarm always lasts as long as the reason for the alarm is present, but not less than the specified time.



Note

If the EVU is disconnected from voltage, then both relays are de-energised, moving to their normally-closed contact.



Note

The error relay can not be configured. It always switches on during normal operation and switches off in the event of an error. To get the same behaviour for the alarm relays, both must be configured as "OPEN".

7.3.2.2 Test

In the "Test" submenu, you can change the states of the relay outputs for the sake of the test.

**Green background area** = current state

**Red background area** = manually switched state (test mode)



The digital inputs cannot be configured.  
Fig. 69 only informs of the switched state.

Note

In the "Channel Overview" menu, click on In/Outputs | Digital IO | Test (Fig. 69, Pos. 3).

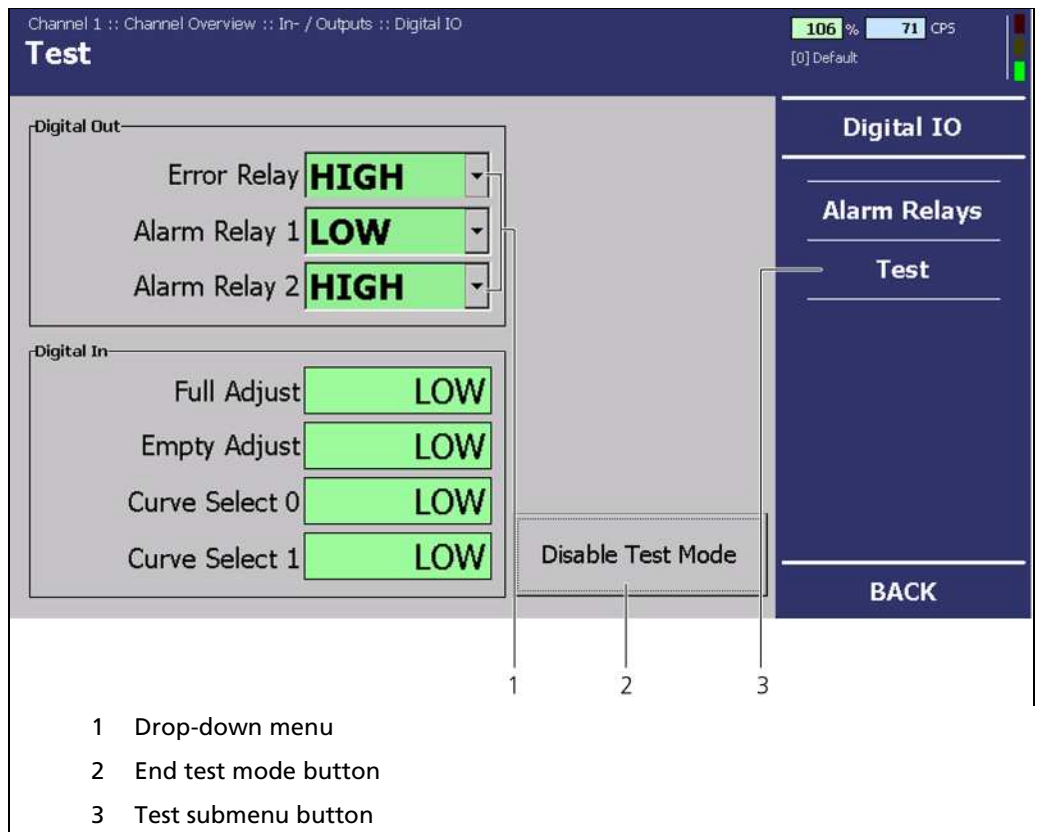


Fig. 69 "Channel Overview" menu, In/Outputs - Digital IO (Test)

**Test** (Continued)

<b>Digital Outputs</b>	CLOSED= Relay energised OPEN= Relay de-energised
<b>Digital inputs</b>	CLOSED= Terminals connected OPEN = Terminals not connected

1. Click on the **"Error Relay" drop-down menu**, to switch the error relay manually (Fig. 69, Pos. 1).
2. Click on the **"Alarm Relay 1" drop-down menu** menu to switch the alarm relay manually (Fig. 69, Pos. 1).
3. Click on the **"Alarm Relay 2" drop-down menu** menu to switch the alarm relay manually (Fig. 69, Pos. 1).
4. Click on **<End Test Mode>** (Fig. 69, Pos. 2) if you would like to end the test mode.



Note

The test function ends automatically after around 5 minutes. If the test pulse rate should be re-enabled, the value must be re-entered.

### 7.3.2.3 Fieldbus

The "Fieldbus" submenu only appears if a Fieldbus module has been installed. For the installation of a Fieldbus module, see chapt. 9.1.2.



Note

To be able to use the Fieldbus module, you must install the provided GSD file in the process control system.

1. In the "Channel Overview" menu click on In/Outputs | Fieldbus (Fig. 70, Pos. 2).
2. Click in the "Profibus" input field: Address" (Fig. 70, Pos. 1).  
⇒ The numeric keypad opens (Fig. 18).

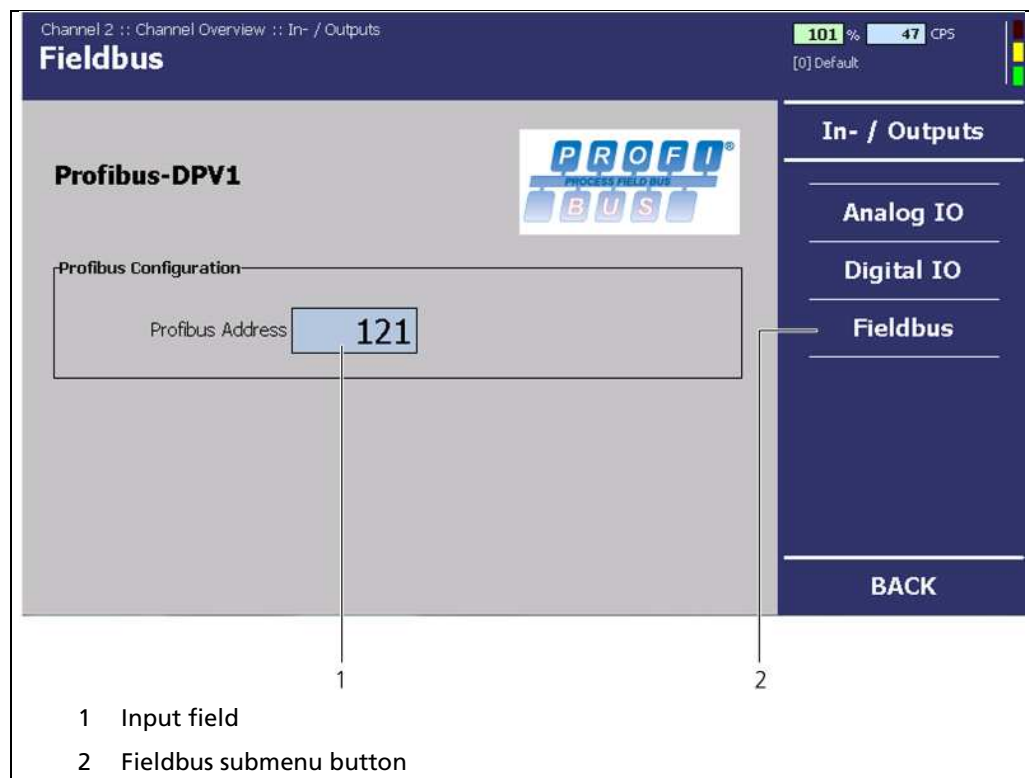


Fig. 70 "Channel Overview" Menu, In/Outputs - Fieldbus

3. In the input field „Profibus: Configuration" enter the address of the bus device (Fig. 70, Pos. 2).

## 7.4 Error

In the "Channel Overview" menu, click on <Error> (Fig. 49, Pos. 8).

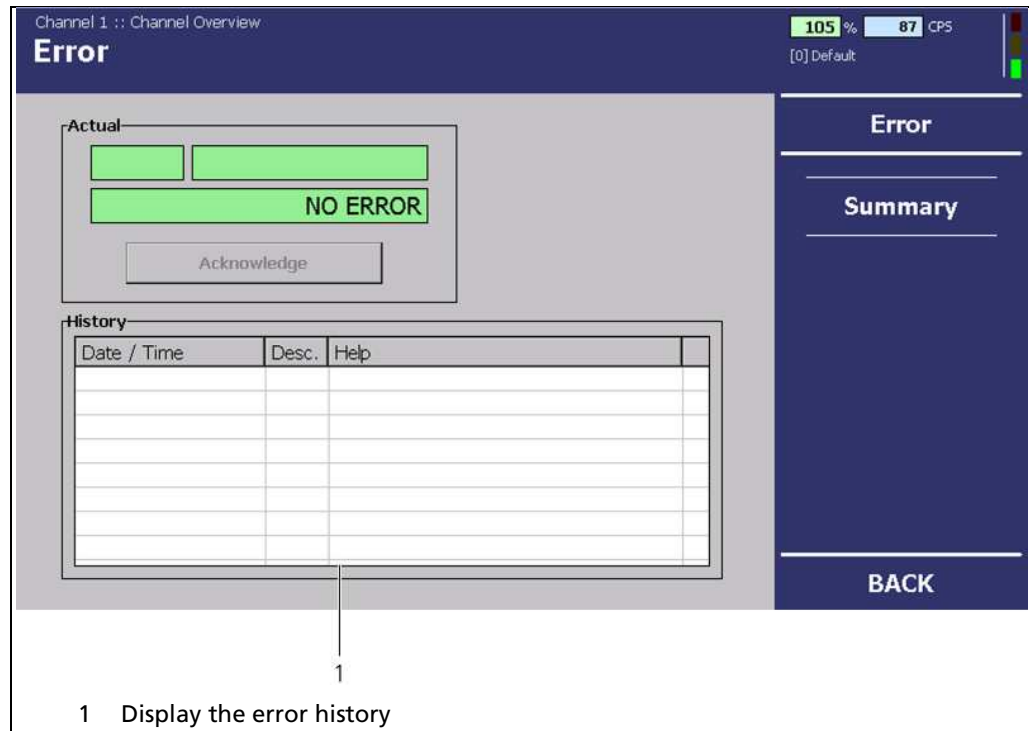


Fig. 71 "Channel Overview" Menu, Error

In the "Error" submenu, you can view the following information:

- Current** Displays the current error message and the error code.
- History** Displays the error history with the error message and the error codes.



### 7.4.1 Overview

In the "Channel Overview" menu, click on Error | Overview to reach the Overview submenu (Fig. 72, Pos. 2).

Channel 1 :: Channel Overview :: Error

**Summary** 105% 78 CPS [0] Default

Desc.	Help	Count	A..	Occurance	Occurance 1
101	HW module corrupted	0	x	2000-01-01 00:00:00	2000-01-01
102	Device data corrupted	1	x	2011-10-24 09:01:44	2000-01-01
103	RAM, flash or CPU	0	x	2000-01-01 00:00:00	2000-01-01
104	WD reset	0	x	2000-01-01 00:00:00	2000-01-01
105	WD failure	0	x	2000-01-01 00:00:00	2000-01-01
106	WD off	0	x	2000-01-01 00:00:00	2000-01-01
107	RTC date/time	0	x	2000-01-01 00:00:00	2000-01-01
108	Software exception	0	x	2000-01-01 00:00:00	2000-01-01
201	Monitor ADC failure	0	x	2000-01-01 00:00:00	2000-01-01
202	ADC calibration	0	x	2000-01-01 00:00:00	2000-01-01
203	24V failure	0	x	2000-01-01 00:00:00	2000-01-01
204	3.3V failure	0	x	2000-01-01 00:00:00	2000-01-01
205	GND failure	0	x	2000-01-01 00:00:00	2000-01-01
206	Ref 2.5V failure	0	x	2000-01-01 00:00:00	2000-01-01
207	Temp. sensor failure	0	x	2000-01-01 00:00:00	2000-01-01
208	Temperature too high	0	x	2000-01-01 00:00:00	2000-01-01
209	Quartz synchronization	0	x	2000-01-01 00:00:00	2000-01-01
301	Calibration not monotonic	30	x	2011-11-24 12:19:31	2011-11-24

1 Display of the error details of the error messages

2 Overview submenu button

Fig. 72 "Channel Overview" Menu, Error Overview

In the Overview submenu, you can find a detailed error list (Fig. 72, Pos. 1).

## 7.5 Service

In the Service submenu you have the following options:

- Exporting service data onto a USB flash drive.

**Service data includes:**

- The change log
- The error log
- The production data
- Resetting of the channel settings to factory setting (calibrating, time constants, alarms thresholds, etc.)
- Restarting of the software (of the relevant measurement channel).

In the "Channel Overview" menu click on <Service> to reach the Service submenu (Fig. 49, Pos. 8).

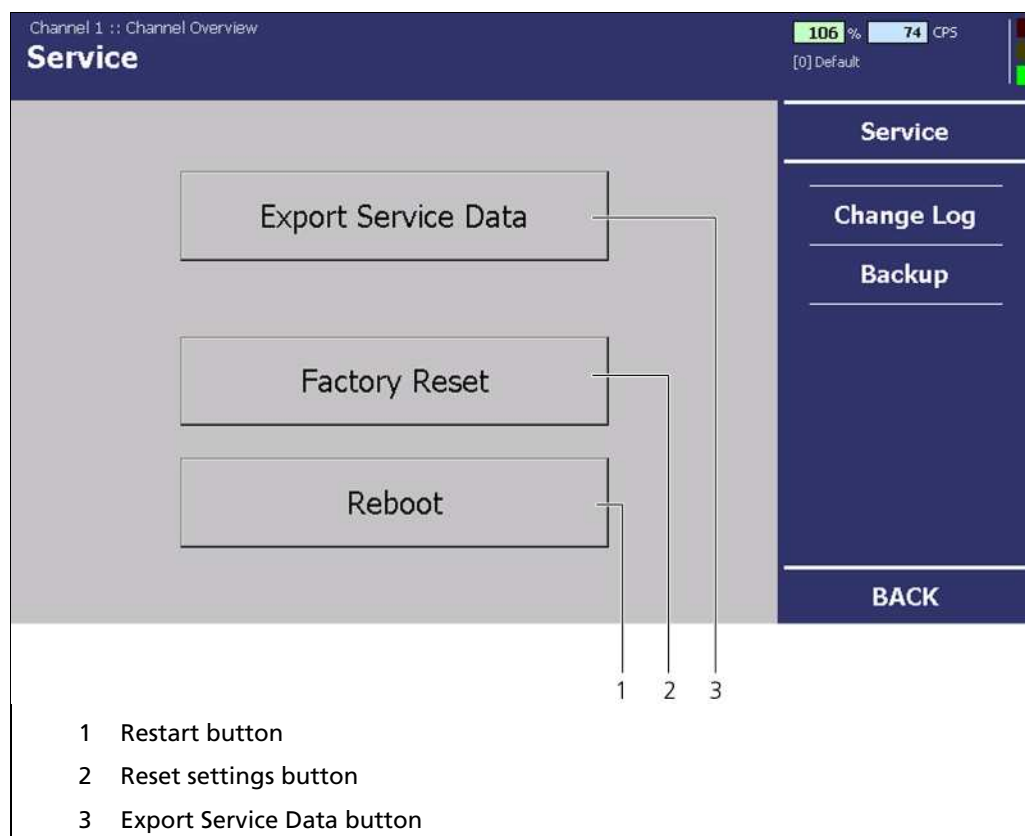


Fig. 73 "Channel Overview" Menu, Service

### 7.5.1 Exporting Service Data



Note

The <Export Service Data> button becomes active if you connect a USB flash drive to the front panel.

4. Click on <Export Service Data> (Fig. 73, Pos. 3).  
⇒ The warning window opens automatically.
5. Confirm the warning by clicking on <OK>.

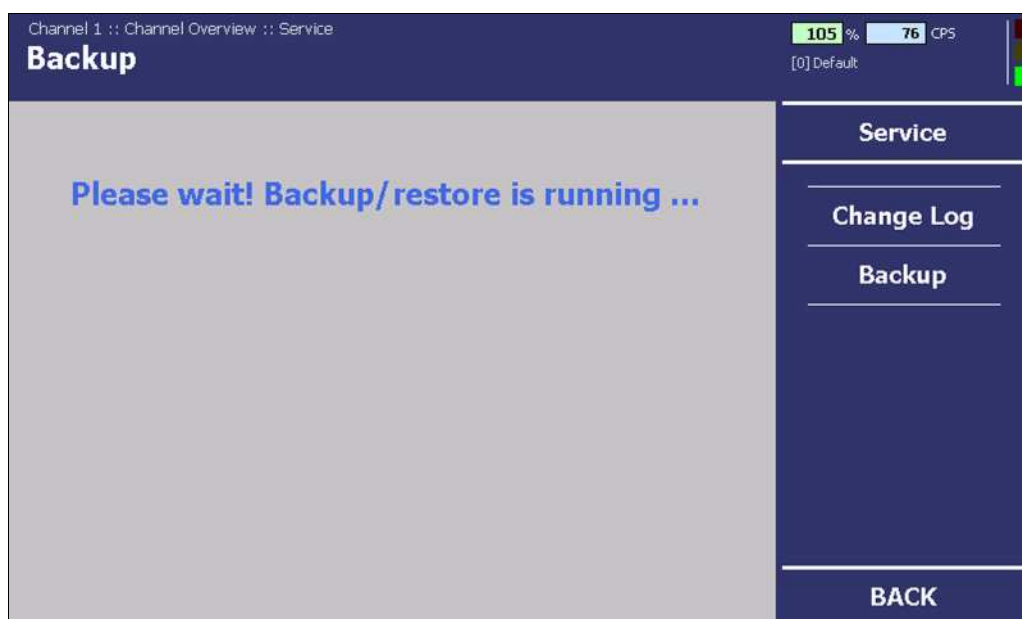


Fig. 74 "Channel Overview" Menu, Service - Backup/restore is running

⇒ The export of data starts (Fig. 74).



Attention

If you click on <Factory Settings> all applied settings will be reset.

The measurement is retained.

If you click <Restart> the measurement channel restarts.

The measurement of the relevant channel is then retained.

The measurements of the other measurement channels remain unaffected by this.

## 7.5.2 Change log

In the Change Log submenu you can view all the applied settings.

In the "Channel Overview" menu click on **Service | Change log** to reach the Change Log submenu (Fig. 75, Pos. 2)

⇒ The change log is displayed (Fig. 75, Pos. 1).

Channel 1 :: Channel Overview :: Service

**Change Log**

105% 76 CPS  
[0] Default

Date / Time	Description	New Value	Old Value
2011-10-24 05:41:42	Rem CEntry	50.00	0.00
2011-10-24 05:38:55	TEST OFF	1.00	0.00
2011-10-24 05:36:42	TEST ON	0.00	1.00
2011-10-24 05:33:16	Add CEntry	100.00	150.00
2011-10-24 05:33:02	AdjustMode	0.00	1.00
2011-10-24 05:32:50	Add CEntry	50.00	1200.00
2011-10-24 05:32:23	Add CEntry	100.00	150.00
2011-10-24 05:32:02	Add CEntry	0.00	1500.00

Service

Change Log

Backup

BACK

1 "Channel Overview" Menu service button

2 Display of the change log table

Fig. 75 "Channel Overview" Menu, Service- Change Log

### 7.5.3 Backup

The "Backup" submenu offers you the following options:

- Backing up the settings on a USB flash drive.
- Restoring of settings on a USB flash drive.



Note

Backing up the settings is always recommended to ensure quality and so original settings can be restored in the event of an emergency.

If several identical strands are being operated then it is recommended that a change to the settings is carried out in one single channel and then transferred by USB flash drive to the other channels.

In the "Channel Overview" menu click on **Service | Backup**

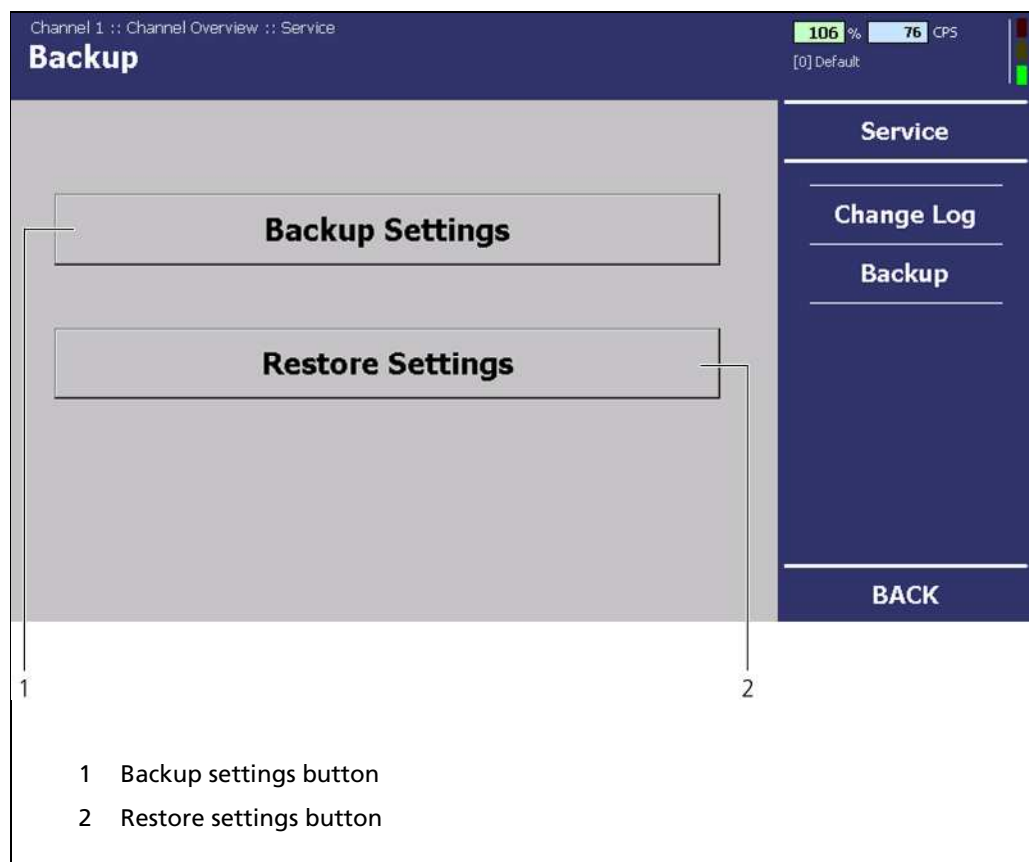


Fig. 76 "Channel Overview" Menu, Service - Backup



Note

The buttons <Backup Settings> and <Restore Settings> can only be selected if you have connected a USB-Stick to the front panel.

**Backup** (Continued)

6. Connect a USB flash drive to the USB port of the EVU front panel (Fig.1, Pos. 3).
7. Click on <Backup Settings> Fig. 76, Pos. 1).  
⇒ A confirmation message with the command to wait opens.

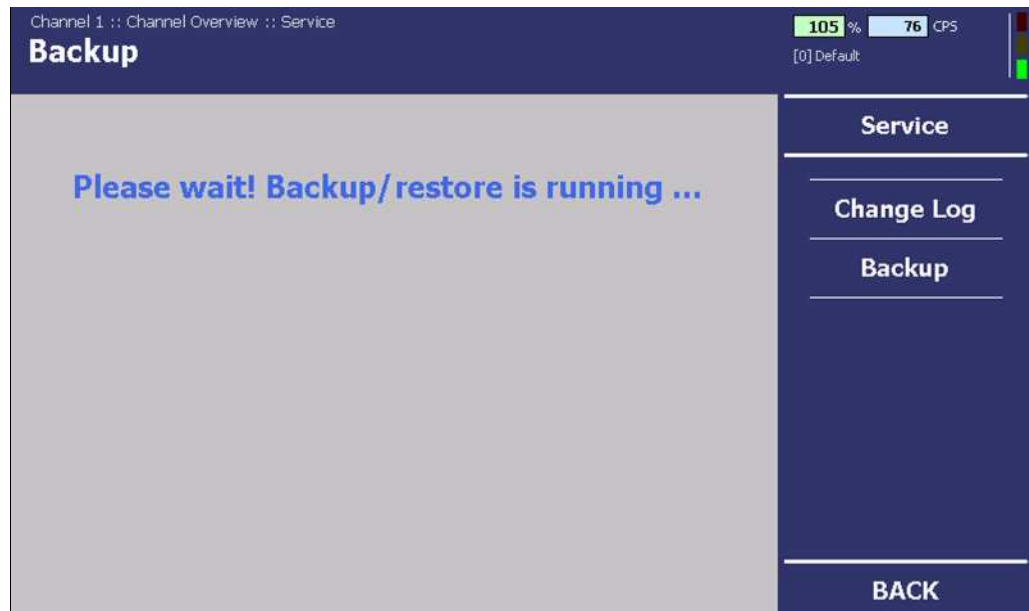


Fig. 77 "Channel Overview" Menu, Service - Backup/restore is running

⇒ A confirmation message opens after a successful backup.

8. After the backup/restore is finished, click on <OK>.



Note

All **data relevant to measurement** is backed up:  
All calibrations  
Filter constants  
Alarm Thresholds

## Restore

9. Connect a USB flash drive to the USB port of the EVU front panel (Fig.1, Pos. 3).
10. Click on <Restore Settings> (Fig. 76, Pos. 2).
  - ⇒ A window for selecting files opens.
11. Select a file and begin the restoration.
  - ⇒ A confirmation message with the command to wait opens.
  - ⇒ A confirmation message opens after a successful restoration.



Note

The files with backed-up settings have **.dds** at the end. A **.txt** file is also exported which is solely for information purposes.





# 8 Troubleshooting

## 8.1 Error Search

Problem	Cause	Measure
No signal	EVU does not work	<ul style="list-style-type: none"> <li>▶ Check power supply and fuses; is LED 1 blinking on the display?</li> </ul>
No signal	Detector does not work	<ul style="list-style-type: none"> <li>▶ Check the functioning of the detector</li> </ul>
Count rate too low	Shielding not opened or not opened correctly	<ul style="list-style-type: none"> <li>▶ Check lock and ensure it is in OPEN position</li> </ul>
	Incorrect focus of the effective radiation on the detector	<ul style="list-style-type: none"> <li>▶ Correct and optimise the alignment</li> </ul>
	Objects in the beam path	<ul style="list-style-type: none"> <li>▶ Offset irradiation level</li> </ul>
	Source at the end of its usable life span	<ul style="list-style-type: none"> <li>▶ Replace source</li> </ul>
No or incorrect fill level display	Fill level value entry incorrect	<ul style="list-style-type: none"> <li>▶ Check the calibration value and the fill level display</li> </ul>
The fill level display deviates	Defect in detector	<ul style="list-style-type: none"> <li>▶ Check detector</li> </ul>
	Incorrect calibration	<ul style="list-style-type: none"> <li>▶ Check calibration values</li> </ul>
	Count rate too low (see above)	<ul style="list-style-type: none"> <li>▶ Check source age and irradiation level, replace detector</li> </ul>
No menus are displayed which are linked to the extension module.	Extension module defect	<ul style="list-style-type: none"> <li>▶ Replace extension module</li> </ul>
	Extension module is not correctly installed	<ul style="list-style-type: none"> <li>▶ Check cable connection (flat ribbon cable) between the fieldbus module and the basic module</li> <li>▶ Check whether the extension module is pushed in properly.</li> </ul>
No data from the fieldbus module is being received in the control centre.	Fieldbus module defect	<ul style="list-style-type: none"> <li>▶ Replace fieldbus module</li> </ul>
	Fieldbus module is not correctly installed	<ul style="list-style-type: none"> <li>▶ Check cable connection (flat ribbon cable) between the extension module and the basic module</li> <li>▶ Check whether the extension module is pushed in properly.</li> </ul>
No data is being received in the control centre via Ethernet	Transfer of the measurement data deactivated	<ul style="list-style-type: none"> <li>▶ Activate the output of measurement data over the network (<b>Data Logger menu   Network</b>)</li> </ul>

## 8.2 Error Codes of the Evaluation Unit

In the following tables you can find the EVU error codes which give you exact information on how to fix them. All castXpert LB 452 errors have the prefix "M", all GAMMAcast LB67xx errors the prefix "D".

The detector error codes can be seen in the "48452BA1" manual in chapt. 7.1.

### 8.2.1 System

Code	Text	Description	Correction	Class
101	HW module corrupted	Missing circuit board or incompatible test header	<ul style="list-style-type: none"> <li>➤ Carry out software update</li> <li>➤ Contact service</li> </ul>	Error
102	Device data	Data inconsistency found	<ul style="list-style-type: none"> <li>➤ Carry out factory reset</li> </ul>	Error
103	RAM, Flash or CPU	Error in main memory Hardware error	<ul style="list-style-type: none"> <li>➤ Contact service</li> </ul>	Error
104	WD reset	The system has been reset by the watch dog (WD) Hardware error	<ul style="list-style-type: none"> <li>➤ Contact service</li> </ul>	Warning
105	WD failure	The watch dog (WD) was activated but the system was not reset Hardware error	<ul style="list-style-type: none"> <li>➤ Contact service</li> </ul>	Error
106	WD off	The debug jumper is sticking, the watchdog is disabled	<ul style="list-style-type: none"> <li>➤ Remove debug jumper</li> </ul>	Error
107	RTC date/time	Error in the actual time clock or invalid time	<ul style="list-style-type: none"> <li>➤ Check the date and time settings</li> <li>➤ Contact service</li> </ul>	Warning
108	Software exception	Software exception	<ul style="list-style-type: none"> <li>➤ Carry out software update. If the error still remains, contact the service.</li> </ul>	Error

## 8.2.2 Main board

Code	Text	Description	Correction	Class
201	Monitoring ADC	The monitoring ADC (Analogue Digital Converter) has failed Hardware error	► Contact service	Error
202	ADC Calibration	Error while calibrating the ADC	► Contact service	Error
203	24 V failure	Faulty 24 V operating voltage Hardware error	► Contact service	Error
204	3.3 V failure	Faulty 3.3 V operating voltage Hardware error.	► Contact service	Error
205	GND failure	Measured GND value too large Hardware error.	► Contact service	Error
206	Ref 2.5 V failure	Faulty 2.5 V reference voltage Hardware error	► Contact service	Error
207	Temp sensor	Temperature sensor on CPU board failed Hardware error	► Contact service	Warning
208	Temperature too high	Temperature of the system is or was too high.	► Please ensure adequate cooling of the EVU	Warning
209	Quartz synchronization	One of the oscillation quartzes does not work correctly	► Contact service if error exists consistently	Warning

## 8.2.3 Application

Code	Text	Description	Correction	Class
301	Calibration not monotonic	Calibration curve not monotonic	<ul style="list-style-type: none"> <li>➤ Check calibration table</li> </ul>	Error
302	Background too high	Background count rate larger than smallest occurring calibration point	<ul style="list-style-type: none"> <li>➤ Check calibration table</li> <li>➤ Check background count rate</li> </ul>	Error
303	Empty/Full ratio	Ratio between full and empty count rate too small	<ul style="list-style-type: none"> <li>➤ Check calibration table</li> <li>➤ Change required ratio on the plausibility page</li> <li>➤ Ensure that there are no objects or residue in the beam path</li> </ul>	Error
304	Empty adjust tolerance	Change outside of the plausibility limits during empty adjustment	<ul style="list-style-type: none"> <li>➤ Check source</li> <li>➤ Change plausibility limit</li> <li>➤ Carry out the adjustment (twice) again. The error is automatically cleared</li> </ul>	Error
305	Full adjust tolerance	Change outside of the plausibility limits during full adjustment	<ul style="list-style-type: none"> <li>➤ Check source</li> <li>➤ Change plausibility limit</li> <li>➤ Carry out the adjustment (twice) again. The error is automatically cleared</li> </ul>	Error
306	Count rate stability out of bounds	While reading in, the count rate is not constant and outside the statistical window	<ul style="list-style-type: none"> <li>➤ Ensure that no other factors influence the count rate during the read in (e.g. disruptions in the beam path)</li> <li>➤ Carry out the adjustment (twice, if needed) again. The error is automatically cleared</li> </ul>	Error
307	Decay compensation	Error during decay compensation (disabled during casting - factory settings)	<ul style="list-style-type: none"> <li>➤ Contact service</li> </ul>	Error
308	Automatic calibration	Error during automatic calibration with a calibration unit	<ul style="list-style-type: none"> <li>➤ Carry out calibration again</li> <li>➤ To ensure that the measurement is carried out without interference</li> </ul>	Error

## 8.2.4 GAMMAcast Control

Code	Text	Description	Correction	Class
501	No detector found	No compatible GAMMAcast detector found	<ul style="list-style-type: none"> <li>➤ Connect a GAMMAcast detector</li> <li>➤ Ensure the correct cabling is in place</li> <li>➤ Carry out software update</li> <li>➤ Contact service</li> </ul>	Error
502	Detector communication	Communication error GAMMAcast - Disruption on the line	<ul style="list-style-type: none"> <li>➤ Ensure the correct connection of the screen</li> <li>➤ Replace cable</li> <li>➤ Contact service</li> </ul>	Warning
503	Detector internal error	GAMMAcast or ECcast in error state (Error details and confirmation in the GAMMAcast error menu)	<ul style="list-style-type: none"> <li>➤ Operating Instructions GAMMAcast detector or ECcast system</li> </ul>	Error
504	Detector internal warning	GAMMAcast or ECcast system in warning status (Error details and confirmation in the error menu of GAMMAcast)	<ul style="list-style-type: none"> <li>➤ See operating instructions GAMMAcast detector or ECcast system</li> </ul>	Warning
505	Detector temp too high	Detector temperature is/was too high	<ul style="list-style-type: none"> <li>➤ Ensure sufficient cooling</li> </ul>	Warning
506	Detector Raw Value	Variation discovered between the pulses received by the GAMMAcast and the pulses transmitted via the communication	<ul style="list-style-type: none"> <li>➤ Check cabling</li> <li>➤ Contact service</li> </ul>	Error

## 8.2.5 Process Connection

Code	Text	Description	Correction	Class
701	Current output	Faulty current output on the basic module	<ul style="list-style-type: none"> <li>▶ Calibrate current output</li> <li>▶ Contact service</li> </ul>	Warning
702	Current output loop open	Current output on the basic module not closed	<ul style="list-style-type: none"> <li>▶ Check cabling on current output side</li> </ul>	Warning
801	Current output	Current output faulty on extension module	<ul style="list-style-type: none"> <li>▶ Calibrate current output</li> <li>▶ Contact service</li> </ul>	Warning
802	Current output loop open	Current output on the extension module not closed	<ul style="list-style-type: none"> <li>▶ Check cabling on current output side</li> </ul>	Warning
803	Temp sensor	Temperature sensor on the extension module failed Hardware error	<ul style="list-style-type: none"> <li>▶ Contact service</li> </ul>	Warning
901	Temp sensor	Temperature sensor on the fieldbus module failed Hardware error	<ul style="list-style-type: none"> <li>▶ Contact service</li> </ul>	Warning
902	Fieldbus setup	Error during the fieldbus module set-up process Hardware error	<ul style="list-style-type: none"> <li>▶ Contact service</li> </ul>	Error
903	Fieldbus Parameter	Error during parameter exchange with the fieldbus module Hardware error	<ul style="list-style-type: none"> <li>▶ Contact service</li> </ul>	Warning
904	Fieldbus module error	Internal fieldbus module error Hardware error	<ul style="list-style-type: none"> <li>▶ Contact service</li> </ul>	Error
905	Fieldbus module error	Internal serious exception in fieldbus module Hardware error	<ul style="list-style-type: none"> <li>▶ Contact service</li> </ul>	Error
906	No fieldbus	Fieldbus module has not found a master	<ul style="list-style-type: none"> <li>▶ Check connection with the fieldbus master</li> <li>▶ Ensure the correct installation of the fieldbus module</li> </ul>	Warning

# 9 Maintenance

In the maintenance chapter, the installation of modules, the replacing of fuses and the cleaning of the EVU are described.

## 9.1 Installation of Modules



Danger

### Danger to life from electric shock!

The installation may only be carried out by a qualified electrician.

Exposed live parts in the device interior.

- Never open the device before you have switched the voltage off!



Warning

### Damage to the device!

Short circuit.

- Install the modules in the correct card slots.
- Please always observe the prescribed sequence when installing modules.



Note

The EVU is delivered equipped, depending on the order. The installation of the modules is only necessary if:

- another measurement channel is to be fitted
- an existing measurement channel is to be supplemented with an extension and/or fieldbus module
- a defective module is to be replaced
- A software update is to be carried out

The following modules can be installed in the EVU:

- Basic module
- Extension module
- Fieldbus Module

## Installation of Modules (Continued)

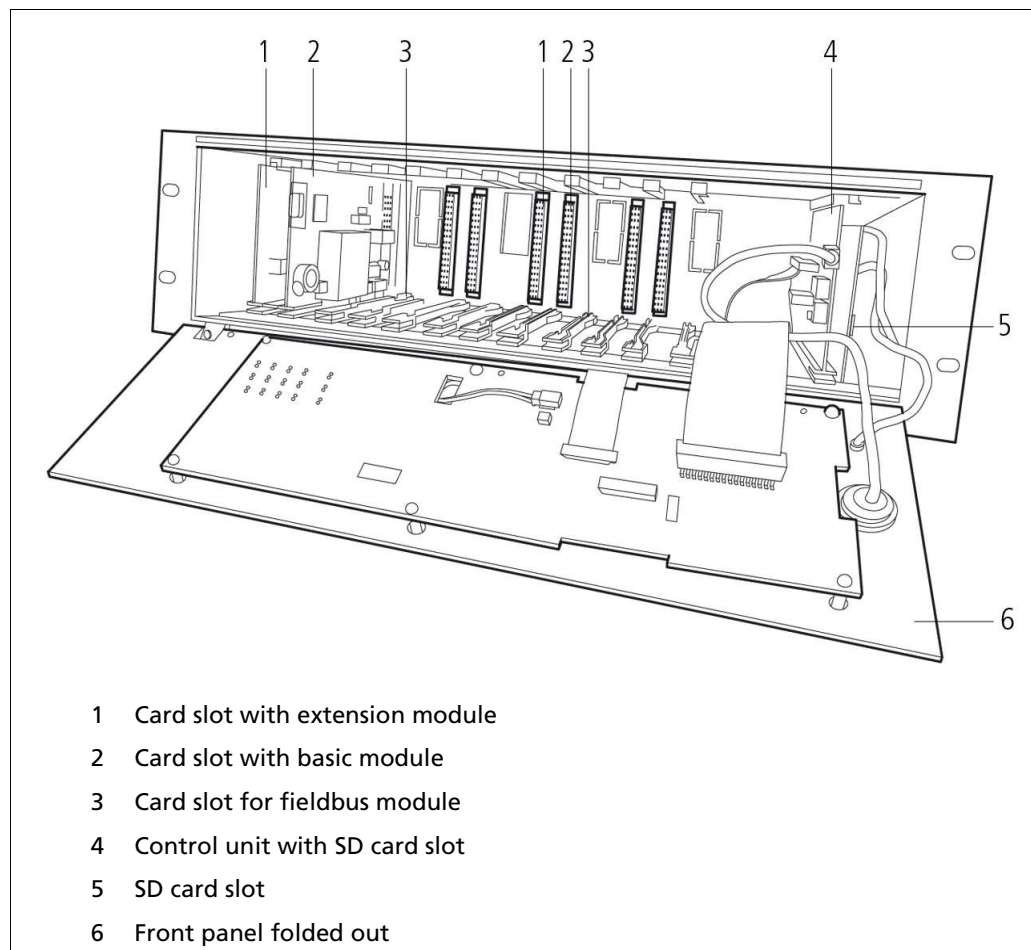


Fig. 78 Front view in the open device



## Installation of Modules (Continued)

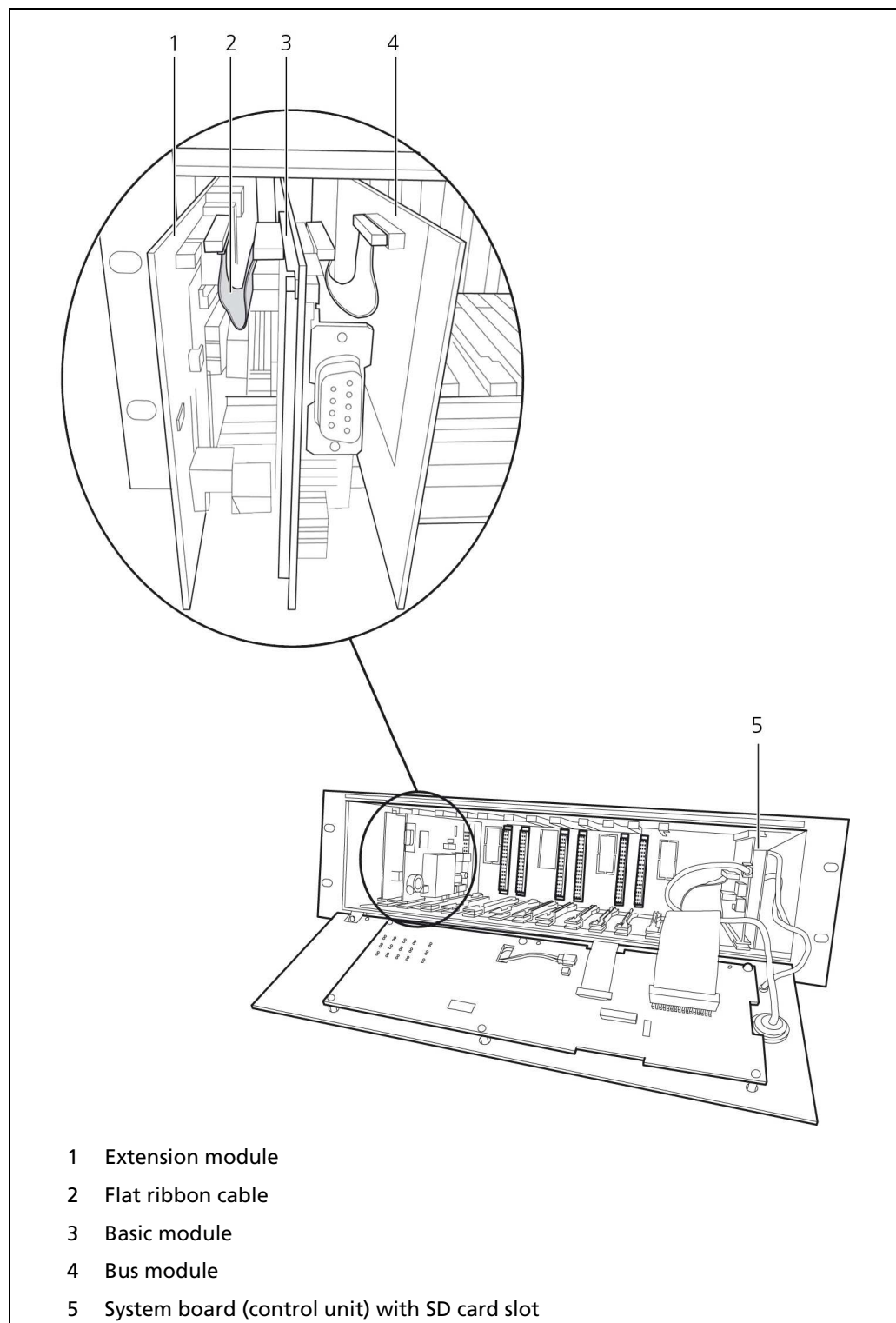


Fig. 79 Overview of the Modules

### 9.1.1 Installation of the Basic Module/Extension Module



Attention

#### Damage to the device!

Short circuit

- Install the module in the correct card slot!
- Please always observe the prescribed sequence when installing modules!



Note

If an **extension module** is to be installed, it must be connected with the basic card via the flat ribbon cable **before** the installation.



Note

The slots are labelled with an adhesive strip with the module name on.

1. Disconnect the EVU voltage.
2. Loosen the screws (Fig. 11, Pos. 2) on the front panel.
3. Fold the front panel down.
4. Connect the extension module and the basic module with a flat ribbon cable before installation (included in delivery contents) (Fig. 70, Pos. 2).
5. Push in the extension module, basic module and fieldbus module if need be again at the same time until they have clicked into place.
6. Connect all the connection cables to the rear side (Fig. 3).
7. Fold the front panel up again.
8. Tighten the screws.
9. Switch on the EVU.

## 9.1.2 Installation of the Fieldbus Module



Attention

### Damage to the device!

Short circuit

- Install the module in the correct card slot!
- Please always observe the prescribed sequence when installing modules!



Note

### Device is not recognized!

Limited range of functions

- Carry out an EVU software update before installing the fieldbus module if the control unit software version is less than version 1.0.3!

1. Disconnect the EVU voltage.
2. Loosen the screws (Fig. 11, Pos. 2).
3. Fold the front panel down.
4. Remove any already-installed modules of the relevant measurement channel before installing the fieldbus module (Fig. 86).
5. Remove the metal cover on the rear side of the housing (Fig. 80, Pos. 1). The cover is already punched out and is held at three points. Loosen the hold points with light pressure (e.g. with a screw driver).

## Fieldbus Module Installation (Continued)

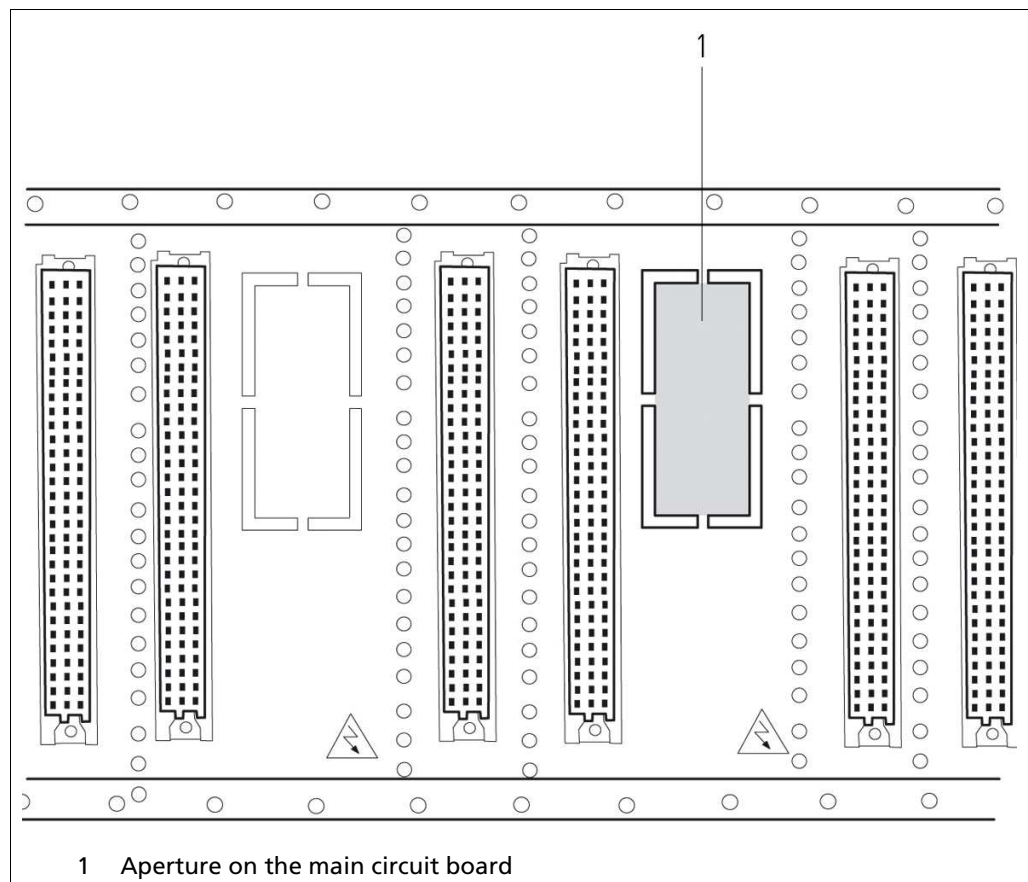


Fig. 80 EVU LB 452, main circuit board

6. Separate and remove the four hold points of the aperture on the pre-punched, green main circuit board with a wire cutter (Fig. 55, Pos. 1).
7. Connect the module with the flat ribbon cable again (included in delivery contents) (Fig. 70, Pos. 2).
8. Push in the basic module, fieldbus module and extension module if need be again **at the same time** until they have clicked into place.
9. Connect all the connection cables to the rear side (Fig. 3).
10. Fold the front panel up again.
11. Tighten the screws.
12. Switch on the EVU.
13. Install the GSD file in the control centre.

## 9.2 Replacing of Fuses



Attention

### Damage to the device! Short circuit!

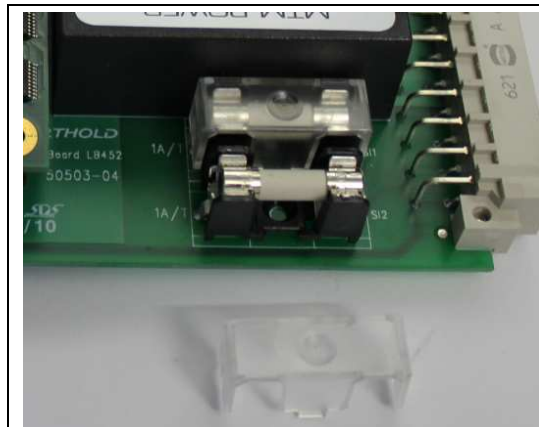
The modules can be damaged if the wrong fuses are used.

- Only use fuses which correspond to the fuses on the modules.

Two different types of fuses are used in the EVU. These fuse the individual modules and mains inlets:

	<p>The two <b>mains fuses Si1</b> and <b>Si2</b> on the basic module fuse the current input.</p> <p>If there is a defect in one of the two fuses, no signal can be transmitted over the measurement channels.</p>	
<p>Basic module</p>	<p>Basic module</p> <p>The <b>5 A fuse Si3</b> fuses the error relay.</p> <p>If there is a defect in the fuses, the error relay does not work.</p>	
	<p>Extension module</p>	<p>The two <b>5 A fuses Si3</b> and <b>Si4</b> fuse both alarm relays.</p> <p>If there is a defect in the fuses, the alarm relay does not work.</p>

## Replacing of Fuses (Continued)



System Board

The two mains fuses Si1 and Si2 on the system board fuse the power supply unit.

If there is a defect in the fuses, no power is supplied to the EVU.

### 9.2.1 Replacing of Basic Module Fuse

1. Disconnect the EVU voltage.
2. Loosen the three screws on the front panel (Fig. 11, Pos. 2).
3. Fold the front panel down.
4. Pull out the basic module and if need be the extension module and/or fieldbus module (Fig. 10, Pos. 3) carefully.
5. Remove the flat ribbon cable, if needed, (Fig. 10, Pos. 2) from the extension module and/or the fieldbus module
6. Pull carefully on the fuse (Fig. 81, Pos. 1) until the top part is fully removed.
7. Remove the plastic covering from the fuses (Fig. 81, Pos. 2).
8. Take the fuses out carefully.

## Replacing of Basic Module Fuse (Continued)

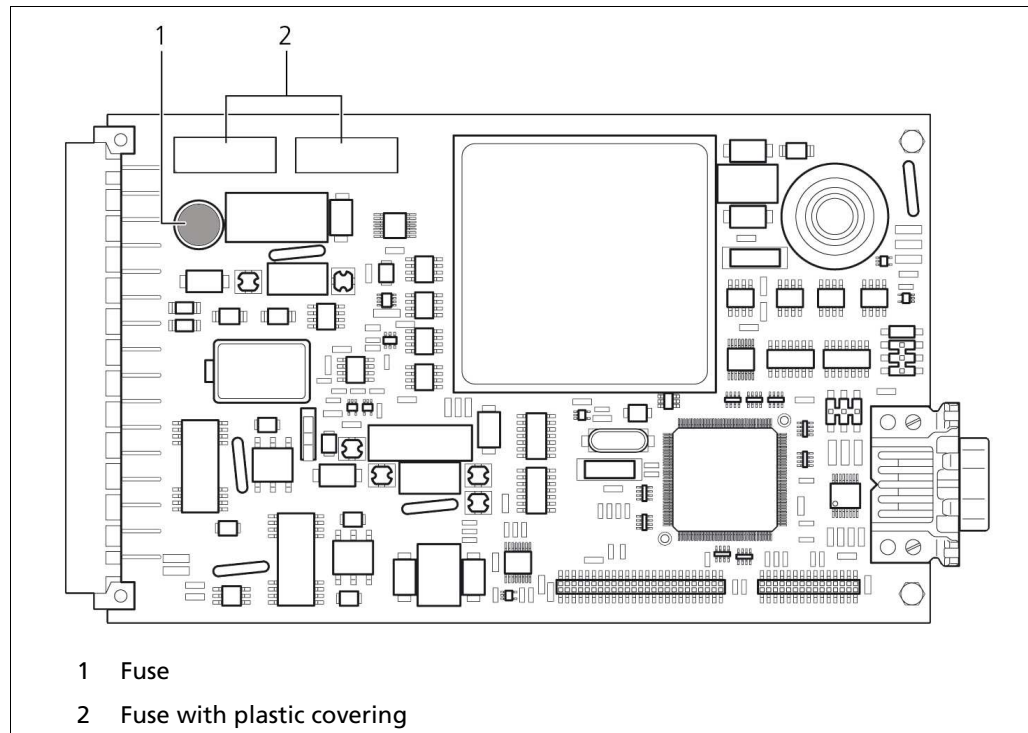


Fig. 81 Basic module fuses

9. Fit the new fuses into the basic module with the contacts and the cavities provided.
10. Connect the basic module if need be to the extension or fieldbus module with flat ribbon cables.
11. Push the module into the EVU again.
12. Fold the front panel up again.
13. Tighten the screws again.

### 9.2.2 Replacing of Extension Module Fuse

1. Disconnect the EVU voltage.
2. Loosen the three screws on the front panel (Fig. 11, Pos. 2).
3. Fold the front panel down.
4. Pull the extension module and the basic module out (Fig. 10, Pos. 3) carefully.
5. Remove the flat ribbon cable (Fig. 10, Pos. 2) from the extension module and the basic module.
6. Pull carefully on the fuses (Fig. 1, Pos. 1) until the top part is fully removed.

## Replacing of Extension Module Fuse (Continued)

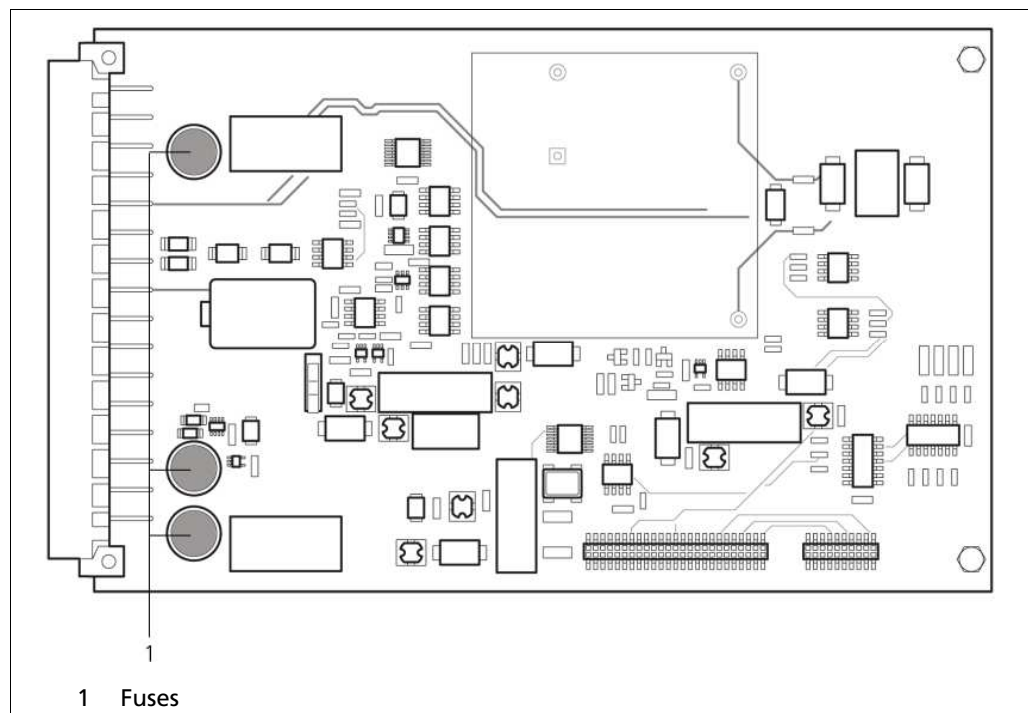


Fig. 1 Extension Module Fuses

7. Fit the new fuses into the extension module with the contacts and the cavities provided.
8. Connect the extension module to the basic module again with the flat ribbon cable.
9. Push the module into the EVU again.
10. Fold the front panel up again.
11. Tighten the screws again.



## 9.3 Cleaning



Attention

### Damage to the touch display!

Solvents and abrasive agents can damage the touch display.

➤ Only clean the touch display with a wet cloth.

---

- Only clean the EVU with a dry cloth or a dusting brush.
- Only clean the front panel and the touch display with a wet cloth.



# 10 Decommissioning



Danger

## Danger of death by electric shock

Decommissioning may only be carried out by qualified electricians..

- All relevant safety regulations have to be observed.
- Decommissioning may only be carried out if the device has been de-energised.
- Only open the device when it is de-energised.
- In case of an electric shock, carry out first measures and immediately call an emergency service..

Follow this sequence for decommissioning:

1. Remove all cables from the rear side of the housing.
2. Remove the connection cables between the EVU and the GAMMAcast detector.
3. Remove all externally connected devices (e.g. USB stick, SD card, etc.).
4. Dismount the EVU from the 19" rack.

## 10.1 Disposal of Measurement System



Caution

### Toxic!

The product contains electronic components containing toxic substances that are harmful to health.

- Disposal is to be carried out in accordance with the disposal regulations via a disposal expert.

If the device is to be decommissioned, have it disposed of according to legal regulations (e.g. RL 2002/96/EC) by a specialised waste management company.



# 11 Technical Information

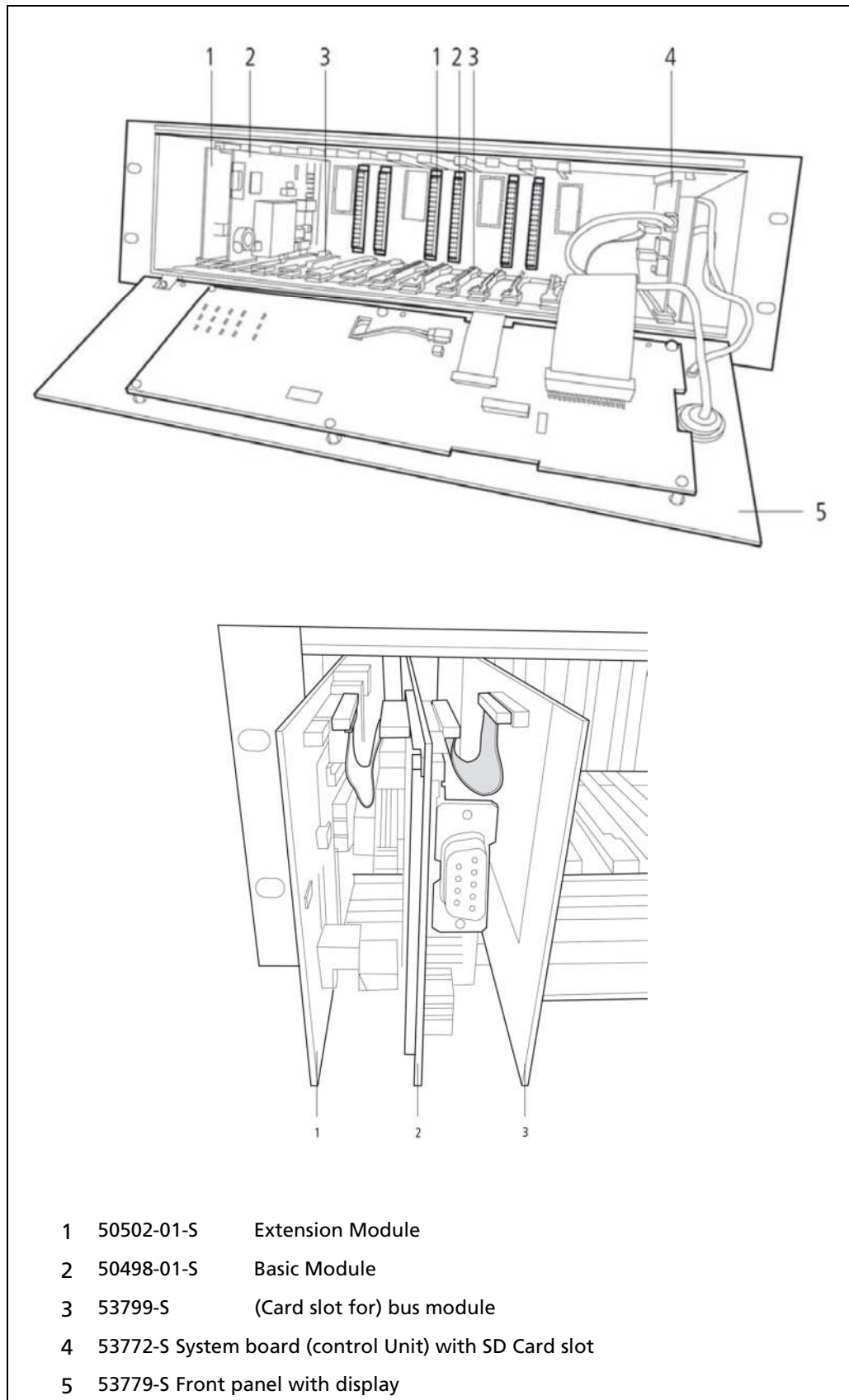
## 11.1 castxpert LB 452: Technical Data

Mechanical Design	
Frame	19" Rack, 3 HE Operating unit with 7 inch colour display and touch screen
Max. Assembly	4 measurement channels
Weight	approx. 4-6 kg depending on assembly
Degree of protection	IP 20
Connections	USB port for the connection of USB storage devices or external devices Keyboard Ethernet (RJ-45 standard socket) Control unit operating voltage output (90-264 VAC, 50/60 Hz) 4 operating voltage outputs (to provide voltage for measurement channels)
Power consumption	Control unit equipped with a measurement channel: approx. 30 W Every additional measurement channel: approx. 15 W
Operating-temperature	0 ... + 50 °C
Storage temperature	-20 ... +70 °C
Control unit	Control of the display Configuration of measurement channels Fuses: 2 x (Si1 and Si2) 1A/T/250 V according to IEC60127-2/1
Each Measurement Channel	
Basic Module (required)	CPU with separate power supply unit and connection (90-264 VAC, 50/60 Hz) Detector connection 4-20 mA current output (fill level) with option of activating current output signal monitoring (can be switched on and off): Potential-free Switchable source (max. Impedance 500 Ω) or sink (max. DC 24 V, 500 Ω; min. DC 12 V, 250 Ω) mode Adjustable fault current in the event of an error: 2 mA, 22 mA or freezing of last value 2 digital inputs: Floating, for external empty and full adjustment Relay output for error signalling: Single pole double throw (SPDT), max. AC 33 V, DC 46 V, 5 A, non-inductive Fuses: 2 x (Si1 and Si2) 1A/T/250 V according to IEC60127-2/1 1 x (Si3) 5A/T/250 V according to IEC60127-3

<p>Extension-Module (Option)</p>	<p>4-20 mA current output with option of activating current output signal monitoring:  potential-free  Switchable source (max. Impedance 500 Ω) or sink (max. DC 24 V, 500 Ω; min. DC 12 V, 250 Ω) mode  Adjustable fault current in the event of an error: 2 mA, 22 mA or freezing of last value  Can be configured for:      Fill level (additional time constant, freely adjustable)      Detector temperature      Detector count</p> <p>2 digital inputs:  potential-free, for ext. Choice of up to 4 calibration curves</p> <p>2 relay outputs for alarm signalling:  Alarm relay 1: Single pole double throw (SPDT)  Alarm relay 2: Single pole single throw, normally open (SPST NO)  Max. of 33 VAC, 46 VDC, 5 A for each, non-inductive  Can be configured for alarm signals:      Max. level      Min. level      Detector temperature      Digital input confirmation</p> <p>Pulse output:  Detector pulses looped, max. 12 V amplitude</p> <p>Fuses:  2 x (Si3 and Si4) 5A/T/250 V according to IEC60127-3  1 x (Si5) 50 mA/T/250V according to IEC60127-3</p>
<p>Bus Module (Option)</p>	<p>GSD file is provided. Transmission of the following data:  Cyclic output data: Fill level, detector value (CPS),  Detector temperature, currently selected calibration curve,  system status (RUN/ERROR/WARNING/STOP)      Cyclic input data: Error confirmation, calibration curve, full and empty adjustment</p> <p>Profibus DP:  Complete Profibus DPV1 Slave according to IEC 61158  Automatic Profibus baud rate recognition (9,600 bit/s - 12 Mbit/s)  Standardised Profibus RS-485 port  Integrated isolation with DC/DC converter and opto-coupler  Profibus connection via 9-pole D-Sub socket</p> <p>Profinet IO (planning stage):  Complete Profinet IO device implementation (Slave) with RT classification  Fast Ethernet transfer 100 MBit/s in full duplex operation  Integrated isolation  Profinet IO connection via RJ45 standard socket</p>

Entire System	
Software	<p>Data entry via touch screen</p> <p>Operating languages:            Bulgarian, Chinese (option), German, English, French, Italian, Korean (option), Portuguese, Romanian, Russian, Spanish, Czech, Hungarian</p> <p>Cycle time: 0.005 s (5 ms)</p> <p>Two time constants for filtering the raw signal:            Lower measurement range: Fast reaction            Upper measurement range: Calm signal            Change-over point freely definable</p> <p>Plausibility checks for avoiding adjustment errors            Minimum empty/full count rate ratio            Max. deviation from last adjustment</p> <p>Calibration:            Stores up to 8 different calibrations            Exact or multi-point calibration as frequency polygon (e.g. for AOS-source)            Two adjustment modes            Factoring in of the natural background radiation</p> <p>Access to detector control and service (depending on detector connected)</p> <p>Test mode:            Current outputs, digital in/outputs, calibration            Password protection against unauthorised changes to the settings</p> <p>Data log on internal storage (SD) card or via Ethernet:            Separately for each measurement channel      Smallest log interval: 0.5 s            Date/time, pulses, fill level, detector temperature, error status,            Index of the active calibration curve</p> <p>Export of data to USB storage device:            Data log, error log, change log</p> <p>Export and import of all measurement channel settings using USB storage device</p> <p>Software update (control unit, measurement channel, detector) using USB storage device</p>

## 11.2 castxpert LB 452: Inside Overview

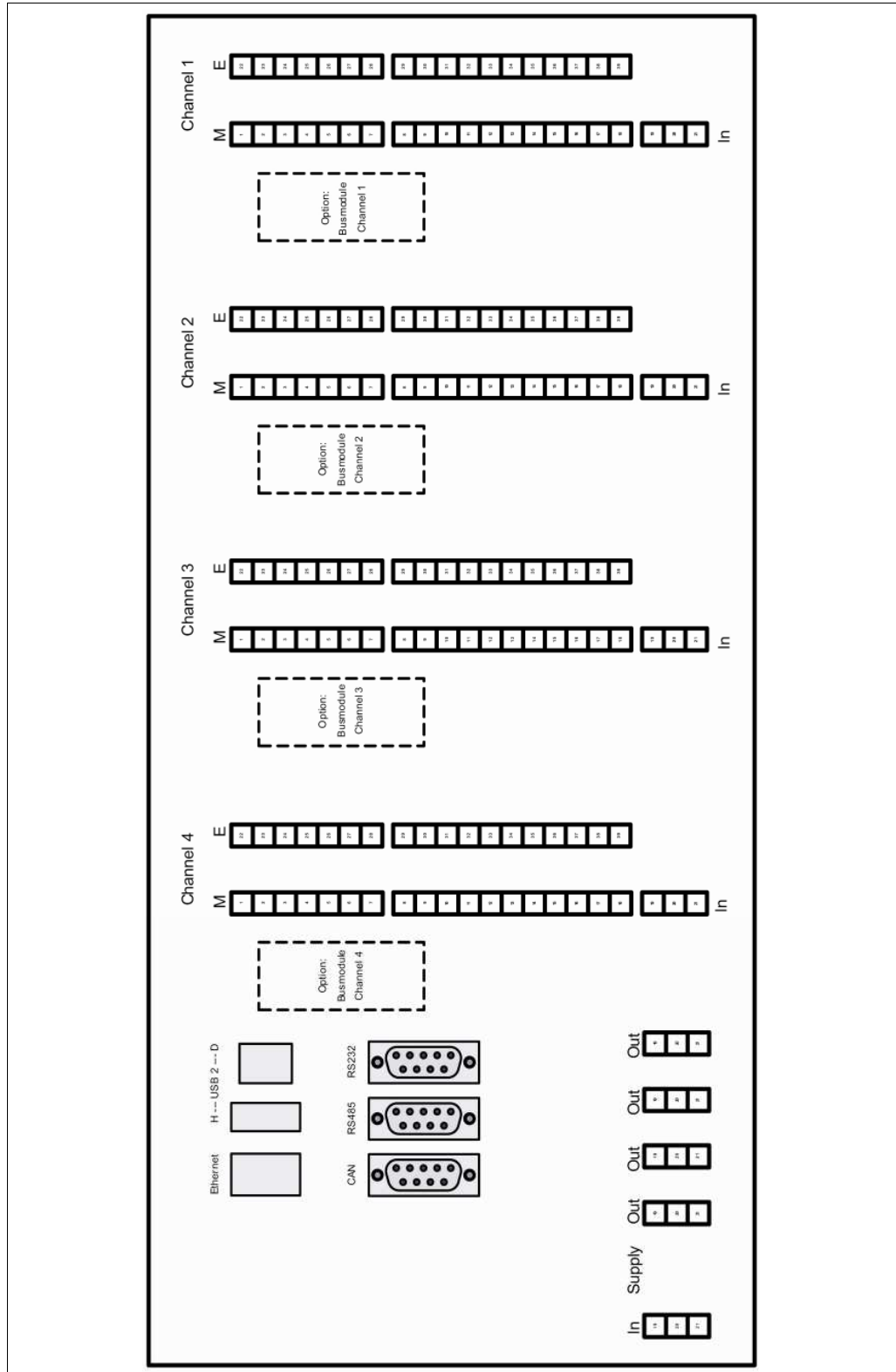




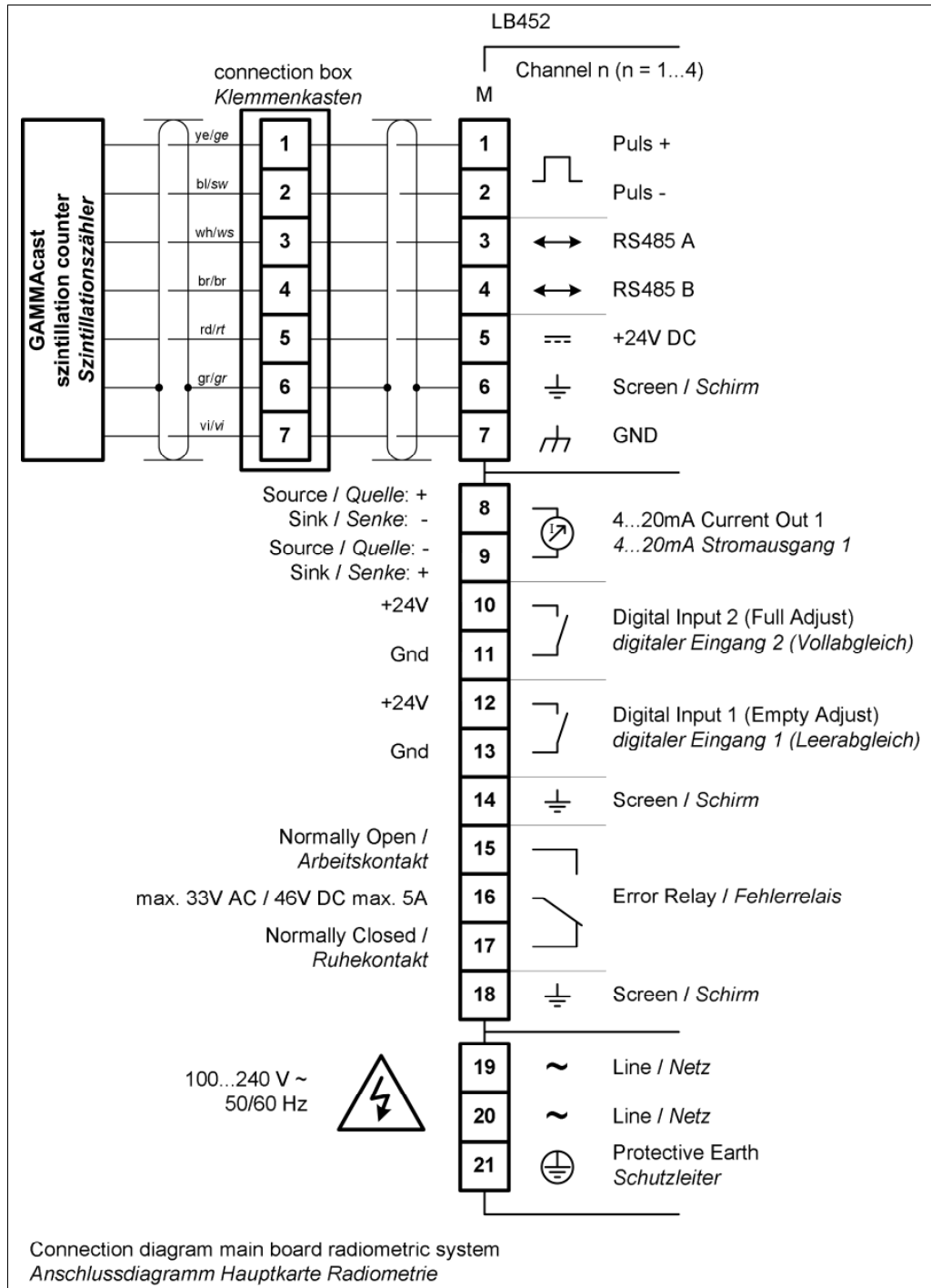
### 11.3 castxpert LB 452: Replacement Parts List

Replacement parts castXpert LB 452	
53779-S	Front panel with display for castXpert LB 452
53772-S	System-control unit for castXpert LB 452

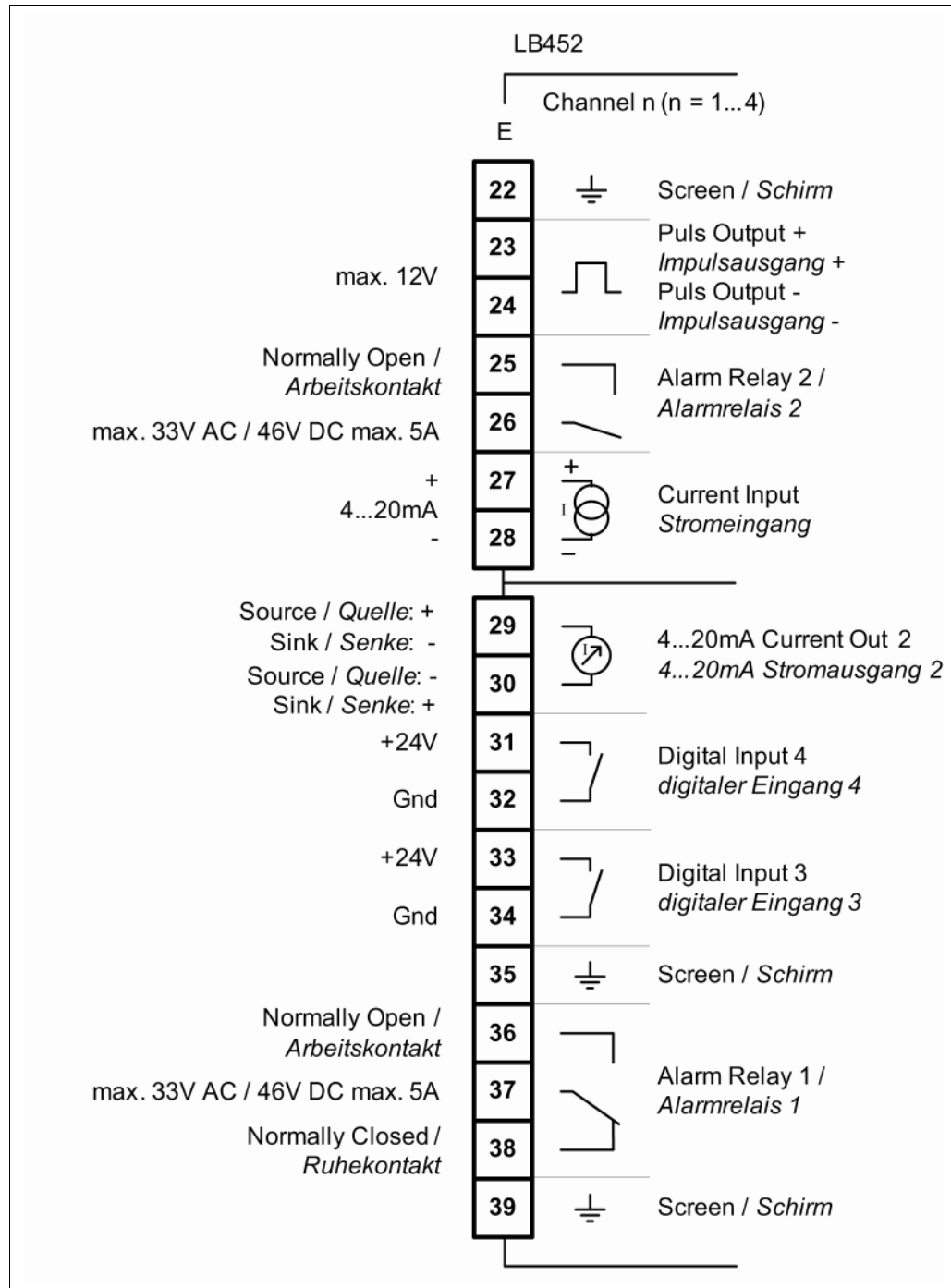
### 11.4 castxpert LB 452 Connections: Rear Overview



### 11.5 castxpert LB 452 Connections: Measuring channel base module



### 11.6 castxpert LB 452 Connections: Measurement Channel Extension Module



## 11.7 Data Definition Profibus DP

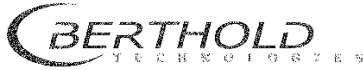
### Cyclic Output Data

Variable name	Description	Type	Size
Mould Level	Current Mould Level unit: %/mm/inch (selectable)	Float	32 Bit
Detector Raw Value	Current Detector Raw Value unit: GAMMAcast - Pulses per Second (CPS) ECcast – Millivolt (mV)	Float	32 Bit
Detector Temperature	Current Detector Temperature Unit: °C/°F (selectable)	Float	32 Bit
Calibration Index	Currently used calibration [0 ... 7] (decimal) (Calibration curve, alarm thresholds, time constant, etc.)	Byte	8 Bit
System Status	System Status. This field contains binary coded information:  <b>Bits 0-2: Main state of the system</b> Bit 0; 0x1 (1): RUN/MEASUREMENT RUNNING Bit 1; 0x2 (2): STOP Bit 2; 0x4 (4): ERROR  <b>Bit 3: Warning</b> Bit 3; 0x0 (0): NO WARNING Bit 3; 0x1 (1): WARNING  <b>Bits 4-11: Stop condition</b> Bit 4-11; 0x00 (0): Not in STOP state Bit 4; 0x01 (1): No detector found Bit 5; 0x02 (2): Detector Offline Bit 6; 0x04 (4): Test Mode Bit 7; 0x08 (8): Calibration running Bit 8; 0x10 (16): Full Adjustment running Bit 9; 0x20 (32): Empty Adjustment running  <b>Bits 12-19: Alarms</b> Bit 12-19; 0x00 (0) No alarm running Bit 12; 0x01 (1): Detector Over Temperature Bit 13; 0x02 (2): Min. Fill Level Bit 14; 0x04 (4): Max. Fill Level Bit 15; 0x08 (8): Start-up mode (time constant) Bit 16; 0x10 (16): Trim Adjust Up running [only ECcast] Bit 17; 0x20 (32): Trim Adjust Down running [only ECcast]  <b>Bits 20-31: Error number</b> A 12-bit unsigned integer number representing the number of the actual error Error# < 1000: LB 452 error Error# > 1000: Detector error	Unsigned Integer	32 Bit
			136 Bit = 17 Bytes

## Cyclical Input Data

Variable Name	Description	Type	Size
Calibration Index	Currently used calibration [0 ... 7] (decimal) (Calibration curve, alarm thresholds, time constant, etc.)	Byte	8 Bit
Function Actuation	By writing a number in this field, functions on the EVU can be actuated: 0x0 (0) Idle (do nothing) Bit 0; 0x1 (1): Empty Adjust Bit 1; 0x2 (2): Full Adjust Bit 2; 0x4 (4): Trim Adjust Up (One Step) [only ECcast] Bit 3; 0x8 (8): Trim Adjust Down (One Step) [only ECcast] Bit 4; 0x10 (16): Start Automatic Calibration [only ECcast] Bit 7; 0x80 (128): Acknowledge Actual Error	Unsigned Integer	32 Bit
			40 Bit = 5 B

# 12 Declaration of Conformity



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## EC-Declaration of Conformity

We, hereby declare under our sole responsibility that the design of the following products / systems / units brought into circulation by us comply with the relevant EC regulations.

This declaration loses its validity should modifications or unsuitable and improper use take place without our authorisation.

Description: **Continuous Casting Level Measurement System  
castXpert**

Type: **LB 452-XX**

	EC-Regulation and Reviews	Standards and Norms	
EMC	2004/108/EC	EN 61326-1	2006-05
		EN 61000-3-2	2006
		EN 61000-3-3	1995
			+A1:2001
			+A2:2005
		EN 61000-4-2	1995
			+ A1:1998
			+ A2:2001
		EN 61000-4-3	2002
		EN 61000-4-4	2004
		EN 61000-4-5	1995
			+A1:2000
		EN 61000-4-6	2003
		EN 61000-4-8	1993
			+ A1:2000
		EN 61000-4-11	2004
		Namur NE21	2004
Low Voltage Directive	2006/95/EC	EN 61010 Part 1	2002-08

This declaration is issued by the manufacturer

BERTHOLD TECHNOLOGIES GmbH & Co. KG  
Calmbacher Str. 22, D-75323 Bad Wildbad, Germany

released by

Dr. Wilfried Reuter  
Technical Director  
Bad Wildbad, 4<sup>th</sup> of May, 2010

Registergericht / Court of Registration  
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